

AN8230K

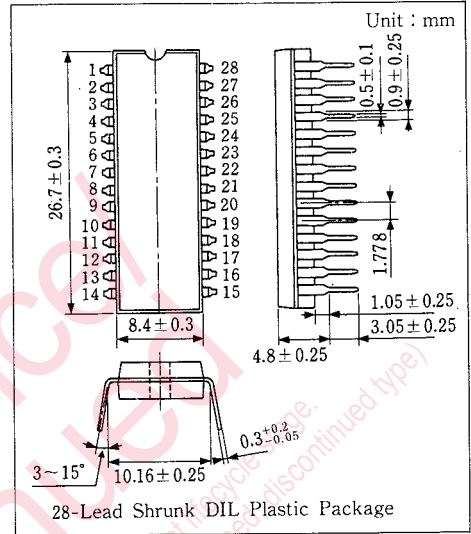
IC for FDD Motor Drive Control

Outline

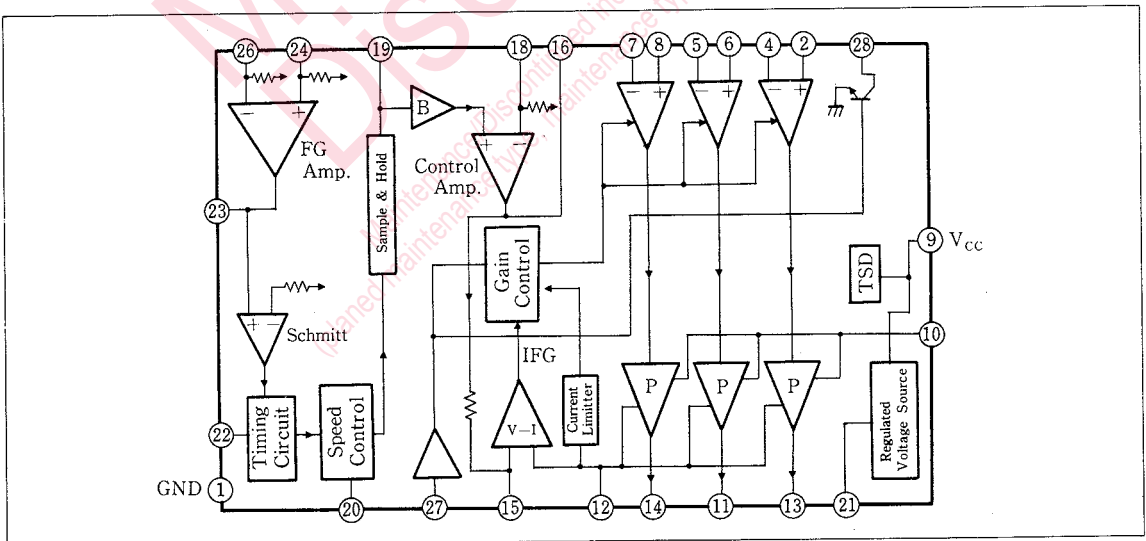
The AN8230K is an FDD motor drive control IC in which a frequency-controlled speed control circuit and a 3-phase full wave drive circuit are integrated on a single chip.

Features

- Total current in stop mode : less than 0.3mA
- Current-limit circuit
- Thermal shut-down circuit
- Maximum output current : 500mA



Block Diagram



■ Pin

Pin No.	Pin Name	Pin No.	Pin Name
1	GND	15	V _I Conv. Ripple Reduction
2	Hall Amp.Input(Ha ⁺)	16	Cont. Amp. Output
3	NC	17	NC
4	Hall Amp.Input(Ha ⁺)	18	Cont. Amp. Input
5	Hall Amp.Input(Ha ⁻)	19	Sample & Hold
6	Hall Amp.Input(Hb ⁺)	20	Speed Control
7	Hall Amp.Input(Hc ⁻)	21	V _s
8	Hall Amp.Input(Hc ⁺)	22	Ref. O _{sc} .
9	V _{cc}	23	FG Amp. Output
10	V _M	24	FG Amp. Input(+)
11	Current Output	25	NC
12	GND(Power)	26	FG Amp. Input(-)
13	Current Output	27	Start/Stop
14	Current Output	28	Hall Element Bias

■ Absolute Maximum Ratings (Ta=25°C)

Item	Symbol	Rating	Unit
Supply Voltage	V _{cc}	18	V
Power Dissipation	P _D	1780	mW
Output Current	I _o	±500	mA
Hall Input Voltage Range	V _{HB}	2.2~8.5	V
Operating Ambient Temperature	T _{opr}	-20~+70	°C
Storage Temperature	T _{stg}	-55~+150	°C

