

**Preliminary** TOSHIBA CMOS Digital Integrated Circuit Silicon Monolithic

# T6K41

## Column and Row Driver LSI for a Dot Matrix Graphic LCD

The T6K41 is a driver for a small-to-medium-sized dot matrix graphic LCD, especially for four-gray-scale monochromatic STN LCDs. This driver can be interfaced to the MPU via an 8-bit (80/68-series) or a serial interface, and is operated asynchronously with the MPU.

Since the T6K41 contains a CR oscillator, it can generate the timing signals required for the LCD.

The T6K41 has 128 outputs for the LCD drive (segment) signals that constitute the display data, 128 outputs for the LCD drive (common) signals that constitute the scanning signals and 16 bits of static-LCD drive (icon) signals. Furthermore, the T6K41 has 128 × 128 × 2 bits display RAM and 16-bit register. Thus, this single device allows you to drive an LCD panel comprised of up to 128 × 128 + 16 dots with a minimize of power requirement. It also incorporates a gray-scale function.

The display RAM of the T6K41 is a two-port RAM so that the MPU access it without any wait time.

To minimize power consumption, the T6K41 has a display change mode (power save mode) in which only a 16-dot icon can be displayed. Furthermore, it has various built-in analog circuits such as a voltage regulator, voltage divider resistors, power supply op-amp, DC-DC converters (×2 to ×6) and a contrast control (electronic volume) circuit. All these circuits enable the LCD panel to be driven with a single power supply.

Unit: mm		
T6K41	Lead Pitch	
	IN	OUT

Please contact your nearest TOSHIBA dealer for individual package dimensions.

No idea

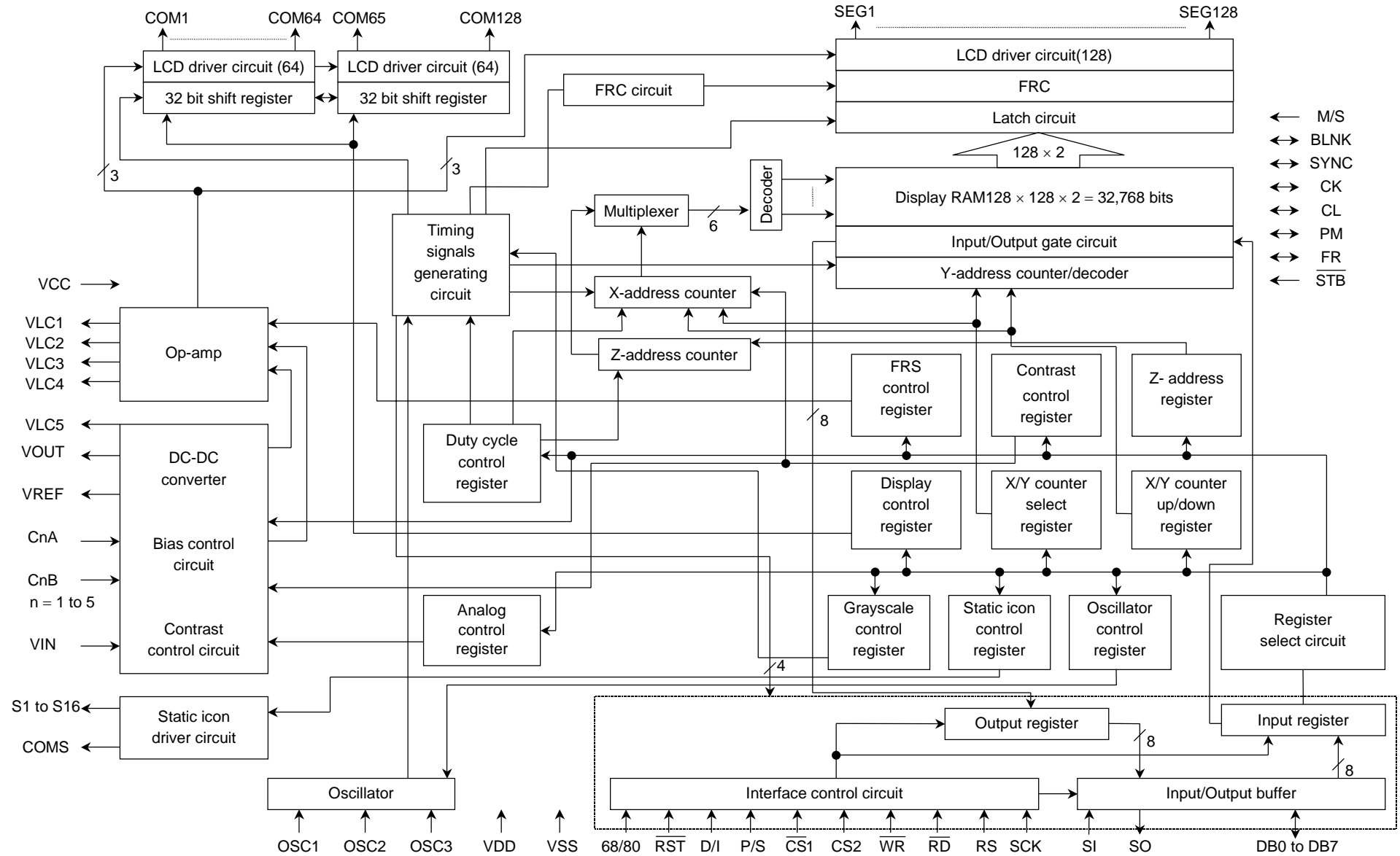
TCP (Tape Carrier Package)

