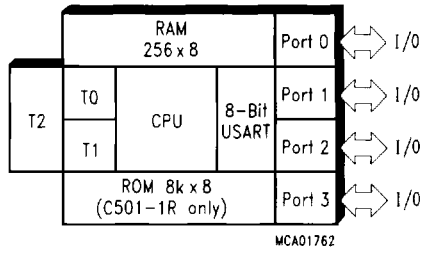
SIEMENS

8-Bit CMOS Microcontroller C501

Preliminary

- Fully compatible to standard 8051 microcontroller
- Versions for 12/24/40 MHz operating frequency
- 8 K × 8 ROM (C501-1R only)
- 256 × 8 RAM
- Four 8-bit ports
- Three 16-bit Timers / Counters (Timer 2 with Up/Down Counter feature)
- USART
- Six interrupt sources, two priority levels
- Power Saving Modes
- P-DIP-40, P-LCC-44 package, and P-MQFP-44
- Temperature ranges: SAB-C501 T_A: 0 °C to 70 °C
  SAF-C501 T_A: – 40 °C to 85 °C

C501



The C501-L/C501-1R described in this document is compatible with the SAB 80C32/C52 and can be used for all present SAB 80C52 applications.

The C501-1R contains a non-volatile 8 K × 8 read-only program memory, a volatile 256 × 8 read/write data memory, four ports, three 16-bit timers counters, a seven source, two priority level interrupt structure and a serial port. The C501-L is identical, except that it lacks the program memory on chip. Therefore, the term C501 refers to both versions within this specification unless otherwise noted. Further, the term C501 refers to all versions which are available in the different temperature ranges, marked with SAB-C501.... or SAF-C501.... .

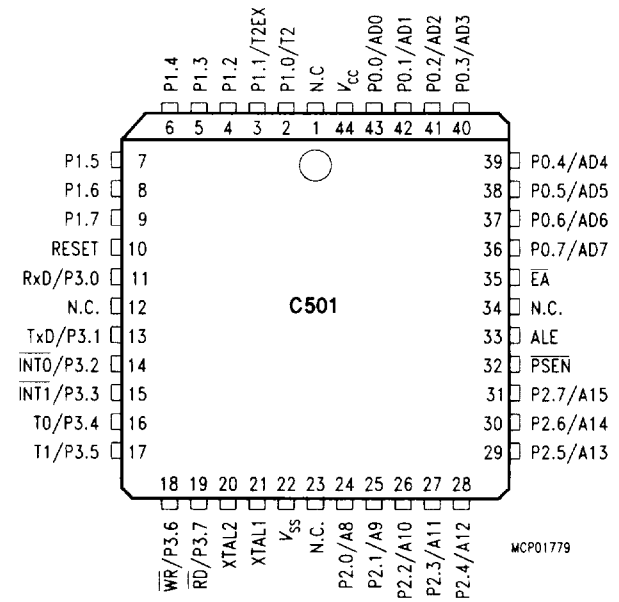
Ordering Information

Type	Ordering Code	Package	Description (8-Bit CMOS microcontroller)
SAB-C501-LN	Q67120-C844	P-LCC-44	for external memory (12 MHz)
SAB-C501-LP	Q67120-C846	P-DIP-40	
SAB-C501-LM	Q67120-C943	P-MQFP-44	
SAB-C501G-LN	Q67120-C0969	P-LCC-44	
SAB-C501G-LP	Q67120-C0968	P-DIP-40	
SAB-C501G-LM	Q67126-C0970	P-MQFP-44	
SAB-C501G-1RN	Q67120-DXXX	P-LCC-44	with mask-programmable ROM (12 MHz)
SAB-C501G-1RP	Q67120-DXXX	P-DIP-40	
SAB-C501G-1RM	Q67126-DXXX	P-MQFP-44	
SAB-C501-L24N	Q67120-C948	P-LCC-44	for external memory (24 MHz)
SAB-C501-L24P	Q67120-C979	P-DIP-40	
SAB-C501-L24M	Q67120-C972	P-MQFP-44	
SAB-C501G-L24N	Q67120-C1001	P-LCC-44	
SAB-C501G-L24P	Q67120-C0999	P-DIP-40	
SAB-C501G-L24M	Q67126-C1014	P-MQFP-44	
SAB-C501G-1R24N	Q67120-DXXX	P-LCC-44	with mask-programmable ROM (24 MHz)
SAB-C501G-1R24P	Q67120-DXXX	P-DIP-40	
SAB-C501G-1R24M	Q67126-DXXX	P-MQFP-44	
SAB-C501-L40N	Q67120-C867	P-LCC-44	for external memory (40 MHz)
SAB-C501-L40P	Q67120-C868	P-DIP-40	
SAB-C501-L40M	Q67120-C947	P-MQFP-44	
SAB-C501G-L40N	Q67120-C1002	P-LCC-44	
SAB-C501G-L40P	Q67120-C1000	P-DIP-40	
SAB-C501G-L40M	Q67126-C1009	P-MQFP-44	
SAB-C501G-1R40N	Q67120-DXXX	P-LCC-44	with mask-programmable ROM (40 MHz)
SAB-C501G-1R40P	Q67120-DXXX	P-DIP-40	
SAB-C501G-1R40M	Q67126-DXXX	P-MQFP-44	
SAF-C501-LN	Q67120-C845	P-LCC-44	for external memory (12 MHz)
SAF-C501-LP	Q67120-C847	P-DIP-40	ext. temp. – 40 °C to 85 °C
SAF-C501-L40N	Q67120-C990	P-LCC-44	for external memory (40 MHz)
SAF-C501-L40P	Q67120-C991	P-DIP-40	ext. temp. – 40 °C to 85 °C

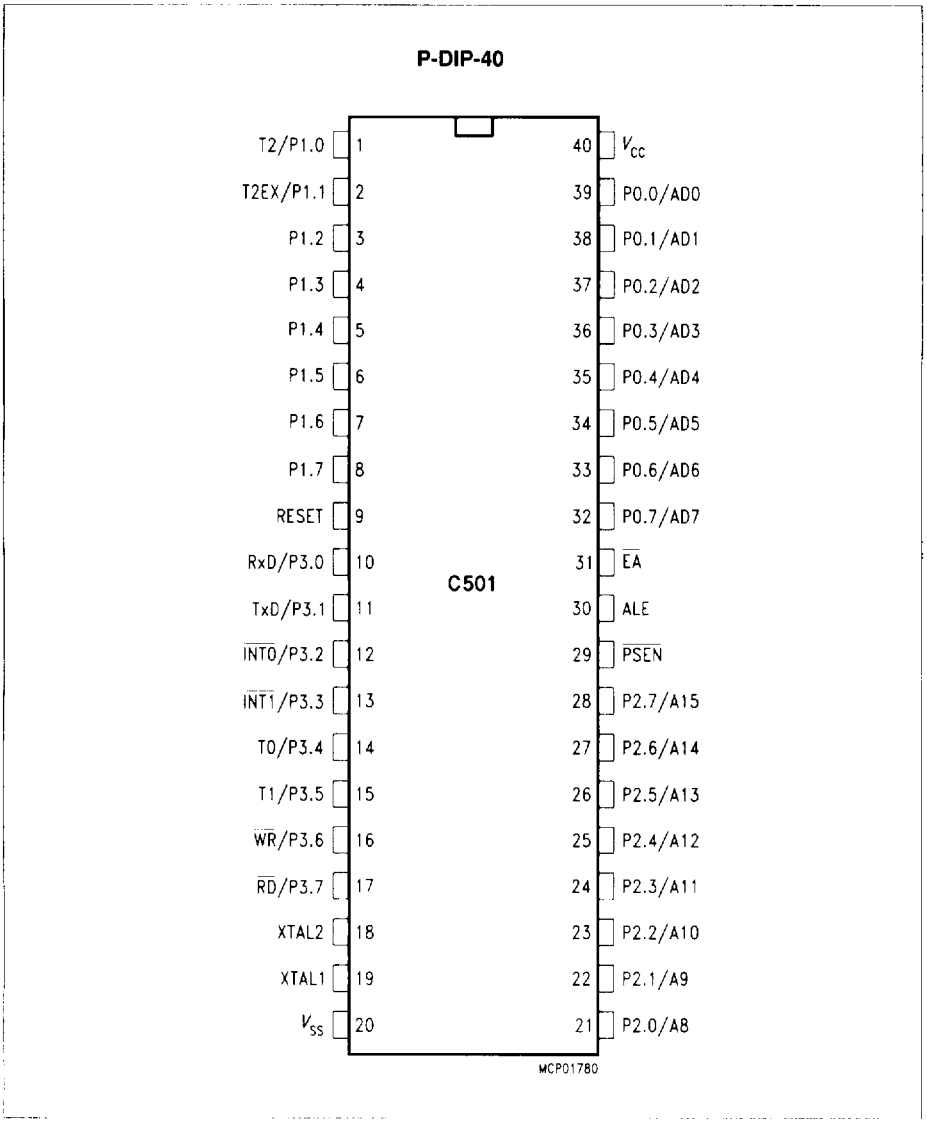
Note: Versions for extended temperature range – 40 °C to 110 °C (SAH-C501) on request.
The C501G versions are the latest steppings.
The C501 "non-G" versions are planned to be phased out.
The ordering number of ROM types (DXXXX extensions) is defined after program release (verification) of the customer.

Pin Configuration
(top view)