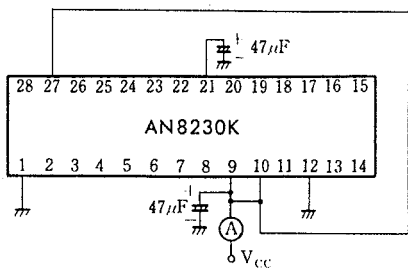
■ Electrical Characteristics (Ta=25°C)

Item	Symbol	Test Circuit	Condition	min.	typ.	max.	Unit
Standby Supply Current	I _{cs}	1	V _{STOP} =12V, V _M =12V			0.3	mA
No-load Supply Current	I _{cm}	2	V _M =12V, V _{VI} =1.7V			15	mA
Stabilized Supply Voltage	V _s	3	V _{STOP} =0.8V	4.0	4.5	5.2	V
Start/Stop Input Voltage "H"	V _{STH}	4	V _{CC} =9.6V	2			V
Start/Stop Input Voltage "L"	V _{STL}	5	V _{CC} =9.6V			0.8	V
Start/Stop Input Current "H"	I _{STH}	4	V _{STOP} =2V			100	nA
Start/Stop Input Current "L"	I _{STL}	5	V _{STOP} =0.8V	-150			μA
Hall Bias Current (for pins)	I _{HB}	6	V _{VI} =3.2V, V _{HL} =2.5V, V _{HH} =3.2V			3	μA
FG Amp. Input Bias Voltage "+"	V _{FG+}	7	V _{VI} =1.7V, V _{STOP} =0.8V	2.0	2.25	2.6	V
FG Amp. Input Bias Voltage "-"	V _{FG-}	7	V _{VI} =1.7V, V _{STOP} =0.8V	2.0	2.25	2.6	V
Schmitt Amp. Input Bias Voltage "H"	V _{SH}	8	V _{STOP} =0.8V, I _{FG+} =50μA			4	V
Schmitt Amp. Input Bias Voltage "L"	V _{SL}	8	V _{STOP} =0.8V, I _{FG+} =-50μA	1			V
Speed Control Input Bias Current	I _{SP}	9	V _{SP} =2.3V, V _{CC} =16V, V _{OSC} =0V, V _{STOP} =0.8V			100	nA
S/H Input Bias Current	I _{SHB}	10	V _{SH} =2.3V, V _{CC} =16V, V _{OSC} =0V, V _{STOP} =0.8V			100	nA
Output Voltage "L"	V _{OL}	11	I _{OL} =300mA, V _{VI} =3.2V, V _{CC} =V _M =9V			1	V
Current Limit Reference Voltage	V _{LM}	12	V _M =12V, V _{VI} =3.2V		0.5	0.55	V

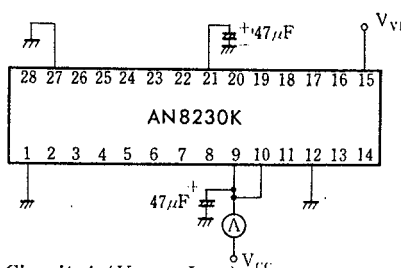
Note 1) V_{CC}=12V, V_{STOP}=0V, V_{PG}=0V in case of no specific conditions

Note 2) Supply power to V_{CC} and V_M simultaneously, or V_M first.

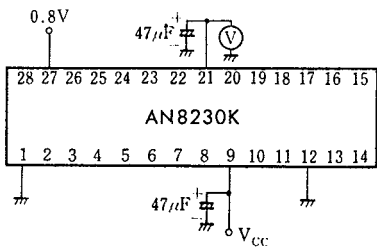
Test Circuit 1 (I_{CS})



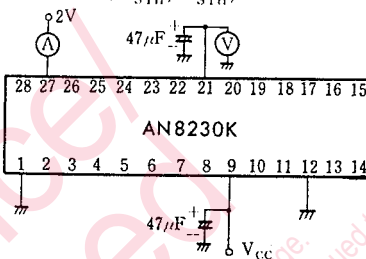
Test Circuit 2 (I_{CM})



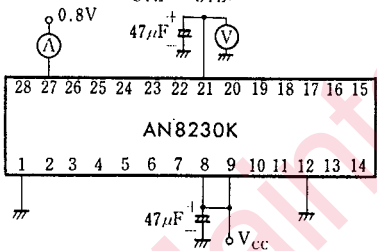
Test Circuit 3 (V_S)



Test Circuit 4 (V_{STH} , I_{STH})

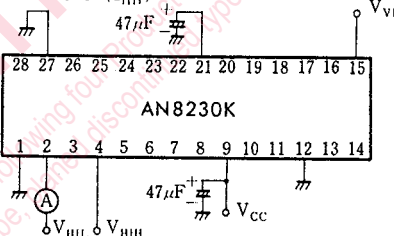


Test Circuit 5 (V_{STL} , I_{STL})



- When 2V is applied to Pin ②, measure Pin ② voltage to check that the stabilized power circuit is turned ON.
- Measure the current value when 2V is applied to Pin ②.