## Features

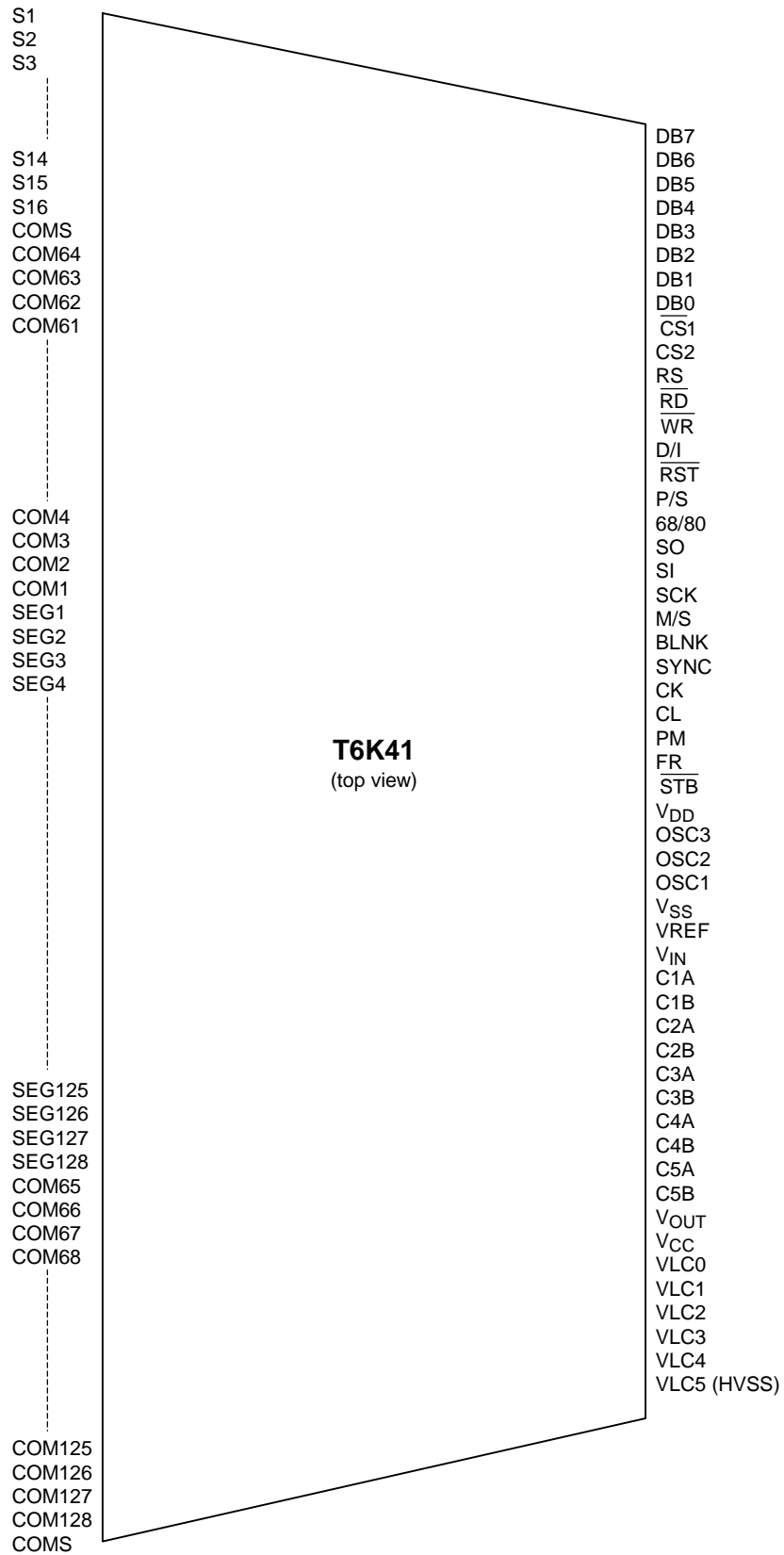
- LCD drive outputs : 128 rows (common) × 128 columns (segment) + 16 icons
- Display RAM : 128 × 128 × 2 = 32,768 bits, 2-port RAM
- Gray scales : 4 gray-scale levels (palette function)
- Word length : 8-bit/word
- Display duty cycle : 1/72, 1/80, 1/100 or 1/128 duty during Normal Mode.  
(Duty cycles in Normal Mode are set in software by the MPU.)
- Display modes : Normal Mode: Full display  
Power Save Mode: Icon display  
Partial Display Mode: Partial display  
Standby Mode: Clock stopped (all internal circuits turned off)
- MPU : 8-bit (68/80 Series) parallel or serial interface
- Oscillator : Built-in CR oscillator with external resistors
- Power supply circuits : Resistors to divide bias voltage, op-amp for LCD drive power supply, DC-DC converters (×2 to ×6), contrast control circuit.
- Operating voltage :  $V_{DD} = 2.4\text{ V to }3.3\text{ V}$ ,  $V_{IN} = 2.7\text{ V to }3.3\text{ V}$
- LCD drive voltage :  $V_{CC} = 16.5\text{ V (max)}$   
 $V_{OUT} = 15.4\text{ V (typ.)}$  or  $V_{OUT} = 13.0\text{ V (typ.)}$  (for internal voltage regulator)  
These voltages can be selected in software.
- CMOS process
- Low power consumption :  $I_{SS} = 300\text{ }\mu\text{A (typ.)}$   
Conditions:  $V_{DD} = V_{IN} = 3.0\text{ V}$ , when DC-DC converter is used (×6 Mode), LCD non-loaded,  $T_a = 25^\circ\text{C}$ , 1/128 duty, 1/12 bias,  $f_{osc} = 82\text{ kHz}$  (when internal oscillator is used), voltage regulator ON, op-amp ON, display data = ALL 4-gray-scale checker pattern, no data access from MPU.
- Temperature coefficient of voltage regulator:  $-0.05\%/^\circ\text{C}$
- Package :

Product	Package
T6K41 (xxx, xxx)	TCP (Tape carrier package)
JBT6K41-AS	Gold bump chip

## Block Diagram



**Pin Assignment**



Note 1: The above diagram shows the pin configuration of the LSI chip, not that of the tape carrier package.