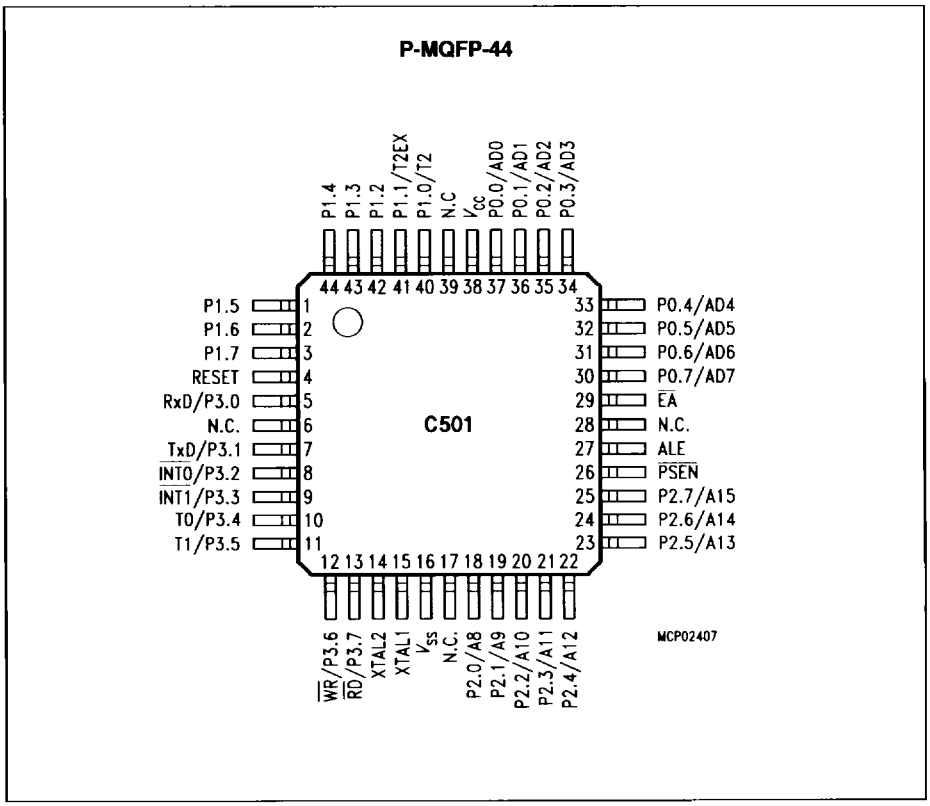
P-LCC-44

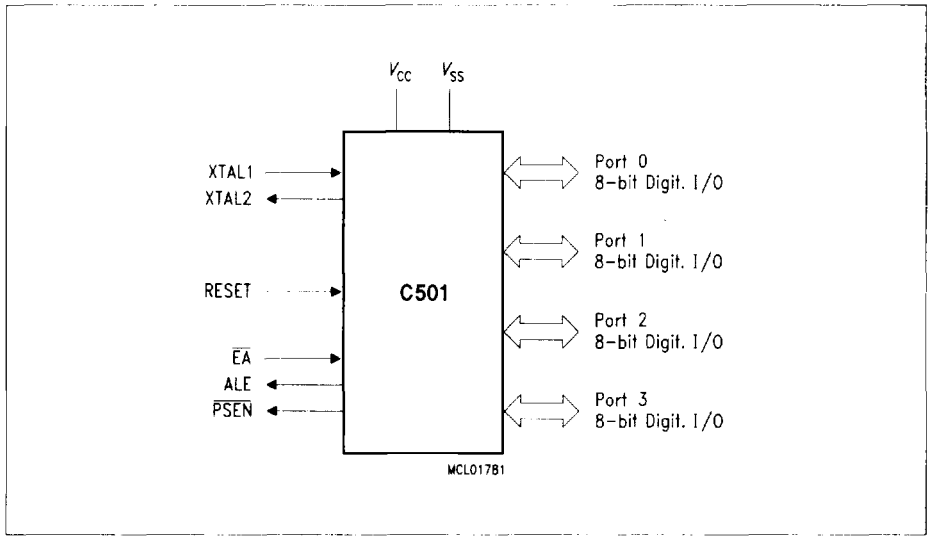


Pin Configuration
(top view)



Pin Configuration
(top view)





Logic Symbol

Pin Definitions and Functions

Symbol	Pin Number			I/O[1]	Function
	P-LCC-44	P-DIP-40	P-MQFP-44		
P1.0 – P1.7	2–9	1–8	40–44, 1–3,	I/O	**Port 1** is a bidirectional I/O port with internal pull-up resistors. Port 1 pins that have 1s written to them are pulled high by the internal pullup resistors, and in that state can be used as inputs. As inputs, port 1 pins being externally pulled low will source current (I_{IL}, in the DC characteristics) because of the internal pull-up resistors. Port 1 also contains the timer 2 pins as secondary function. The output latch corresponding to a secondary function must be pro-grammed to a one (1) for that function to operate. The secondary functions are assigned to the pins of port 1, as follows:
	2	1	40		
	3	2	41		P1.0 T2 Input to counter 2 P1.1 T2EX Capture - Reload trigger of timer 2 / Up-Down count

[1] I = Input
O = Output

Pin Definitions and Functions (cont'd)

Symbol	Pin Number			I/O*)	Function
	P-LCC-44	P-DIP-40	P-MQFP-44		
P3.0 – P3.7	11, 13–19	10–17	5, 7–13	I/O	**Port 3** is a bidirectional I/O port with internal pull-up resistors. Port 3 pins that have 1s written to them are pulled high by the internal pull-up resistors, and in that state they can be used as inputs. As inputs, port 3 pins being externally pulled low will source current (I_{IL}, in the DC characteristics) because of the internal pull-up resistors. Port 3 also contains the interrupt, timer, serial port 0 and external memory strobe pins which are used by various options. The output latch corresponding to a secondary function must be programmed to a one (1) for that function to operate.
					The secondary functions are assigned to the pins of port 3, as follows:
	11	10	5		P3.0 RxD receiver data input (asynchronous) or data input
	13	11	7		output (synchronous) of serial interface 0
					P3.1 TxD transmitter data output (asynchronous) or clock
	14	12	8		output (synchronous) of the serial interface 0
	15	13	9		P3.2 $\overline{INT0}$ interrupt 0 input/timer 0 gate control
	16	14	10		P3.3 $\overline{INT1}$ interrupt 1 input/timer 1
	17	15	11		gate control
	18	16	12		P3.4 T0 counter 0 input
					P3.5 T1 counter 1 input
					P3.6 $\overline{WR}$ the write control signal
	19	17	13		latches the data byte from port 0 into the external data memory
					P3.7 $\overline{RD}$ the read control signal enables the external data memory to port 0

*) I = Input
O = Output

Pin Definitions and Functions (cont'd)

Symbol	Pin Number			I/O[1]	Function
	P-LCC-44	P-DIP-40	P-MQFP-44		
XTAL2	20	18	14	–	**XTAL2** Output of the inverting oscillator amplifier.
XTAL1	21	19	15	–	**XTAL1** Input to the inverting oscillator amplifier and input to the internal clock generator circuits. To drive the device from an external clock source, XTAL1 should be driven, while XTAL2 is left unconnected. There are no requirements on the duty cycle of the external clock signal, since the input to the internal clocking circuitry is divided down by a divide-by-two flip-flop. Minimum and maximum high and low times as well as rise fall times specified in the AC characteristics must be observed.
P2.0 – P2.7	24–31	21–28	18–25	I/O	**Port 2** is a bidirectional I/O port with internal pull-up resistors. Port 2 pins that have 1s written to them are pulled high by the internal pull-up resistors, and in that state they can be used as inputs. As inputs, port 2 pins being externally pulled low will source current (I_{IL}, in the DC characteristics) because of the internal pull-up resistors. Port 2 emits the high-order address byte during fetches from external program memory and during accesses to external data memory that use 16-bit addresses (MOVX @DPTR). In this application it uses strong internal pull-up resistors when issuing 1s. During accesses to external data memory that use 8-bit addresses (MOVX @Ri), port 2 issues the contents of the P2 special function register.

*) I = Input
O = Output

Pin Definitions and Functions (cont'd)

Symbol	Pin Number			I/O[1]	Function
	P-LCC-44	P-DIP-40	P-MQFP-44		
$\overline{PSEN}$	32	29	26	O	**The $\overline{Program\ Store\ Enable}$** output is a control signal that enables the external program memory to the bus during external fetch operations. It is activated every six oscillator periods except during external data memory accesses. Remains high during internal program execution.
RESET	10	9	4	I	**RESET** A high level on this pin for two machine cycles while the oscillator is running resets the device. An internal diffused resistor to V_{SS} permits power-on reset using only an external capacitor to V_{CC}.
ALE	33	30	27	O	The **Address Latch Enable** output is used for latching the low-byte of the address into external memory during normal operation. It is activated every six oscillator periods except during an external data memory access.
$\overline{EA}$	35	31	29	I	**$\overline{External\ Access\ Enable}$** When held at high level, instructions are fetched from the internal ROM (C501-1R only) when the PC is less than 2000_H. When held at low level, the C501 fetches all instructions from external program memory. For the C501-L this pin must be tied low.

*) I = Input
O = Output

Pin Definitions and Functions (cont'd)

Symbol	Pin Number			I/O[1]	Function
	P-LCC-44	P-DIP-40	P-MQFP-44		
P0.0 – P0.7	43–36	39–32	37–30	I/O	**Port 0** is an 8-bit open-drain bidirectional I/O port. Port 0 pins that have 1s written to them float, and in that state can be used as high-impedance inputs. Port 0 is also the multiplexed low-order address and data bus during accesses to external program or data memory. In this application it uses strong internal pull-up resistors when issuing 1s. Port 0 also outputs the code bytes during program verification in the C501-1R. External pull-up resistors are required during program verification.
V_{SS}	22	20	16	–	**Circuit ground potential**
V_{CC}	44	40	38	–	**Supply terminal** for all operating modes
N.C.	1, 12, 23, 34	–	6, 17, 28, 39	–	**No connection**

Functional Description

The C501 is fully compatible to the standard 8051 microcontroller family.

It is compatible with the SAB 80C52. While maintaining all architectural and operational characteristics of the SAB 80C52, the C501 incorporates some enhancements in the Timer2 Unit.

Figure 1 shows a block diagram of the C501.

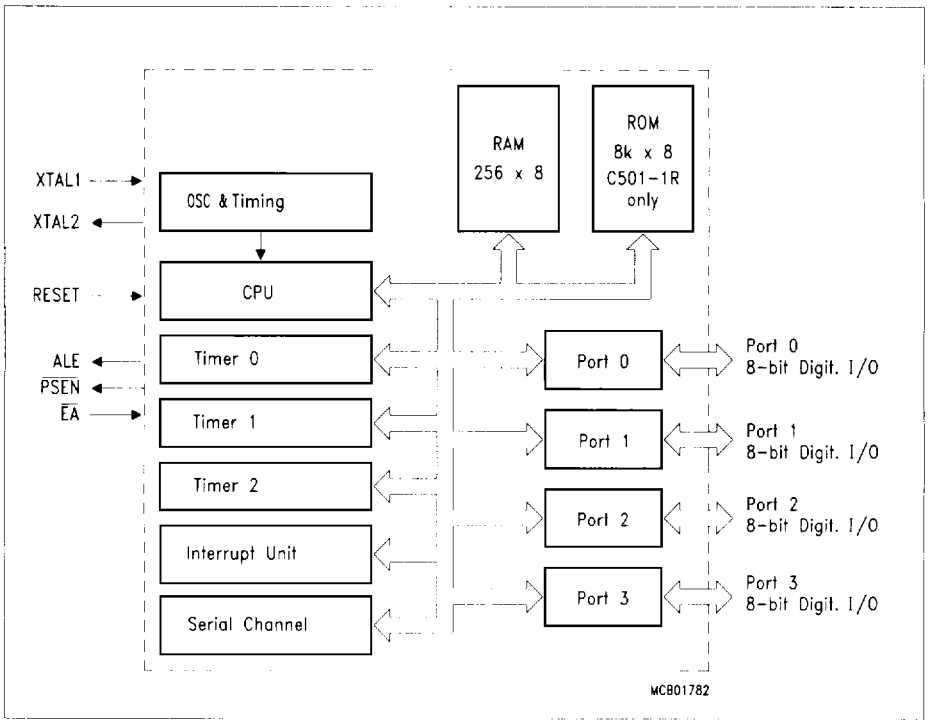


Figure 1
Block Diagram of the C501

CPU

The C501 is efficient both as a controller and as an arithmetic processor. It has extensive facilities for binary and BCD arithmetic and excels in its bit-handling capabilities. Efficient use of program memory results from an instruction set consisting of 44 % one-byte, 4 % two-byte, and 15 % three-byte instructions. With a 12 MHz crystal, 58 % of the instructions are executed in 1.0 µs 24 MHz: 500 ns, 40 MHz: 300 ns).