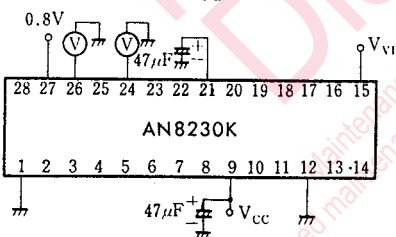
Test Circuit 6 (I_{IH})



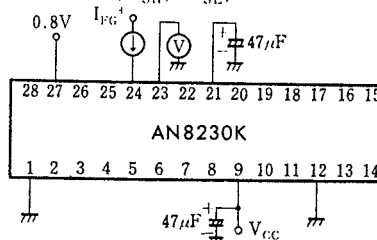
- When 0.8V is applied to Pin ②, measure Pin ② voltage to check that the stabilized power circuit is turned ON.
- Measure the current value when 0.8V is applied to Pin ②.

- Apply V_{VIH} to the measuring pin to measure I_{IH} . Similar procedure is made for Pins ④ to ⑧.

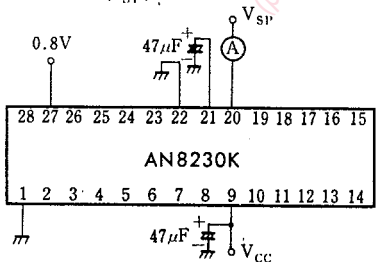
Test Circuit 7 (V_{FG}^+ , V_{FG}^-)



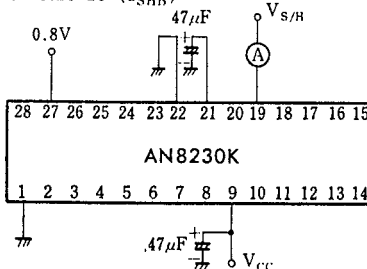
Test Circuit 8 (V_{SH} , V_{SL})



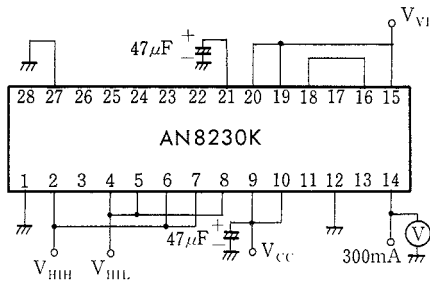
Test Circuit 9 (I_{SP})



Test Circuit 10 (I_{SHB})

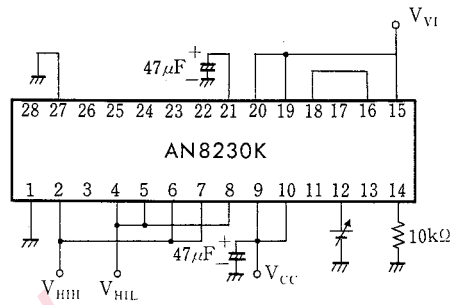


Test Circuit 11 (V_{OL})



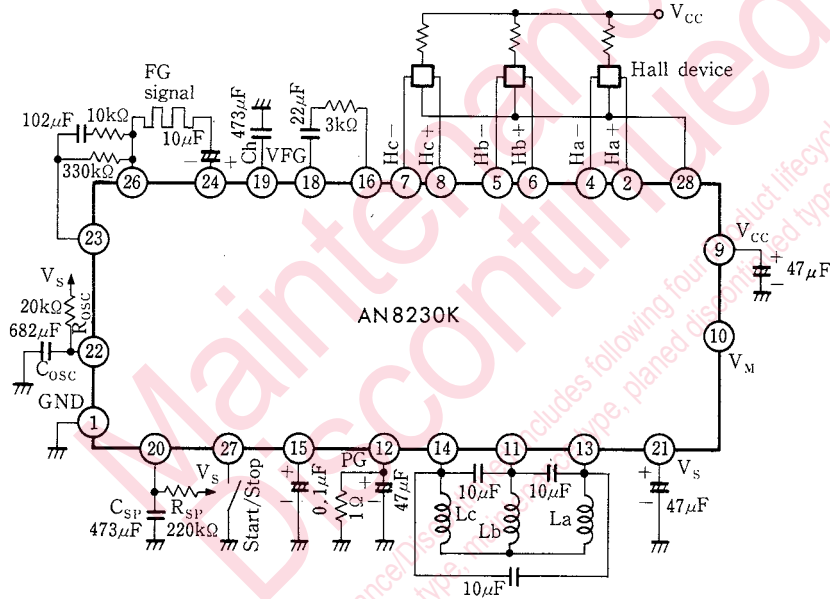
● Measure Pin ⑬ voltage when 300mA is applied to it.

Test Circuit 12 (V_{LM})



● Change the voltage to be applied to Pin ⑫ and measure the voltage when Pin ⑬ becomes from "H" to "L".

■ Application Circuit



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