## Pad Specification

Note 2: Please refer to the T6K41 technical datasheet for pad specification.

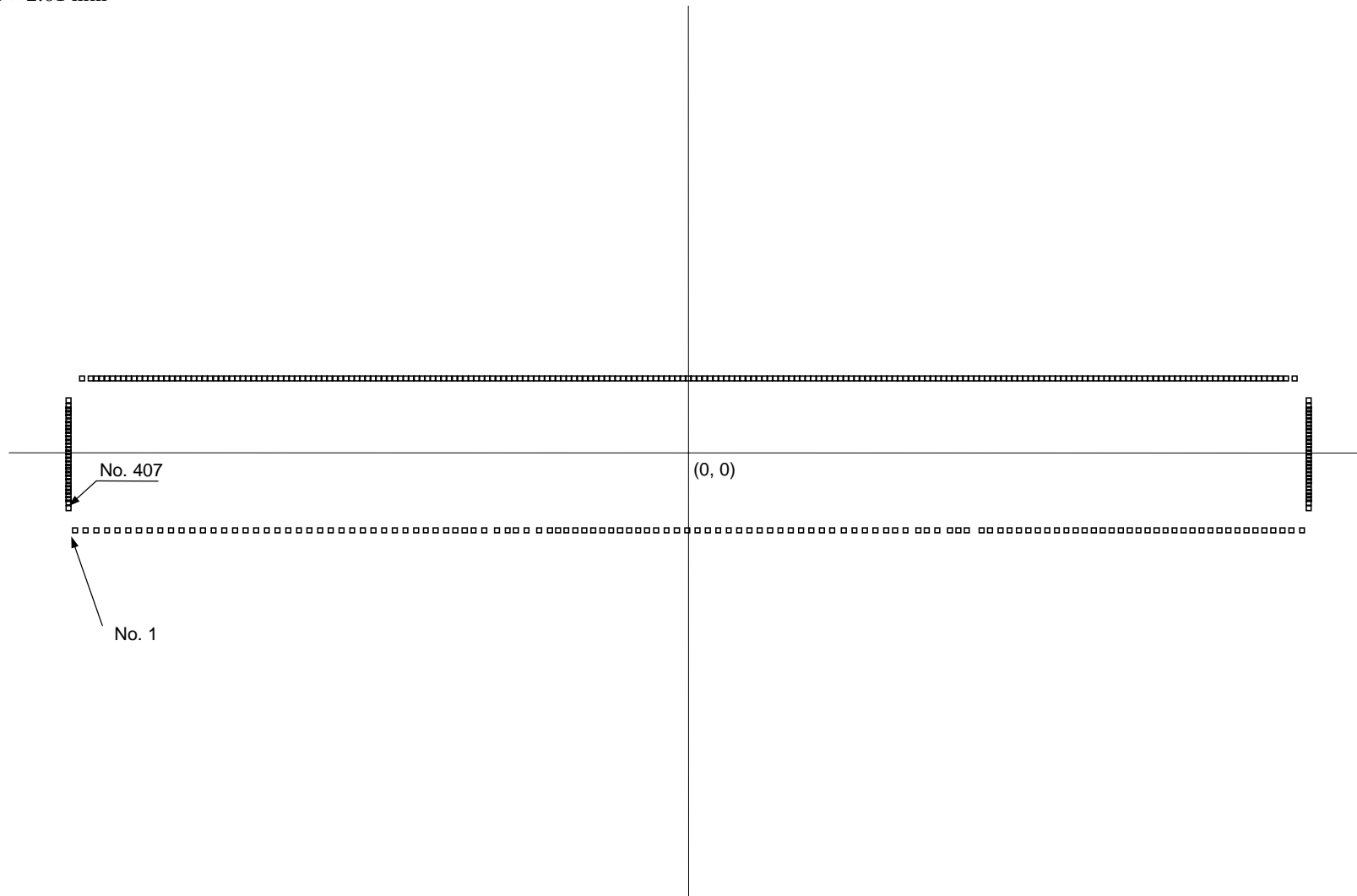
Item	Size	Unit
Chip Size	12300 × 2610	μm
Chip Tip Coordinates	(1)	-6150, -1305
	(2)	-6150, -1305
	(3)	6150, 1305
	(4)	6150, -1305
Bump Pitch	52	μm
Bump Height	14±4	μm

Item	Number of Pins
Input pin	105 Pins (including Dummy pins)
Output pin	283 Pins (including Dummy pins)
TEST Pin	2 Pins (Note 3)
FUSE Pin	17 Pins (Note 3)

Note 3: TEST and FUSE pins are LSI test pins, leave these pins open.

## Pad Layout

Chip size: 12.3 × 2.61 mm



Note 4: Please refer to the T6K41 technical datasheet for pad layout and coordinates values.