Special Function Register PSW

	MSB							LSB	
Bit No.	7	6	5	4	3	2	1	0	
Addr. $D0_H$	CY	AC	F0	RS1	RS0	OV	F1	P	PSW

Bit		Function
CY		**Carry Flag**
AC		**Auxiliary Carry Flag** (for BCD operations)
F0		**General Purpose Flag**
RS1	**RS0**	**Register Bank select control bits**
0	0	Bank 0 selected, data address $00_H - 07_H$
0	1	Bank 1 selected, data address $08_H - 0F_H$
1	0	Bank 2 selected, data address $10_H - 17_H$
1	1	Bank 3 selected, data address $18_H - 1F_H$
OV		**Overflow Flag**
F1		**General Purpose Flag**
P		**Parity Flag** Set/cleared by hardware each instruction cycle to indicate an odd/ even number of "one" bits in the accumulator, i.e. even parity.

Reset value of PSW is 00_H.

Special Function Registers

All registers, except the program counter and the four general purpose register banks, reside in the special function register area.

The 27 special function registers (SFR) include pointers and registers that provide an interface between the CPU and the other on-chip peripherals. There are also 128 directly addressable bits within the SFR area.

All SFRs are listed in **table 1**, **table 2**, and **table 3**.

In **table 1** they are organized in numeric order of their addresses. In **table 2** they are organized in groups which refer to the functional blocks of the C501. **Table 3** illustrates the contents of the SFRs.

Table 1
Special Function Registers in Numeric Order of their Addresses

Address	Register	Contents after Reset	Address	Register	Contents after Reset
80_H	**P0** [1]	**FF_H**	**98_H**	**SCON** [1]	**00_H**
81_H	SP	07_H	99_H	SBUF	XX_H [2]
82_H	DPL	00_H	$9A_H$	reserved	XX_H [2]
83_H	DPH	00_H	$9B_H$	reserved	XX_H [2]
84_H	reserved	XX_H [2]	$9C_H$	reserved	XX_H [2]
85_H	reserved	XX_H [2]	$9D_H$	reserved	XX_H [2]
86_H	reserved	XX_H [2]	$9E_H$	reserved	XX_H [2]
87_H	PCON	$0XXX0000_B$ [2]	$9F_H$	reserved	XX_H [2]
88_H	**TCON** [1]	**00_H**	**$A0_H$**	**P2** [1]	**FF_H**
89_H	TMOD	00_H	$A1_H$	reserved	XX_H [2]
$8A_H$	TL0	00_H	$A2_H$	reserved	XX_H [2]
$8B_H$	TL1	00_H	$A3_H$	reserved	XX_H [2]
$8C_H$	TH0	00_H	$A4_H$	reserved	XX_H [2]
$8D_H$	TH1	00_H	$A5_H$	reserved	XX_H [2]
$8E_H$	reserved	XX_H [2]	$A6_H$	reserved	XX_H [2]
$8F_H$	reserved	XX_H [2]	$A7_H$	reserved	XX_H [2]
90_H	**P1** [1]	**FF_H**	**$A8_H$**	**IE** [1]	**$0X000000_B$** [2]
91_H	reserved	00_H	$A9_H$	reserved	XX_H [2]
92_H	reserved	XX_H [2]	AA_H	reserved	XX_H [2]
93_H	reserved	XX_H [2]	AB_H	reserved	XX_H [2]
94_H	reserved	XX_H [2]	AC_H	reserved	XX_H [2]
95_H	reserved	XX_H [2]	AD_H	reserved	XX_H [2]
96_H	reserved	XX_H [2]	AE_H	reserved	XX_H [2]
97_H	reserved	XX_H [2]	AF_H	reserved	XX_H [2]

[1] Bit-addressable Special Function Register
[2] X means that the value is indeterminate and the location is reserved

Table 1
Special Function Registers in Numeric Order of their Addresses (cont'd)

Address	Register	Contents after Reset	Address	Register	Contents after Reset
$B0_H$	**P3**[1]	**FF_H**	**$D8_H$**	reserved	XX_H[2]
$B1_H$	reserved	XX_H[2]	$D9_H$	reserved	XX_H[2]
$B2_H$	reserved	XX_H[2]	DA_H	reserved	XX_H[2]
$B3_H$	reserved	XX_H[2]	DB_H	reserved	XX_H[2]
$B4_H$	reserved	XX_H[2]	DC_H	reserved	XX_H[2]
$B5_H$	reserved	XX_H[2]	DD_H	reserved	XX_H[2]
$N6_H$	reserved	XX_H[2]	DE_H	reserved	XX_H[2]
$B7_H$	reserved	XX_H[2]	DF_H	reserved	XX_H[2]
$B8_H$	**IP**[1]	**$XX000000_B$**[2]	**$E0_H$**	**ACC**[1]	**00_H**
$B9_H$	reserved	XX_H[2]	$E1_H$	reserved	XX_H[2]
BA_H	reserved	XX_H[2]	$E2_H$	reserved	XX_H[2]
BB_H	reserved	XX_H[2]	$E3_H$	reserved	XX_H[2]
BC_H	reserved	XX_H[2]	$E4_H$	reserved	XX_H[2]
BD_H	reserved	XX_H[2]	$E5_H$	reserved	XX_H[2]
BE_H	reserved	XX_H[2]	$E6_H$	reserved	XX_H[2]
BF_H	reserved	XX_H[2]	$E7_H$	reserved	XX_H[2]
$C0_H$	reserved	XX_H[2]	**$E8_H$**	reserved	XX_H[2]
$C1_H$	reserved	XX_H[2]	$E9_H$	reserved	XX_H[2]
$C2_H$	reserved	XX_H[2]	EA_H	reserved	XX_H[2]
$C3_H$	reserved	XX_H[2]	EB_H	reserved	XX_H[2]
$C4_H$	reserved	XX_H[2]	EC_H	reserved	XX_H[2]
$C5_H$	reserved	XX_H[2]	ED_H	reserved	XX_H[2]
$C6_H$	reserved	XX_H[2]	EE_H	reserved	XX_H[2]
$C7_H$	reserved	XX_H[2]	EF_H	reserved	XX_H[2]
$C8_H$	**T2CON**	**00_H**	**$F0_H$**	**B**[1]	**00_H**
$C9_H$	T2MOD	$XXXXXXX0_B$[2]	$F1_H$	reserved	XX_H[2]
CA_H	RC2L	00_H	$F2_H$	reserved	XX_H[2]
CB_H	RC2H	00_H	$F3_H$	reserved	XX_H[2]
CC_H	TL2	00_H	$F4_H$	reserved	XX_H[2]
CD_H	TH2	00_H	$F5_H$	reserved	XX_H[2]
CE_H	reserved	XX_H[2]	$F6_H$	reserved	XX_H[2]
CF_H	reserved	XX_H[2]	$F7_H$	reserved	XX_H[2]
$D0_H$	**PSW**[1]	**00_H**	**$F8_H$**	reserved	XX_H[2]
$D1_H$	reserved	XX_H[2]	$F9_H$	reserved	XX_H[2]
$D2_H$	reserved	XX_H[2]	FA_H	reserved	XX_H[2]
$D3_H$	reserved	XX_H[2]	FB_H	reserved	XX_H[2]
$D4_H$	reserved	XX_H[2]	FC_H	reserved	XX_H[2]
$D5_H$	reserved	XX_H[2]	FD_H	reserved	XX_H[2]
$D6_H$	reserved	XX_H[2]	FE_H	reserved	XX_H[2]
$D7_H$	reserved	XX_H[2]	FF_H	reserved	XX_H[2]

[1] Bit-addressable Special Function Register
[2] X means that the value is indeterminate and the location is reserved

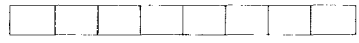
Table 2
Special Function Registers - Functional Blocks

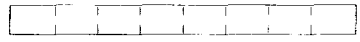
Block	Symbol	Name	Address	Contents after Reset
CPU	ACC	Accumulator	**$E0_H$** [1]	00_H
	B	B-Register	**$F0_H$** [1]	00_H
	DPH	Data Pointer, High Byte	83_H	00_H
	DPL	Data Pointer, Low Byte	82_H	00_H
	PSW	Program Status Word Register	**$D0_H$** [1]	00_H
	SP	Stack Pointer	81_H	07H
Interrupt System	IE	Interrupt Enable Register	**$A8_H$** [1]	$0X000000_B$ [2]
	IP	Interrupt Priority Register	**$B8_H$** [1]	$XX000000_B$ [2]
Ports	P0	Port 0	**80_H** [1]	FF_H
	P1	Port 1	**90_H** [1]	XX_H [3]
	P2	Port 2	**$A0_H$** [1]	FF_H
	P3	Port 3	**$B0_H$** [1]	FF_H
Serial Channels	PCON [2]	Power Control Register	87_H	$0XXX0000_B$ [2]
	SBUF	Serial Channel Buffer Reg.	99_H	XX_H [3]
	SCON	Serial Channel 0 Control Reg.	**98H** [1]	00_H
Timer 0 / Timer 1	TCON	Timer 0/1 Control Register	**88_H** [1]	00_H
	TH0	Timer 0, High Byte	$8C_H$	00_H
	TH1	Timer 1, High Byte	$8DH_H$	00_H
	TL0	Timer 0, Low Byte	$8A_H$	00_H
	TL1	Timer 1, Low Byte	$8B_H$	00_H
	TMOD	Timer Mode Register	89_H	00_H
Timer 2	T2CON	Timer 2 Control Register	**$C8_H$** [1]	00_H
	T2MOD	Timer 2 Mode Register	$C9_H$	00_H
	RC2H	Timer 2 Reload Capture Reg., High Byte	CB_H	00_H
	RC2L	Timer 2 Reload Capture Reg., Low Byte	CA_H	00_H
	TH2	Timer 2, High Byte	CD_H	00_H
	TL2	Timer 2, Low Byte	CC_H	00_H
Pow. Sav. Modes	PCON	Power Control Register	87_H	$0XXX0000_B$ [2]

[1] Bit-addressable special function registers
[2] This special function register is listed repeatedly since some bits of it also belong to other functional blocks
[3] X means that the value is indeterminate and the location is reserved