## Pad Coordinates (1)

[Unit:  $\mu\text{m}$ ]

No.	NAME	X-Point	Y-Point	No.	NAME	X-Point	Y-Point	No.	NAME	X-Point	Y-Point
1	VCL5	-5871	-1124	46	TDUMMY8	-1328	-1124	91	TDUMMY19	2986	-1124
2	VLC5	-5769	-1124	47	DMYVSS	-1249	-1124	92	/STB	3072	-1124
3	VLC5	-5667	-1124	48	V <sub>SS</sub>	-1170	-1124	93	FR	3161	-1124
4	VLC5	-5565	-1124	49	V <sub>SS</sub>	-1084	-1124	94	PM	3252	-1124
5	VLC4	-5463	-1124	50	V <sub>SS</sub>	-998	-1124	95	CL	3343	-1124
6	VLC4	-5361	-1124	51	V <sub>SS</sub>	-912	-1124	96	CK	3434	-1124
7	VLC3	-5259	-1124	52	V <sub>SS</sub>	-826	-1124	97	SYNC	3525	-1124
8	VLC3	-5157	-1124	53	TEST3	-740	-1124	98	BLNK	3616	-1124
9	VLC2	-5055	-1124	54	OSC1	-654	-1124	99	M/S	3705	-1124
10	VLC2	-4953	-1124	55	DMYVSS	-568	-1124	100	SCK	3791	-1124
11	VLC1	-4851	-1124	56	OSC2	-482	-1124	101	SI	3877	-1124
12	VLC1	-4749	-1124	57	DMYVSS	-396	-1124	102	SO	3963	-1124
13	VLC0	-4647	-1124	58	OSC3	-310	-1124	103	DMYVDD	4049	-1124
14	VLC0	-4545	-1124	59	FUSE31	-210	-1124	104	68/80	4135	-1124
15	VLC0	-4443	-1124	60	FUSE32	-111	-1124	105	DMYVSS	4221	-1124
16	VLC0	-4341	-1124	61	FUSE3G	-12	-1124	106	P/S	4307	-1124
17	VCC1	-4239	-1124	62	FUSE33	87	-1124	107	DMYVDD	4393	-1124
18	VCC1	-4137	-1124	63	FUSE34	186	-1124	108	/RST	4479	-1124
19	VCC1	-4035	-1124	64	FUSE21	285	-1124	109	D/I	4565	-1124
20	VCC1	-3933	-1124	65	FUSE22	384	-1124	110	/WR	4651	-1124
21	TEST2	-3831	-1124	66	FUSE23	483	-1124	111	/RD	4737	-1124
22	VOUT	-3729	-1124	67	FUSE2G	582	-1124	112	RS	4823	-1124
23	VOUT	-3627	-1124	68	FUSE24	681	-1124	113	CS2	4909	-1124
24	C5B	-3525	-1124	69	FUSE25	780	-1124	114	/CS1	4995	-1124
25	C5A	-3423	-1124	70	FUSE11	879	-1124	115	DMYVSS	5081	-1124
26	C4B	-3321	-1124	71	FUSE12	978	-1124	116	DB0	5167	-1124
27	C4A	-3219	-1124	72	FUSE13	1077	-1124	117	DB1	5253	-1124
28	C3B	-3117	-1124	73	FUSE1G	1176	-1124	118	DB2	5339	-1124
29	C3A	-3015	-1124	74	FUSE14	1275	-1124	119	DB3	5425	-1124
30	C2B	-2913	-1124	75	FUSE15	1374	-1124	120	DB4	5511	-1124
31	C2A	-2811	-1124	76	V <sub>DD</sub>	1486	-1124	121	DB5	5597	-1124
32	C1B	-2709	-1124	77	V <sub>DD</sub>	1587	-1124	122	DB6	5683	-1124
33	C1A	-2607	-1124	78	V <sub>DD</sub>	1688	-1124	123	DB7	5769	-1124
34	DMYVSS	-2514	-1124	79	V <sub>DD</sub>	1789	-1124	124	DMYVDD	5871	-1124
35	VIN	-2421	-1124	80	V <sub>DD</sub>	1890	-1124	125	DUMMY1	5934	-803
36	VIN	-2319	-1124	81	TDUMMY9	1976	-1124	126	DUMMY2	5934	-721
37	DMYVSS	-2231	-1124	82	TDUMMY10	2077	-1124	127	DUMMY3	5934	-669
38	VREG	-2142	-1124	83	TDUMMY11	2199	-1124	128	DUMMY4	5934	-617
39	TDUMMY1	-2056	-1124	84	TDUMMY12	2279	-1124	129	DUMMY5	5934	-565
40	TDUMMY2	-1955	-1124	85	TDUMMY13	2380	-1124	130	DUMMY6	5934	-513
41	TDUMMY3	-1833	-1124	86	TDUMMY14	2502	-1124	131	S1	5934	-461
42	TDUMMY4	-1732	-1124	87	TDUMMY15	2582	-1124	132	S2	5934	-409
43	TDUMMY5	-1652	-1124	88	TDUMMY16	2662	-1124	133	S3	5934	-357
44	TDUMMY6	-1551	-1124	89	TDUMMY17	2805	-1124	134	S4	5934	-305
45	TDUMMY7	-1429	-1124	90	TDUMMY18	2885	-1124	135	S5	5934	-253

## Pad Coordinates (2)

[Unit:  $\mu\text{m}$ ]