Table 3
Contents of SFRs, SFRs in Numeric Order

Address	Register	Bit 7	6	5	4	3	2	1	0
80_H	P0								
81_H	SP								
82_H	DPL								
83_H	DPH								
87_H	PCON	SMOD	–	–	–	GF1	GF0	PDE	IDLE
88_H	TCON	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0
89_H	TMOD	GATE	C/$\overline{T}$	M1	M0	GATE	C/$\overline{T}$	M1	M0
$8A_H$	TL0								
$8B_H$	TL1								
$8C_H$	TH0								
$8D_H$	TH1								
90_H	P1								
98_H	SCON	SM0	SM1	SM2	REN	TB8	RB8	TI	RI
99_H	SBUF								
$A0_H$	P2								
$A8_H$	IE	EA	–	ET2	ES	ET1	EX1	ET0	EX0
$B0_H$	P3								
$B8_H$	IP	–	–	PT2	PS	PT1	PX1	PT0	PX0
$C8_H$	T2CON	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	C/$\overline{T2}$	CP/$\overline{RL2}$
$C9_H$	T2MOD	–	–	–	–	–	–	–	DCEN


SFR bit and byte addressable


SFR not bit addressable

– : = this bit location is reserved

Table 3
Contents of SFRs, SFRs in Numeric Order (cont'd)

Address	Register	Bit 7	6	5	4	3	2	1	0
CA_H	RC2L								
CB_H	RC2H								
CC_H	TL2								
CD_H	TH2								
$D0_H$	PSW	CY	AC	F0	RS1	RS0	OV	F1	P
$E0_H$	ACC								
$F0_H$	B								

SFR bit and byte addressable

SFR not bit addressable

– : = this bit location is reserved

Timer / Counter 0 and 1

Timer/Counter 0 and 1 can be used in four operating modes as listed in **table 4**:

Table 4
Timer/Counter 0 and 1 Operating Modes

Mode	Description	TMOD				Input Clock	
		Gate	C/$\overline{T}$	M1	M0	internal	external (max)
0	8-bit timer/counter with a divide-by-32 prescaler	X	X	0	0	$f_{OSC}/12 \times 32$	$f_{OSC}/24 \times 32$
1	16-bit timer/counter	X	X	1	1	$f_{OSC}/12$	$f_{OSC}/24$
2	8-bit timer/counter with 8-bit autoreload	X	X	0	0	$f_{OSC}/12$	$f_{OSC}/24$
3	Timer/counter 0 used as one 8-bit timer/counter and one 8-bit timer Timer 1 stops	X	X	1	1	$f_{OSC}/12$	$f_{OSC}/24$

In the "timer" function (C/$\overline{T}$ = '0') the register is incremented every machine cycle. Therefore the count rate is $f_{OSC}/12$.

In the "counter" function the register is incremented in response to a 1-to-0 transition at its corresponding external input pin (P3.4/T0, P3.5/T1). Since it takes two machine cycles to detect a falling edge the max. count rate is $f_{OSC}/24$. External inputs $\overline{INT0}$ and $\overline{INT1}$ (P3.2, P3.3) can be programmed to function as a gate to facilitate pulse width measurements. **Figure 2** illustrates the input clock logic.

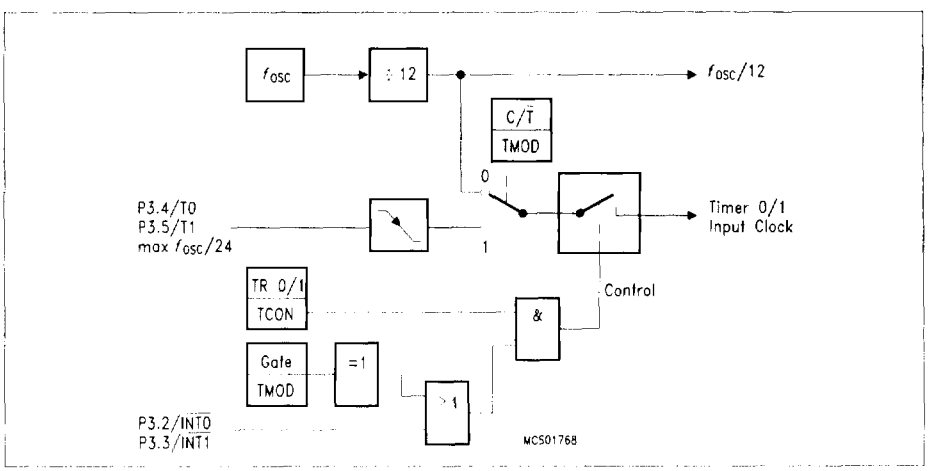


Figure 2
Timer/Counter 0 and 1 Input Clock Logic

Timer 2

Timer 2 is a 16-bit Timer/Counter with an up/down count feature. It can operate either as timer or as an event counter which is selected by bit C/$\overline{T2}$ (T2CON.1). It has three operating modes as shown in **table 5**.

Table 5
Timer/Counter 2 Operating Modes

Mode	T2CON			T2MOD	T2CON	P1.1/ T2EX	Remarks	Input Clock	
	R×CLK or T×CLK	CP/$\overline{RL2}$	TR2	DCEN	EXEN			internal	external (P1.0/T2)
16-bit Auto-reload	0	0	1	0	0	X	reload upon overflow	$f_{osc}/12$	max $f_{osc}/24$
	0	0	1	0	1	↓	reload trigger (falling edge)		
	0	0	1	1	X	0	Down counting		
	0	0	1	1	X	1	Up counting		
16-bit Capture	0	1	1	X	0	X	16 bit Timer/ Counter (only up-counting) capture TH2, TL2 → RC2H, RC2L	$f_{osc}/12$	max $f_{osc}/24$
	0	1	1	X	1	↓			
Baud Rate Generator	1	X	1	X	0	X	no overflow interrupt request (TF2) extra external interrupt ("Timer 2")	$f_{osc}/2$	max $f_{osc}/24$
	1	X	1	X	1	↓			
off	X	X	0	X	X	X	Timer 2 stops	–	–

Note: ↓ = falling edge

Serial Interface (USART)

The serial port is full duplex and can operate in four modes (one synchronous mode, three asynchronous modes) as illustrated in **table 6**. The possible baudrates can be calculated using the formulas given in **table 7**.

Table 6
USART Operating Modes

Mode	SCON		Baudrate	Description
	SM0	SM1		
0	0	0	$f_{osc}/12$	Serial data enters and exits through RxD. TxD outputs the shift clock. 8-bit are transmitted/received (LSB first)
1	0	1	Timer 1/2 overflow rate	8-bit UART 10 bits are transmitted (through TxD) or received (RxD)
2	1	0	$f_{osc}/32$ or $f_{osc}/64$	9-bit UART 11 bits are transmitted (TxD) or received (RxD)
3	1	1	Timer 1/2 overflow rate	9-bit UART Like mode 2 except the variable baud rate

Table 7
Formulas for Calculating Baudrates

Baud Rate derived from	Interface Mode	Baudrate
Oscillator	0 2	$f_{osc}/12$ $(2^{SMOD} \times f_{osc}) / 64$
Timer 1 (16-bit timer) (8-bit timer with 8-bit autoreload)	1,3 1,3	(2^{SMOD} x timer 1 overflow rate) /32 $(2^{SMOD} \times f_{osc}) / (32 \times 12 \times (256\text{-TH1}))$
Timer 2	1,3	f_{osc} / (32 x (65536-(RC2H, RC2L))

Interrupt System

The C501 provides 6 interrupt sources with two priority levels. **Figure 3** gives a general overview of the interrupt sources and illustrates the request and control flags.

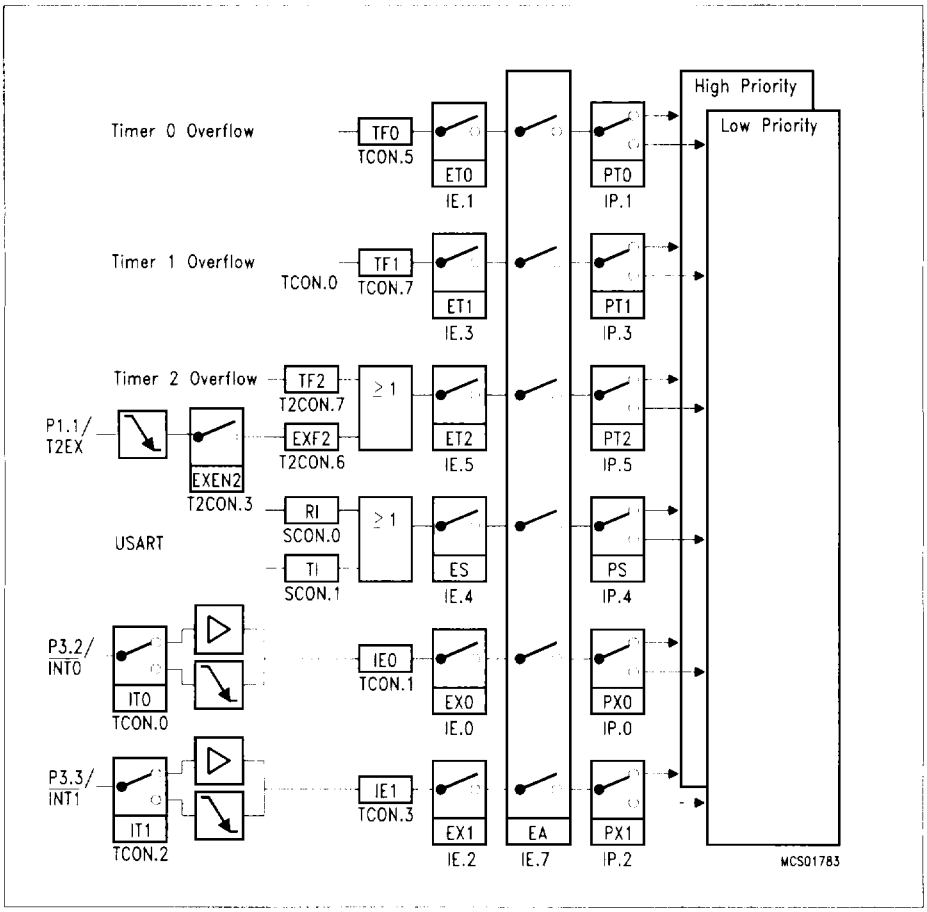


Figure 3
Interrupt Request Sources

Table 8
Interrupt Sources and their Corresponding Interrupt Vectors

Source (Request Flags)	Vector	Vector Address
IE0	External interrupt 0	0003_H
TF0	Timer 0 interrupt	$000B_H$
IE1	External interrupt 1	0013_H
TF1	Timer 1 interrupt	$001B_H$
RI + TI	Serial port interrupt	0023_H
TF2 + EXF2	Timer 2 interrupt	$002B_H$

A low-priority interrupt can itself be interrupted by a high-priority interrupt, but not by another low-priority interrupt. A high-priority interrupt cannot be interrupted by any other interrupt source.

If two requests of different priority level are received simultaneously, the request of higher priority is serviced. If requests of the same priority are received simultaneously, an internal polling sequence determines which request is serviced. Thus within each priority level there is a second priority structure determined by the polling sequence as shown in **table 9**.

Table 9
Interrupt Priority-Within-Level

Interrupt Source		Priority
External Interrupt 0,	IE0	High
Timer 0 Interrupt,	TF0	
External Interrupt 1,	IE1	↓
Timer 1 Interrupt,	TF1	
Serial Channel,	RI + TI	
Timer 2 Interrupt,	TF2 + EXF2	Low

Power Saving Modes

Two power down modes are available, the Idle Mode and Power Down Mode.

The bits PDE and IDLE of the register PCON select the Power Down mode or the Idle mode, respectively. If the Power Down mode and the Idle mode are set at the same time, the Power Down mode takes precedence. **Table 10** gives a general overview of the power saving modes.

Table 10
Power Saving Modes Overview

Mode	Entering Instruction Example	Leaving by	Remarks
Idle mode	ORL PCON, #01_H	– enabled interrupt – Hardware Reset	CPU is gated off CPU status registers maintain their data. Peripherals are active
Power-Down Mode	ORL PCON, #02_H	Hardware Reset	Oscillator is stopped, contents of on-chip RAM and SFR's are maintained (leaving Power Down Mode means redefinition of SFR contents).

In the Power Down mode of operation, V_{CC} can be reduced to minimize power consumption. It must be ensured, however, that V_{CC} is not reduced before the Power Down mode is invoked, and that V_{CC} is restored to its normal operating level, before the Power Down mode is terminated. The reset signal that terminates the Power Down mode also restarts the oscillator. The reset should not be activated before V_{CC} is restored to its normal operating level and must be held active long enough to allow the oscillator to restart and stabilize (similar to power-on reset).

Absolute Maximum Ratings

Ambient temperature under bias (T_A) ..... – 40 to + 85 °C
Storage temperature (T_{ST}) ..... – 65 to + 150 °C

Voltage on V_{CC} pins with respect to ground (V_{SS}) ..... – 0.5 V to 6.5 V
Voltage on any pin with respect to ground (V_{SS}) ..... – 0.5 V to V_{CC} + 0.5 V

Input current on any pin during overload condition ..... – 10 mA to + 10 mA
Absolute sum of all input currents during overload condition ..... | 100 mA |

Power dissipation ..... TBD

Note: *Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage of the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for longer periods may affect device reliability. During overload conditions ($V_{IN} > V_{CC}$ or $V_{IN} < V_{SS}$) the Voltage on V_{CC} pins with respect to ground (V_{SS}) must not exceed the values defined by the absolute maximum ratings.*

DC Characteristics

V_{CC} = 5 V + 10 %, – 15 %; V_{SS} = 0 V; T_A = 0 °C to 70 °C for the SAB-C501
T_A = – 40 °C to 85 °C for the SAF-C501

Parameter	Symbol	Limit Values		Unit	Test Condition
		min.	max.		
Input low voltage (except $\overline{EA}$, RESET)	V_{IL}	– 0.5	0.2 V_{CC} – 0.1	V	–
Input low voltage ($\overline{EA}$)	V_{IL1}	– 0.5	0.2 V_{CC} – 0.3	V	–
Input low voltage (RESET)	V_{IL2}	– 0.5	0.2 V_{CC} + 0.1	V	–
Input high voltage (except XTAL1, $\overline{EA}$, RESET)	V_{IH}	0.2 V_{CC} + 0.9	V_{CC} + 0.5	V	–
Input high voltage to XTAL1	V_{IH1}	0.7 V_{CC}	V_{CC} + 0.5	V	
Input high voltage to $\overline{EA}$, RESET	V_{IH2}	0.6 V_{CC}	V_{CC} + 0.5	V	–
Output low voltage (ports 1, 2, 3)	V_{OL}	–	0.45	V	I_{OL} = 1.6 mA [1]
Output low voltage (port 0, ALE, $\overline{PSEN}$)	V_{OL1}	–	0.45	V	I_{OL} = 3.2 mA [1]
Output high voltage (ports 1, 2, 3)	V_{OH}	2.4 0.9 V_{CC}	– –	V	I_{OH} = – 80 µA, I_{OH} = – 10 µA
Output high voltage (port 0 in external bus mode, ALE, $\overline{PSEN}$)	V_{OH1}	2.4 0.9 V_{CC}	– –	V	I_{OH} = – 800 µA [2], I_{OH} = – 80 µA [2]
Logic 0 input current (ports 1, 2, 3)	I_{IL}	– 10	– 50	µA	V_{IN} = 0.45 V
Logical 1-to-0 transition current (ports 1, 2, 3)	I_{TL}	– 65	– 650	µA	V_{IN} = 2 V
Input leakage current (port 0, $\overline{EA}$)	I_{LI}	–	± 1	µA	0.45 < V_{IN} < V_{CC}
Pin capacitance	C_{IO}	–	10	pF	f_C = 1 MHz, T_A = 25 °C
Power supply current:					
Active mode, 12 MHz [7]	I_{CC}	–	21	mA	V_{CC} = 5 V, [4]
Idle mode, 12 MHz [7]	I_{CC}	–	4.8	mA	V_{CC} = 5 V, [5]
Active mode, 24 MHz [7]	I_{CC}	–	36.2	mA	V_{CC} = 5 V, [4]
Idle mode, 24 MHz [7]	I_{CC}	–	8.2	mA	V_{CC} = 5 V, [5]
Active mode, 40 MHz [7]	I_{CC}	–	56.5	mA	V_{CC} = 5 V, [4]
Idle mode, 40 MHz [7]	I_{CC}	–	12.7	mA	V_{CC} = 5 V, [5]
Power Down Mode	I_{PD}	–	50	µA	V_{CC} = 2 ... 5.5 V [3]

1) Capacitive loading on ports 0 and 2 may cause spurious noise pulses to be superimposed on the V_{OL} of ALE and port 3. The noise is due to external bus capacitance discharging into the port 0 and port 2 pins when these pins make 1-to-0 transitions during bus operation. In the worst case (capacitive loading > 100 pF), the noise pulse on ALE line may exceed 0.8 V. In such cases it may be desirable to qualify ALE with a schmitt-trigger, or use an address latch with a schmitt-trigger strobe input.

2) Capacitive loading on ports 0 and 2 may cause the V_{OH} on ALE and $\overline{PSEN}$ to momentarily fall bellow the 0.9 V_{CC} specification when the address lines are stabilizing.

3) I_{PD} (Power Down Mode) is measured under following conditions:
$\overline{EA}$ = Port0 = V_{CC}; RESET = V_{SS}; XTAL2 = N.C.; XTAL1 = V_{SS}; all other pins are disconnected.

4) I_{CC} (active mode) is measured with:
XTAL1 driven with t_{CLCH}, t_{CHCL} = 5 ns, V_{IL} = V_{SS} + 0.5 V, V_{IH} = V_{CC} – 0.5 V; XTAL2 = N.C.;
$\overline{EA}$ = Port0 = RESET= V_{CC}; all other pins are disconnected. I_{CC} would be slightly higher if a crystal oscillator is used (appr. 1 mA).

5) I_{CC} (Idle mode) is measured with all output pins disconnected and with all peripherals disabled;
XTAL1 driven with t_{CLCH}, t_{CHCL} = 5 ns, V_{IL} = V_{SS} + 0.5 V, V_{IH} = V_{CC} – 0.5 V; XTAL2 = N.C.;
RESET = $\overline{EA}$ = V_{SS}; Port0 = V_{CC}; all other pins are disconnected;

7) $I_{CC\,max}$ at other frequencies is given by:
active mode: I_{CC} = 1.27 x f_{OSC} + 5.73
idle mode: I_{CC} = 0.28 x f_{OSC} + 1.45
where f_{OSC} is the oscillator frequency in MHz. I_{CC} values are given in mA and measured at V_{CC} = 5 V.

AC Characteristics for C501-L / C501-1R

V_{CC} = 5 V + 10 %, – 15 %; V_{SS} = 0 V

T_A = 0 °C to 70 °C for the SAB-C501
T_A = – 40 °C to 85 °C for the SAF-C501

(C_L for port 0, ALE and $\overline{PSEN}$ outputs = 100 pF; C_L for all other outputs = 80 pF)

Program Memory Characteristics

Parameter	Symbol	Limit Values				Unit
		12 MHz Clock		Variable Clock $1/t_{CLCL}$ = 3.5 MHz to 12 MHz		
		min.	max.	min.	max.	
ALE pulse width	t_{LHLL}	127	–	$2\,t_{CLCL} - 40$	–	ns
Address setup to ALE	t_{AVLL}	43	–	$t_{CLCL} - 40$	–	ns
Address hold after ALE	t_{LLAX}	30	–	$t_{CLCL} - 53$	–	ns
ALE low to valid instr in	t_{LLIV}	–	233	–	$4\,t_{CLCL} - 100$	ns
ALE to $\overline{PSEN}$	t_{LLPL}	58	–	$t_{CLCL} - 25$	–	ns
$\overline{PSEN}$ pulse width	t_{PLPH}	215	–	$3t_{CLCL} - 35$	–	ns
$\overline{PSEN}$ to valid instr in	t_{PLIV}	–	150	–	$3\,t_{CLCL} - 100$	ns
Input instruction hold after $\overline{PSEN}$	t_{PXIX}	0	–	0	–	ns
Input instruction float after $\overline{PSEN}$	t_{PXIZ}*)	–	63	–	$t_{CLCL} - 20$	ns
Address valid after $\overline{PSEN}$	t_{PXAV}*)	75	–	$t_{CLCL} - 8$	–	ns
Address to valid instr in	t_{AVIV}	–	302	–	$5\,t_{CLCL} - 115$	ns
Address float to $\overline{PSEN}$	t_{AZPL}	0	–	0	–	ns

*) Interfacing the C501 to devices with float times up to 75 ns is permissible. This limited bus contention will not cause any damage to port 0 Drivers.