No.	NAME	X-Point	Y-Point	No.	NAME	X-Point	Y-Point	No.	NAME	X-Point	Y-Point
136	S6	5934	-201	181	COM33	4419	1087	226	SEG13	2079	1087
137	S7	5934	-149	182	COM32	4367	1087	227	SEG14	2027	1087
138	S8	5934	-97	183	COM31	4315	1087	228	SEG15	1975	1087
139	S9	5934	-45	184	COM30	4263	1087	229	SEG16	1923	1087
140	S10	5934	8	185	COM29	4211	1087	230	SEG17	1871	1087
141	S11	5934	60	186	COM28	4159	1087	231	SEG18	1819	1087
142	S12	5934	112	187	COM27	4107	1087	232	SEG19	1767	1087
143	S13	5934	164	188	COM26	4055	1087	233	SEG20	1715	1087
144	S14	5934	216	189	COM25	4003	1087	234	SEG21	1663	1087
145	S15	5934	268	190	COM24	3951	1087	235	SEG22	1611	1087
146	S16	5934	320	191	COM23	3899	1087	236	SEG23	1559	1087
147	COMS2	5934	372	192	COM22	3847	1087	237	SEG24	1507	1087
148	DUMMY7	5934	425	193	COM21	3795	1087	238	SEG25	1455	1087
149	DUMMY8	5934	477	194	COM20	3743	1087	239	SEG26	1403	1087
150	COM64	5934	529	195	COM19	3691	1087	240	SEG27	1351	1087
151	COM63	5934	581	196	COM18	3639	1087	241	SEG28	1299	1087
152	COM62	5934	633	197	COM17	3587	1087	242	SEG29	1247	1087
153	COM61	5934	685	198	COM16	3535	1087	243	SEG30	1195	1087
154	COM60	5934	767	199	COM15	3483	1087	244	SEG31	1143	1087
155	COM59	5801	1087	200	COM14	3431	1087	245	SEG32	1091	1087
156	COM58	5719	1087	201	COM13	3379	1087	246	SEG33	1039	1087
157	COM57	5667	1087	202	COM12	3327	1087	247	SEG34	987	1087
158	COM56	5615	1087	203	COM11	3275	1087	248	SEG35	935	1087
159	COM55	5563	1087	204	COM10	3223	1087	249	SEG36	883	1087
160	COM54	5511	1087	205	COM9	3171	1087	250	SEG37	831	1087
161	COM53	5459	1087	206	COM8	3119	1087	251	SEG38	779	1087
162	COM52	5407	1087	207	COM7	3067	1087	252	SEG39	727	1087
163	COM51	5355	1087	208	COM6	3015	1087	253	SEG40	675	1087
164	COM50	5303	1087	209	COM5	2963	1087	254	SEG41	623	1087
165	COM49	5251	1087	210	COM4	2911	1087	255	SEG42	571	1087
166	COM48	5199	1087	211	COM3	2859	1087	256	SEG43	519	1087
167	COM47	5147	1087	212	COM2	2807	1087	257	SEG44	467	1087
168	COM46	5095	1087	213	COM1	2755	1087	258	SEG45	415	1087
169	COM45	5043	1087	214	SEG1	2703	1087	259	SEG46	363	1087
170	COM44	4991	1087	215	SEG2	2651	1087	260	SEG47	311	1087
171	COM43	4939	1087	216	SEG3	2599	1087	261	SEG48	259	1087
172	COM42	4887	1087	217	SEG4	2547	1087	262	SEG49	207	1087
173	COM41	4835	1087	218	SEG5	2495	1087	263	SEG50	155	1087
174	COM40	4783	1087	219	SEG6	2443	1087	264	SEG51	103	1087
175	COM39	4731	1087	220	SEG7	2391	1087	265	SEG52	51	1087
176	COM38	4679	1087	221	SEG8	2339	1087	266	SEG53	-1	1087
177	COM37	4627	1087	222	SEG9	2287	1087	267	SEG54	-53	1087
178	COM36	4575	1087	223	SEG10	2235	1087	268	SEG55	-105	1087
179	COM35	4523	1087	224	SEG11	2183	1087	269	SEG56	-157	1087
180	COM34	4471	1087	225	SEG12	2131	1087	270	SEG57	-209	1087

## Pad Coordinates (3)

[Unit:  $\mu\text{m}$ ]

No.	NAME	X-Point	Y-Point	No.	NAME	X-Point	Y-Point	No.	NAME	X-Point	Y-Point
271	SEG58	-261	1087	317	SEG104	-2653	1087	363	COM86	-5045	1087
272	SEG59	-313	1087	318	SEG105	-2705	1087	364	COM87	-5097	1087
273	SEG60	-365	1087	319	SEG106	-2757	1087	365	COM88	-5149	1087
274	SEG61	-417	1087	320	SEG107	-2809	1087	366	COM89	-5201	1087
275	SEG62	-469	1087	321	SEG108	-2861	1087	367	COM90	-5253	1087
276	SEG63	-521	1087	322	SEG109	-2913	1087	368	COM91	-5305	1087
277	SEG64	-573	1087	323	SEG110	-2965	1087	369	COM92	-5357	1087
278	SEG65	-625	1087	324	SEG111	-3017	1087	370	COM93	-5409	1087
279	SEG66	-677	1087	325	SEG112	-3069	1087	371	COM94	-5461	1087
280	SEG67	-729	1087	326	SEG113	-3121	1087	372	COM95	-5513	1087
281	SEG68	-781	1087	327	SEG114	-3173	1087	373	COM96	-5565	1087
282	SEG69	-833	1087	328	SEG115	-3225	1087	374	COM97	-5617	1087
283	SEG70	-885	1087	329	SEG116	-3277	1087	375	COM98	-5669	1087
284	SEG71	-937	1087	330	SEG117	-3329	1087	376	COM99	-5721	1087
285	SEG72	-989	1087	331	SEG118	-3381	1087	377	COM100	-5803	1087
286	SEG73	-1041	1087	332	SEG119	-3433	1087	378	COM101	-5934	767
287	SEG74	-1093	1087	333	SEG120	-3485	1087	379	COM102	-5934	685
288	SEG75	-1145	1087	334	SEG121	-3537	1087	380	COM103	-5934	633
289	SEG76	-1197	1087	335	SEG122	-3589	1087	381	COM104	-5934	581
290	SEG77	-1249	1087	336	SEG123	-3641	1087	382	COM105	-5934	529
291	SEG78	-1301	1087	337	SEG124	-3693	1087	383	COM106	-5934	477
292	SEG79	-1353	1087	338	SEG125	-3745	1087	384	COM107	-5934	425
293	SEG80	-1405	1087	339	SEG126	-3797	1087	385	COM108	-5934	373
294	SEG81	-1457	1087	340	SEG127	-3849	1087	386	COM109	-5934	321
295	SEG82	-1509	1087	341	SEG128	-3901	1087	387	COM110	-5934	269
296	SEG83	-1561	1087	342	COM65	-3953	1087	388	COM111	-5934	217
297	SEG84	-1613	1087	343	COM66	-4005	1087	389	COM112	-5934	165
298	SEG85	-1665	1087	344	COM67	-4057	1087	390	COM113	-5934	113
299	SEG86	-1717	1087	345	COM68	-4109	1087	391	COM114	-5934	61
300	SEG87	-1769	1087	346	COM69	-4161	1087	392	COM115	-5934	9
301	SEG88	-1821	1087	347	COM70	-4213	1087	393	COM116	-5934	-43
302	SEG89	-1873	1087	348	COM71	-4265	1087	394	COM117	-5934	-95
303	SEG90	-1925	1087	349	COM72	-4317	1087	395	COM118	-5934	-147
304	SEG91	-1977	1087	350	COM73	-4369	1087	396	COM119	-5934	-199
305	SEG92	-2029	1087	351	COM74	-4421	1087	397	COM120	-5934	-251
306	SEG93	-2081	1087	352	COM75	-4473	1087	398	COM121	-5934	-303
307	SEG94	-2133	1087	353	COM76	-4525	1087	399	COM122	-5934	-355
308	SEG95	-2185	1087	354	COM77	-4577	1087	400	COM123	-5934	-407
309	SEG96	-2237	1087	355	COM78	-4629	1087	401	COM124	-5934	-459
310	SEG97	-2289	1087	356	COM79	-4681	1087	402	COM125	-5934	-511
311	SEG98	-2341	1087	357	COM80	-4733	1087	403	COM126	-5934	-563
312	SEG99	-2393	1087	358	COM81	-4785	1087	404	COM127	-5934	-615
313	SEG100	-2445	1087	359	COM82	-4837	1087	405	COM128	-5934	-667
314	SEG101	-2497	1087	360	COM83	-4889	1087	406	DUMMY9	-5934	-719
315	SEG102	-2549	1087	361	COM84	-4941	1087	407	COMS1	-5934	-801
316	SEG103	-2601	1087	362	COM85	-4993	1087				

## Pin Functions

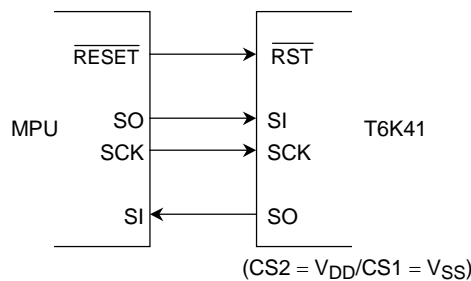
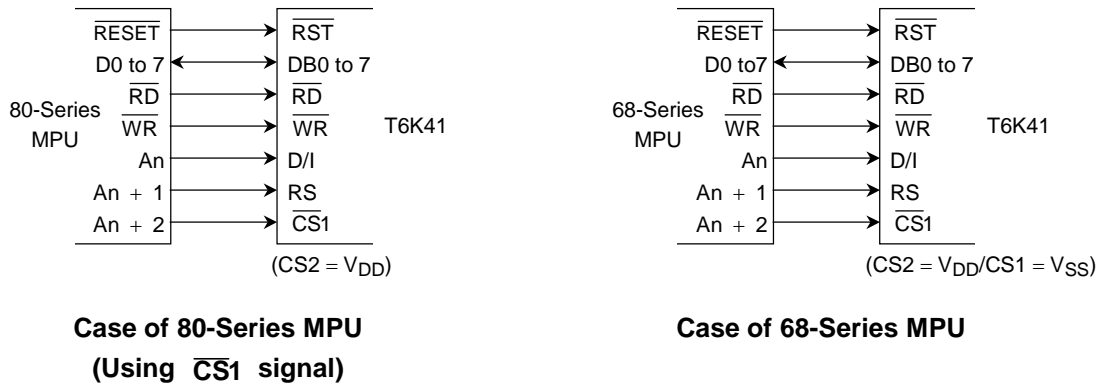
Pin Name	I/O	Functions
SEG1 to SEG128	Output	LCD drive segment signals
COM1 to COM128	Output	LCD drive common signals
S1 to S16	Output	LCD driver segment signals for static icons
COMS	Output	LCD driver common signals for static icons
DB0 to DB7	I/O	Data bus
$\overline{\text{CS1}}$	Input	Chip Select Signal 1 Write data: Data on DB0 to DB7 is latched on the rising edge of $\overline{\text{CS1}}$ . Read data: Data appears on DB0 to DB7 while $\overline{\text{CS1}}$ is Low.
CS2	Input	Chip Select Signal 2 Write data: Data on DB0 to DB7 is latched on the falling edge of CS2. Read data: Data appears on DB0 to DB7 while $\overline{\text{CS1}}$ is High.
D/I	Input	Input for data/instruction select signal <ul style="list-style-type: none"> <li>D/I = High → Indicates that the data on DB0 to DB7 or SI is display data.</li> <li>D/I = Low → Indicates that the data on DB0 to DB7 or SI is an instruction.</li> </ul>
$\overline{\text{WR}}$ (R/W)	Input	Input or Write Select signal (Input for Read/Write Select signal) <ul style="list-style-type: none"> <li>If 80 Series MPU is selected, data on DB0 to DB7 is latched on the rising edge of <math>\overline{\text{WR}}</math></li> <li>If 68 Series MPU is selected, data read is selected if R/W = High and data write is selected if R/W = Low.</li> </ul>
$\overline{\text{RD}}$ (E)	Input	Input for Read Select signal (Input for Enable signal) <ul style="list-style-type: none"> <li>If 80 Series MPU is selected, data appears on DB0 to DB7 while <math>\overline{\text{RD}}</math> = Low.</li> <li>If 68 Series MPU is selected, this pin is used for the Input Enable signal.</li> </ul>
RS	Input	Input for Register Mode Select signal <ul style="list-style-type: none"> <li>If RS = Low, this input is recognized as a register number.</li> <li>If RS = High, this input is recognized as the data to be written to the register.</li> </ul>
P/S	Input	Input for parallel/serial interface select signal <ul style="list-style-type: none"> <li>P/S = High → Parallel interface is selected. SI and SCK must be connected to <math>V_{DD}</math> or <math>V_{SS}</math>.</li> <li>P/S = Low → Serial interface is selected. DB0 to DB7 must be open. <math>\overline{\text{WR}}</math> and <math>\overline{\text{RD}}</math> must be connected to <math>V_{SS}</math>.</li> </ul>
68/80	Input	Input for 68/80 Series Parallel MPU Select signal <ul style="list-style-type: none"> <li>68/80 = High → 68 Series parallel MPU is selected.</li> <li>68/80 = Low → 80 Series parallel MPU is selected.</li> </ul>
SO	Output	Output for serial data
SI	Input	Input for serial data
SCK	Input	Input for serial clock
$\overline{\text{RST}}$	Input	Input for Reset signal <ul style="list-style-type: none"> <li><math>\overline{\text{RST}}</math> = Low → Reset state</li> </ul>
$\overline{\text{STB}}$	Input	Input for Standby signal Usually connected to $V_{DD}$ . <ul style="list-style-type: none"> <li><math>\overline{\text{STB}}</math> = Low → T6K41 is in Standby state. Column drive signals and row drive signals are at the <math>V_{SS}</math> level and the on-chip oscillator is stopped.</li> <li>In standby state T6K41 can be accessed by the MPU.</li> </ul>
OSC1	Input	Input for CR oscillator When using an external clock, input the clock to OSC1 and leave OSC2 and OSC3 open.