AC Characteristics for C501-L / C501-1R (cont'd)

External Data Memory Characteristics

Parameter	Symbol	Limit Values				Unit
		12 MHz Clock		Variable Clock $1/t_{CLCL}$ = 3.5 MHz to 12 MHz		
		min.	max.	min.	max.	
$\overline{RD}$ pulse width	t_{RLRH}	400	–	$6t_{CLCL} - 100$	–	ns
$\overline{WR}$ pulse width	t_{WLWH}	400	–	$6t_{CLCL} - 100$	–	ns
Address hold after ALE	t_{LLAX2}	30	–	$t_{CLCL} - 53$	–	ns
$\overline{RD}$ to valid data in	t_{RLDV}	–	252	–	$5t_{CLCL} - 165$	ns
Data hold after $\overline{RD}$	t_{RHDX}	0	–	0	–	ns
Data float after $\overline{RD}$	t_{RHDZ}	–	97	–	$2t_{CLCL} - 70$	ns
ALE to valid data in	t_{LLDV}	–	517	–	$8t_{CLCL} - 150$	ns
Address to valid data in	t_{AVDV}	–	585	–	$9t_{CLCL} - 165$	ns
ALE to $\overline{WR}$ or $\overline{RD}$	t_{LLWL}	200	300	$3t_{CLCL} - 50$	$3t_{CLCL} + 50$	ns
Address valid to $\overline{WR}$ or $\overline{RD}$	t_{AVWL}	203	–	$4t_{CLCL} - 130$	–	ns
$\overline{WR}$ or $\overline{RD}$ high to ALE high	t_{WHLH}	43	123	$t_{CLCL} - 40$	$t_{CLCL} + 40$	ns
Data valid to $\overline{WR}$ transition	t_{QVWX}	33	–	$t_{CLCL} - 50$	–	ns
Data setup before $\overline{WR}$	t_{QVWH}	433	–	$7t_{CLCL} - 150$	–	ns
Data hold after $\overline{WR}$	t_{WHQX}	33	–	$t_{CLCL} - 50$	–	ns
Address float after $\overline{RD}$	t_{RLAZ}	–	0	–	0	ns

AC Characteristics for C501-L24 / C501-1R24 (cont'd)

External Clock Drive Characteristics

Parameter	Symbol	Limit Values		Unit
		Variable Clock Freq. = 3.5 MHz to 12 MHz		
		min.	max.	
Oscillator period	t_{CLCL}	83.3	285.7	ns
High time	t_{CHCX}	20	$t_{CLCL} - t_{CLCX}$	ns
Low time	t_{CLCX}	20	$t_{CLCL} - t_{CHCX}$	ns
Rise time	t_{CLCH}	–	20	ns
Fall time	t_{CHCL}	–	20	ns

AC Characteristics for C501-L24 / C501-1R24

V_{CC} = 5 V + 10 %, – 15 %; V_{SS} = 0 V

T_A = 0 °C to 70 °C for the SAB-C501

(C_L for port 0, ALE and $\overline{PSEN}$ outputs = 100 pF; C_L for all other outputs = 80 pF)

Program Memory Characteristics

Parameter	Symbol	Limit Values				Unit
		24 MHz Clock		Variable Clock $1/t_{CLCL}$ = 3.5 MHz to 24 MHz		
		min.	max.	min.	max.	
ALE pulse width	t_{LHLL}	43	–	$2\,t_{CLCL} - 40$	–	ns
Address setup to ALE	t_{AVLL}	17	–	$t_{CLCL} - 25$	–	ns
Address hold after ALE	t_{LLAX}	17	–	$t_{CLCL} - 25$	–	ns
ALE low to valid instr in	t_{LLIV}	–	80	–	$4\,t_{CLCL} - 87$	ns
ALE to $\overline{PSEN}$	t_{LLPL}	22	–	$t_{CLCL} - 20$	–	ns
$\overline{PSEN}$ pulse width	t_{PLPH}	95	–	$3\,t_{CLCL} - 30$	–	ns
$\overline{PSEN}$ to valid instr in	t_{PLIV}	–	60	–	$3\,t_{CLCL} - 65$	ns
Input instruction hold after $\overline{PSEN}$	t_{PXIX}	0	–	0	–	ns
Input instruction float after $\overline{PSEN}$	t_{PXIZ}*)	–	32	–	$t_{CLCL} - 10$	ns
Address valid after $\overline{PSEN}$	t_{PXAV}*)	37	–	$t_{CLCL} - 5$	–	ns
Address to valid instr in	t_{AVIV}	–	148	–	$5\,t_{CLCL} - 60$	ns
Address float to $\overline{PSEN}$	t_{AZPL}	0	–	0	–	ns

*) Interfacing the C501 to devices with float times up to 37 ns is permissible. This limited bus contention will not cause any damage to port 0 Drivers.

AC Characteristics for C501-L24 / C501-1R24 (cont'd)

External Data Memory Characteristics

Parameter	Symbol	Limit Values				Unit
		24 MHz Clock		Variable Clock $1/t_{CLCL}$ = 3.5 MHz to 24 MHz		
		min.	max.	min.	max.	
$\overline{RD}$ pulse width	t_{RLRH}	180	–	$6\,t_{CLCL} - 70$	–	ns
$\overline{WR}$ pulse width	t_{WLWH}	180	–	$6\,t_{CLCL} - 70$	–	ns
Address hold after ALE	t_{LLAX2}	15	–	$t_{CLCL} - 27$	–	ns
$\overline{RD}$ to valid data in	t_{RLDV}	–	118	–	$5\,t_{CLCL} - 90$	ns
Data hold after $\overline{RD}$	t_{RHDX}	0	–	0	–	ns
Data float after $\overline{RD}$	t_{RHDZ}	–	63	–	$2\,t_{CLCL} - 20$	ns
ALE to valid data in	t_{LLDV}	–	200	–	$8\,t_{CLCL} - 133$	ns
Address to valid data in	t_{AVDV}	–	220	–	$9\,t_{CLCL} - 155$	ns
ALE to $\overline{WR}$ or $\overline{RD}$	t_{LLWL}	75	175	$3\,t_{CLCL} - 50$	$3\,t_{CLCL} + 50$	ns
Address valid to $\overline{WR}$ or $\overline{RD}$	t_{AVWL}	67	–	$4\,t_{CLCL} - 97$	–	ns
$\overline{WR}$ or $\overline{RD}$ high to ALE high	t_{WHLH}	17	67	$t_{CLCL} - 25$	$t_{CLCL} + 25$	ns
Data valid to $\overline{WR}$ transition	t_{QVWX}	5	–	$t_{CLCL} - 37$	–	ns
Data setup before $\overline{WR}$	t_{QVWH}	170	–	$7\,t_{CLCL} - 122$	–	ns
Data hold after $\overline{WR}$	t_{WHQX}	15	–	$t_{CLCL} - 27$	–	ns
Address float after $\overline{RD}$	t_{RLAZ}	–	0	–	0	ns

AC Characteristics for C501-L24 / C501-1R24 (cont'd)

External Clock Drive Characteristics

Parameter	Symbol	Limit Values		Unit
		Variable Clock Freq. = 3.5 MHz to 24 MHz		
		min.	max.	
Oscillator period	t_{CLCL}	41.7	285.7	ns
High time	t_{CHCX}	12	$t_{CLCL} - t_{CLCX}$	ns
Low time	t_{CLCX}	12	$t_{CLCL} - t_{CHCX}$	ns
Rise time	t_{CLCH}	–	12	ns
Fall time	t_{CHCL}	–	12	ns

AC Characteristics for C501-L40 / C501-1R40

V_{CC} = 5 V + 10 %, – 15 %; V_{SS} = 0 V

T_A = 0 °C to 70 °C for the SAB-C501
T_A = – 40 °C to 85 °C for the SAF-C501

(C_L for port 0, ALE and $\overline{PSEN}$ outputs = 100 pF; C_L for all other outputs = 80 pF)

Program Memory Characteristics

Parameter	Symbol	Limit Values				Unit
		40 MHz Clock		Variable Clock $1/t_{CLCL}$ = 3.5 MHz to 40 MHz		
		min.	max.	min.	max.	
ALE pulse width	t_{LHLL}	35	–	$2\,t_{CLCL} - 15$	–	ns
Address setup to ALE	t_{AVLL}	10	–	$t_{CLCL} - 15$	–	ns
Address hold after ALE	t_{LLAX}	10	–	$t_{CLCL} - 15$	–	ns
ALE low to valid instr in	t_{LLIV}	–	55	–	$4\,t_{CLCL} - 45$	ns
ALE to $\overline{PSEN}$	t_{LLPL}	10	–	$t_{CLCL} - 15$	–	ns
$\overline{PSEN}$ pulse width	t_{PLPH}	60	–	$3\,t_{CLCL} - 15$	–	ns
$\overline{PSEN}$ to valid instr in	t_{PLIV}	–	25	–	$3\,t_{CLCL} - 50$	ns
Input instruction hold after $\overline{PSEN}$	t_{PXIX}	0	–	0	–	ns
Input instruction float after $\overline{PSEN}$	t_{PXIZ}*)	–	20	–	$t_{CLCL} - 5$	ns
Address valid after $\overline{PSEN}$	t_{PXAV}*)	20	–	$t_{CLCL} - 5$	–	ns
Address to valid instr in	t_{AVIV}	–	65	–	$5\,t_{CLCL} - 60$	ns
Address float to $\overline{PSEN}$	t_{AZPL}	– 5	–	– 5	–	ns

*) Interfacing the C501 to devices with float times up to 25 ns is permissible. This limited bus contention will not cause any damage to port 0 Drivers.

AC Characteristics for C501-L40 / C501-1R40 (cont'd)

External Data Memory Characteristics

Parameter	Symbol	Limit Values				Unit
		40 MHz Clock		Variable Clock $1/t_{CLCL}$ = 3.5 MHz to 40 MHz		
		min.	max.	min.	max.	
$\overline{RD}$ pulse width	t_{RLRH}	120	–	6 t_{CLCL} – 30	–	ns
$\overline{WR}$ pulse width	t_{WLWH}	120	–	6 t_{CLCL} – 30	–	ns
Address hold after ALE	t_{LLAX2}	10	–	t_{CLCL} – 15	–	ns
$\overline{RD}$ to valid data in	t_{RLDV}	–	75	–	5 t_{CLCL} – 50	ns
Data hold after $\overline{RD}$	t_{RHDX}	0	–	0	–	ns
Data float after $\overline{RD}$	t_{RHDZ}	–	38	–	2 t_{CLCL} – 12	ns
ALE to valid data in	t_{LLDV}	–	150	–	8 t_{CLCL} – 50	ns
Address to valid data in	t_{AVDV}	–	150	–	9 t_{CLCL} – 75	ns
ALE to $\overline{WR}$ or $\overline{RD}$	t_{LLWL}	60	90	3 t_{CLCL} – 15	3 t_{CLCL} + 15	ns
Address valid to $\overline{WR}$ or $\overline{RD}$	t_{AVWL}	70	–	4 t_{CLCL} – 30	–	ns
$\overline{WR}$ or $\overline{RD}$ high to ALE high	t_{WHLH}	10	40	t_{CLCL} – 15	t_{CLCL} + 15	ns
Data valid to $\overline{WR}$ transition	t_{QVWX}	5	–	t_{CLCL} – 20	–	ns
Data setup before $\overline{WR}$	t_{QVWH}	125	–	7 t_{CLCL} – 50	–	ns
Data hold after $\overline{WR}$	t_{WHQX}	5	–	t_{CLCL} – 20	–	ns
Address float after $\overline{RD}$	t_{RLAZ}	–	0	–	0	ns

AC Characteristics for C501-L40 / C501-1R40 (cont'd)

External Clock Drive Characteristics

Parameter	Symbol	Limit Values		Unit
		Variable Clock Freq. = 3.5 MHz to 40 MHz		
		min.	max.	
Oscillator period	t_{CLCL}	25	285.7	ns
High time	t_{CHCX}	10	$t_{CLCL} - t_{CLCX}$	ns
Low time	t_{CLCX}	10	$t_{CLCL} - t_{CHCX}$	ns
Rise time	t_{CLCH}	–	10	ns
Fall time	t_{CHCL}	–	10	ns