Pin Name	I/O	Functions
OSC2, OSC3	Output	Output for CR oscillator When using the internal clock oscillator, connect a resistor between OSC1 and OSC2 or between OSC1 and OSC3. OSC1 and OSC2: Oscillator for Normal Display Mode OSC1 and OSC3: Oscillator for Partial Display Mode
V <sub>IN</sub>	—	Power supply for DC-DC converter Usually connected to V <sub>DD</sub> The condition $V_{DD} \leq V_{IN}$ must always be met.
C1A, C1B	—	External capacitor-connecting pin for ×2 DC-DC converter
C2A, C2B	—	External capacitor-connecting pin for ×3 DC-DC converter
C3A, C3B	—	External capacitor-connecting pin for ×4 DC-DC converter
C4A, C4B	—	External capacitor-connecting pin for ×5 DC-DC converter
C5A, C5B	—	External capacitor-connecting pin for ×6 DC-DC converter
V <sub>OUT</sub>	—	DC-DC converter output pin
VREF	—	LV regulator output pin
V <sub>CC</sub>	—	LCD driver power supply pin
VLC0 to VLC5	—	LCD drive power supply pin
V <sub>DD</sub> , V <sub>SS</sub>	—	Logic circuit power supply pin
M/S	Input	Input for Master/Save Select signal <ul style="list-style-type: none"> <li>• M/S = High → T6K41 is a master chip.</li> <li>• M/S = Low → T6K41 is a slave chip.</li> </ul>
CL	I/O	Input/Output for Shift Clock pulse <ul style="list-style-type: none"> <li>• Master Mode (M/S = High) → Output</li> <li>• Slave Mode (M/S = Low) → Input</li> </ul>
PM	I/O	Input/Output for Frame signal <ul style="list-style-type: none"> <li>• Master Mode (M/S = High) → Output</li> <li>• Slave Mode (M/S = Low) → Input</li> </ul>
FR	I/O	Input/Output for display alternating signal <ul style="list-style-type: none"> <li>• Master Mode (M/S = High) → Output</li> <li>• Slave Mode (M/S = Low) → Input</li> </ul>
CK	I/O	Input/Output for system clock signal <ul style="list-style-type: none"> <li>• Master Mode (M/S = High) → Output</li> <li>• Slave Mode (M/S = Low) → Input</li> </ul>
SYNC	I/O	Input/Output for gray-scale data synchronous signal <ul style="list-style-type: none"> <li>• Master Mode (M/S = High) → Output</li> <li>• Slave Mode (M/S = Low) → Input</li> </ul>
BLNK	I/O	Input/Output for static icons blinking synchronous signal <ul style="list-style-type: none"> <li>• Master Mode (M/S = High) → Output</li> <li>• Slave Mode (M/S = Low) → Input</li> </ul>

**Function Each Block**

**MPU interface unit**

The T6K41 can be operated with an 80-Series MPU, 68-Series MPU or a serial interface.  
Figure 1 shows an example of interface.