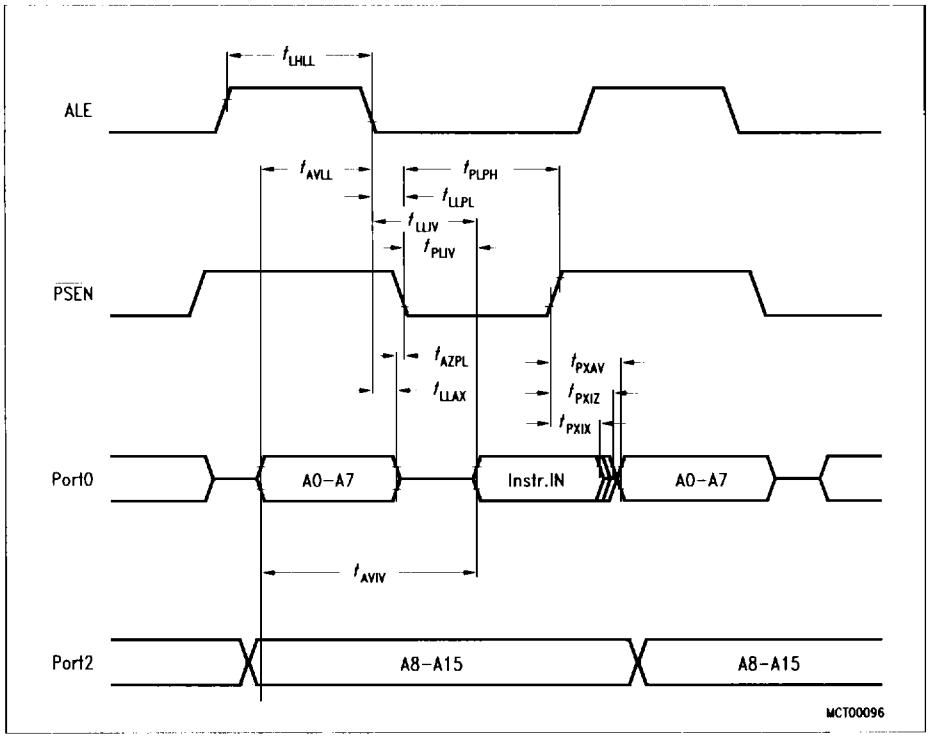


Figure 4
Program Memory Read Cycle

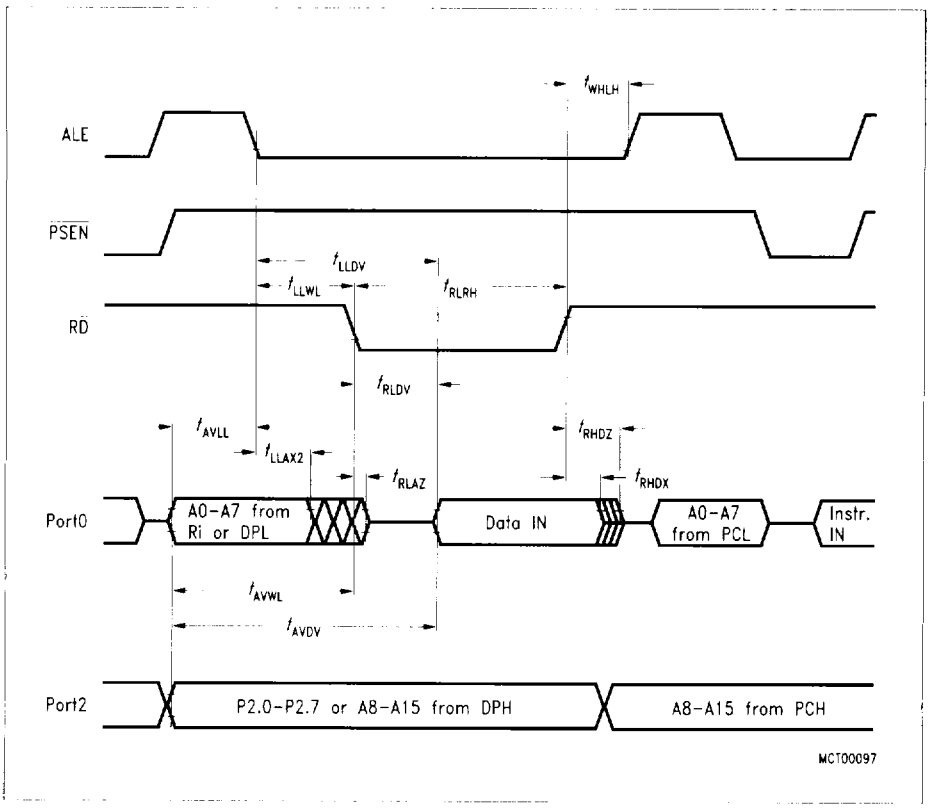


Figure 5
Data Memory Read Cycle

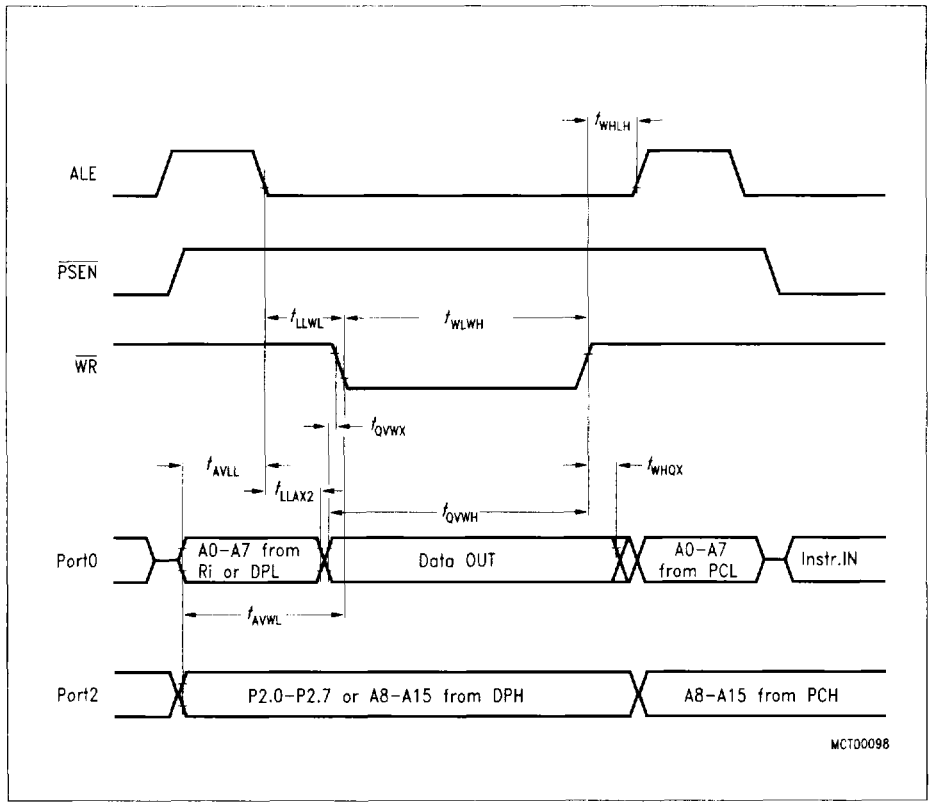


Figure 6
Data Memory Write Cycle

ROM Verification Characteristics for C501-1R

ROM Verification Mode 1

Parameter	Symbol	Limit Values		Unit
		min.	max.	
Address to valid data	t_{AVQV}	–	48 t_{CLCL}	ns
ENABLE to valid data	t_{ELQV}	–	48 t_{CLCL}	ns
Data float after ENABLE	t_{EHQZ}	0	48 t_{CLCL}	ns
Oscillator frequency	$1/t_{CLCL}$	4	6	MHz

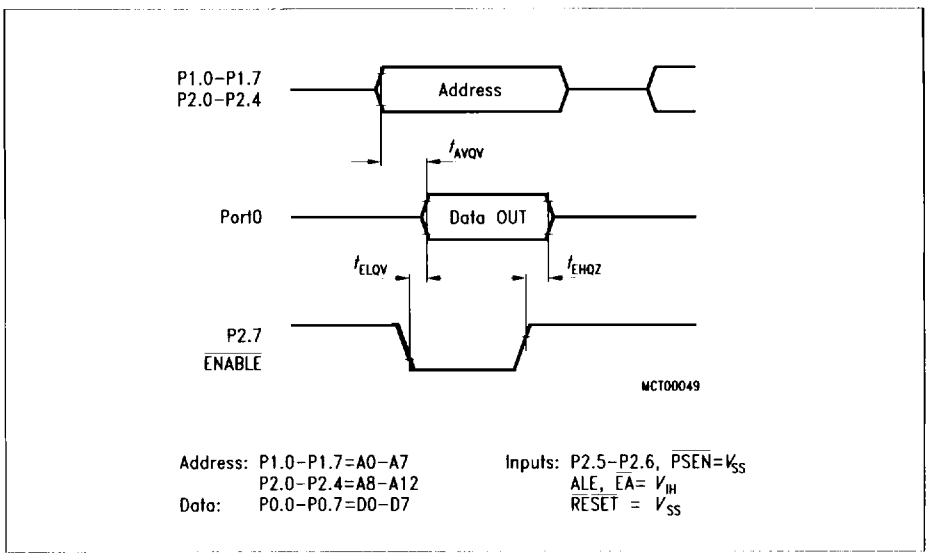
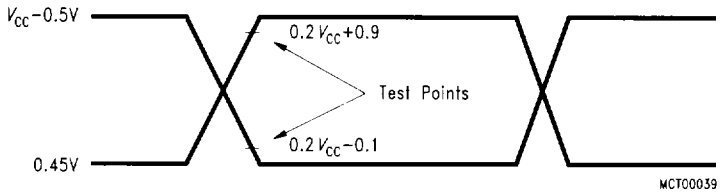
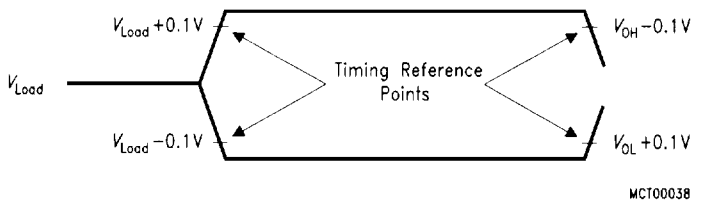


Figure 7
ROM Verification Mode 1



AC Inputs during testing are driven at V_{CC} – 0.5 V for a logic '1' and 0.45 V for a logic '0'. Timing measurements are made at V_{IHmin} for a logic '1' and V_{ILmax} for a logic '0'.

Figure 8
AC Testing: Input, Output Waveforms



For timing purposes a port pin is no longer floating when a 100 mV change from load voltage occurs and begins to float when a 100 mV change from the loaded V_{OH} / V_{OL} level occurs. I_{OL} / I_{OH} ≥ ± 20 mA.

Figure 9
AC Testing: Float Waveforms

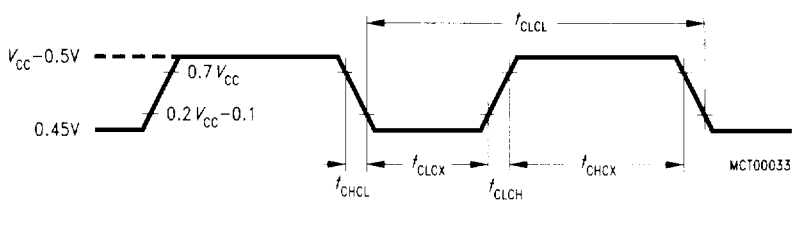


Figure 10
External Clock Cycle

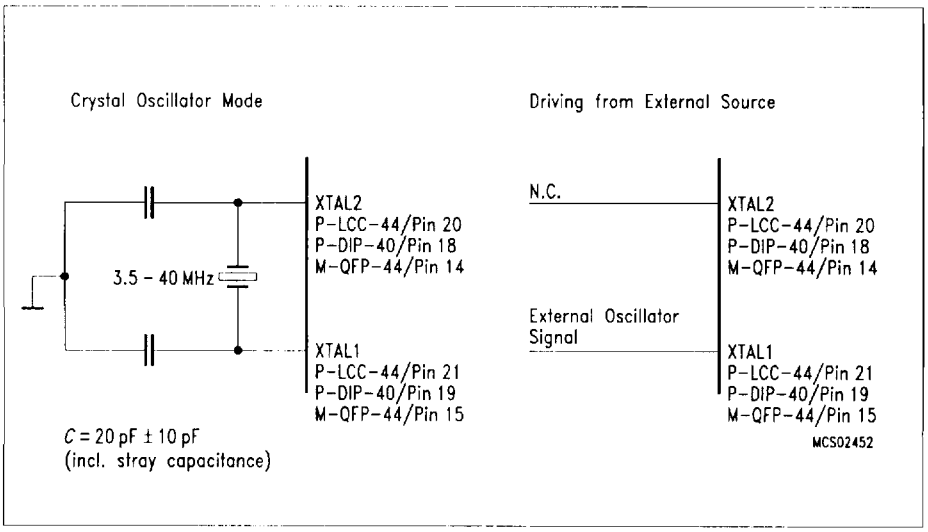
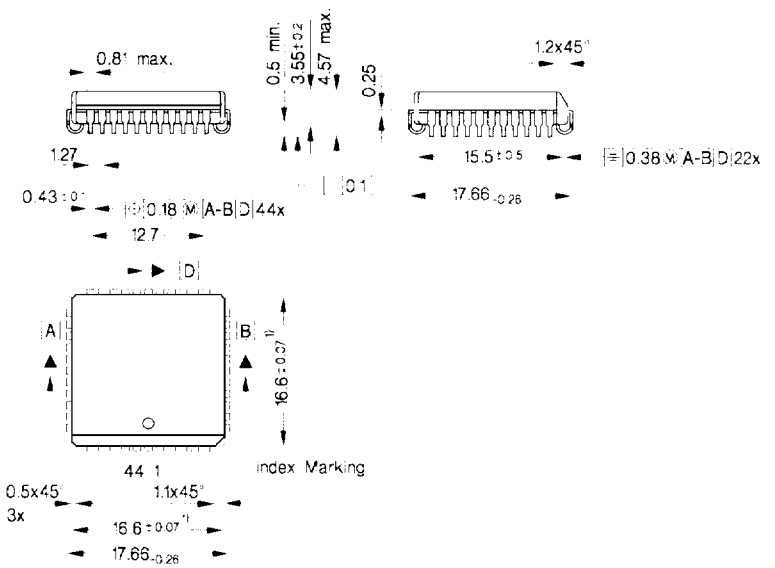


Figure 11
Recommended Oscillator Circuits

Package Outlines

P-LCC-44 – SMD for C501-L / C501-1R ("non-G" Versions)
(Plastic Leaded Chip-Carrier)

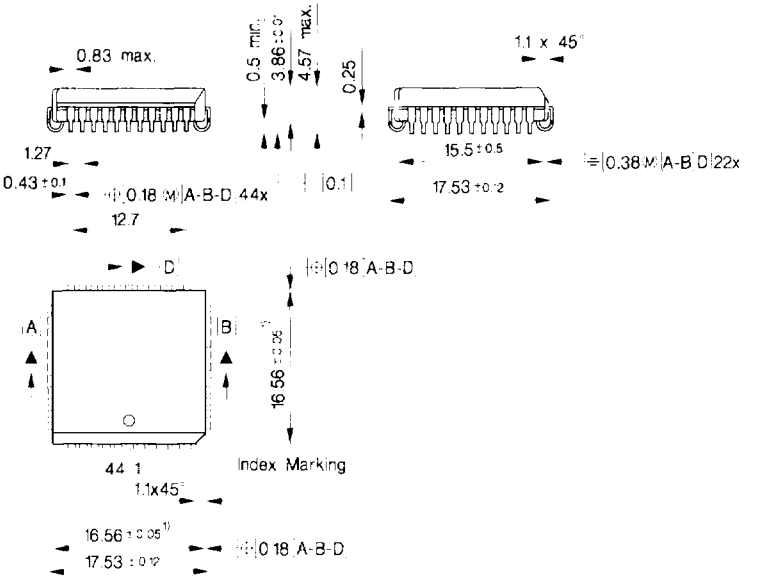


1) Does not include plastic or metal protrusion of 0.15 max. per side

Sorts of Packing
Package outlines for tubes, trays etc. are contained in our Data Book "Package Information"
SMD = Surface Mounted Device

Dimensions in mm

P-LCC-44 – SMD for C501G-L / C501G-1R ("G" Versions)
(Plastic Leaded Chip-Carrier)

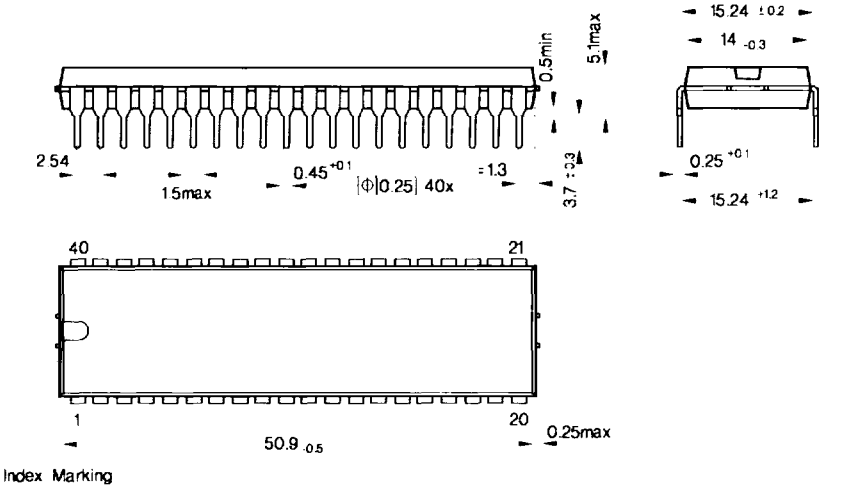


1) Does not include plastic or metal protrusion of 0.15 max. per side

Sorts of Packing
Package outlines for tubes, trays etc. are contained in our Data Book "Package Information"
SMD = Surface Mounted Device

Dimensions in mm

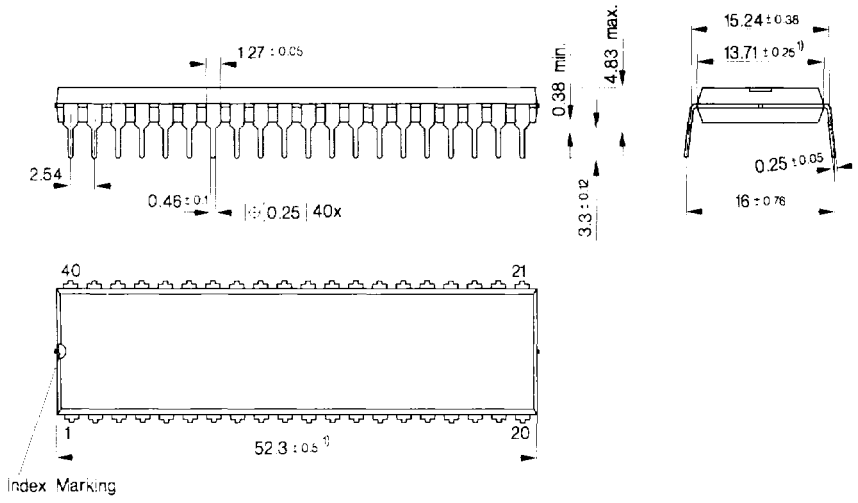
P-DIP-40 for C501-L / C501-1R ("non-G" Versions)
(Plastic Dual in-Line Package)



Sorts of Packing
Package outlines for tubes, trays etc. are contained in our Data Book "Package Information"
SMD = Surface Mounted Device

Dimensions in mm

P-DIP-40 for C501G-L / C501G-1R ("G" Versions)
(Plastic Dual in-Line Package)

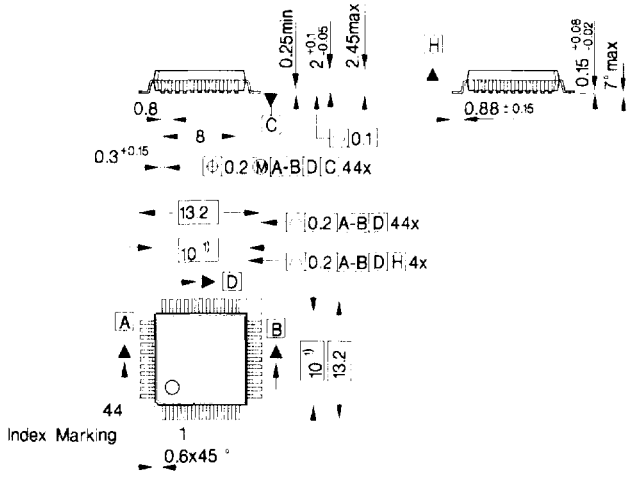


1) Does not include plastic or metal protrusion of 0.25 max. per side

Sorts of Packing
Package outlines for tubes, trays etc. are contained in our Data Book "Package Information"
SMD = Surface Mounted Device

Dimensions in mm

P-MQFP-44 – SMD for C501-L / C501-1R ("non-G" Versions)
(Plastic Metric Quad Flat Package)



1) Does not include plastic or metal protrusion of 0.25 max. per side

Sorts of Packing
Package outlines for tubes, trays etc. are contained in our Data Book "Package Information".
SMD = Surface Mounted Device

Dimensions in mm

P-MQFP-44 – SMD for C501G-L / C501G-1R ("G" Versions)
(Plastic Metric Quad Flat Package)

Detailed schematic is to be defined

Sorts of Packing
Package outlines for tubes, trays etc. are contained in our Data Book "Package Information"
SMD = Surface Mounted Device

Dimensions in mm