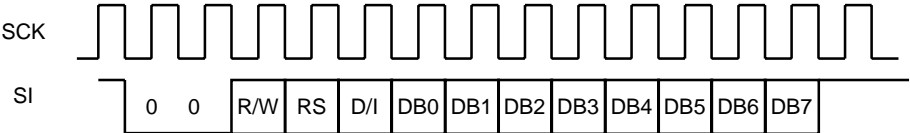
**Figure 1**

The T6K41 selects an 8-bit parallel or serial interface, allowing for data to transferred from the MPU.

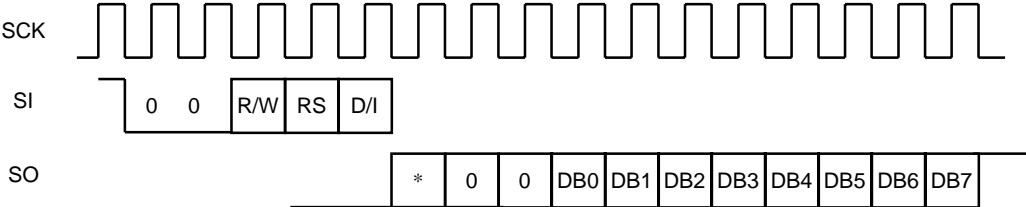
P/S	68/80	Interface Type	$\overline{CS1}$	CS2	D/I	RS	$\overline{WR}$	$\overline{RD}$	SO	SI	SCK	DB0 to 7
H	L	80-Series MPU (CS1)	An + 2	H	An	An + 1	$\overline{WR}$	$\overline{RD}$	Open	L/H	L/H	DB0 to 7
		80-Series MPU (CS2)	L	An + 2	An	An + 1	$\overline{WR}$	$\overline{RD}$	Open	L/H	L/H	DB0 to 7
	H	68-Series MPU	L	H	An	An + 1	R/W	E	Open	L/H	L/H	DB0 to 7
L	L	Serial	L	H	L/H	L/H	L/H	L/H	SO	SI	SCK	Open

Note 5: H denotes the  $V_{DD}$  level; L denotes the  $V_{SS}$  level.

<WRITE>



<READ>



\*: Dummy Data

Figure 2

### **Register select circuit**

This circuit transfers a register chosen by command to the data. T6K41 has R0 to R31 registers. The R23 to R31 registers are provided for test. Do not choose these registers.

### **Input register**

This register stores 8-bit data from the MPU. The D/I signal discriminate between command data and display data.

### **X-address counter**

The X-address counter is a 128-Up/Down counter. It holds the row address of the display RAM. When this counter is selected by a command, it is automatically incremented or decremented each time data is read or written to the display RAM.

### **Y (page) -address counter**

The Y (page) -address counter is a 32-Up/Down counter. It holds the column address of the display RAM. When this counter is selected by a command, it is automatically incremented or decremented each time data is read or written to the display RAM.

### **Z-address counter**

The Z-address counter is a 128-Up counter used to supply the display data stored in the display RAM to the LCD drive circuit. This counter is incremented by CL signal. The data held in the Z-address register is loaded into this counter as Z-address. For instance, when Z start address is 16, the counter increment like this: 16, 17, ,18..., 127, 128, 1, 2..., 14,15,16. Therefore, the display start line is 16-line of the display RAM.

### **X/Y counter up/down register**

This register holds the data that selects the up-count or down-count mode for the X and Y counters.

### **X/Y counter select register**

The register holds the data that selects the X or Y counter to be used.

### **Display ON/OFF register**

This register holds the data that determines whether the display be turned ON or OFF. When turned OFF, the output data turns to default level. When turned ON, the display data appears according to the display RAM data. The display ON or OFF state does not affect the data of display RAM.

### **Duty cycle control register**

This register holds the data that sets one of the four duty cycles that can be used.

### **FRS control register**

This register holds FRS control data.

### **Contrast control register**

This register holds contrast control data.

### **Oscillator control register**

This register holds the data that controls oscillator.

### **Static icon control register**

This register holds the data that controls static icons. The static icons are usually independent of the LCD drive circuit for a normal display, and holds contrast control data, display ON/OFF data, and blink control data.

**Analog circuit ON/OFF register**

This register holds the data that determines whether the internal analog circuit be turned ON or OFF.

**Z-address register**

This register holds the data that determines the display start line. By setting Z-address in this register successively, it is possible to scroll the display up or down.

**Shift register**

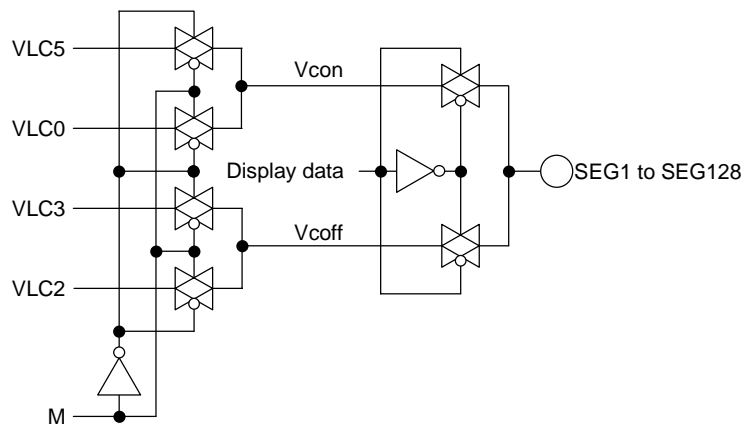
T6K41 has two 64-bit shift registers necessary to shift the turn-on data required for the LCD drive common signals.

**Latch circuit**

The circuit latches the data from the display RAM.

**LCD drive circuit (segment)**

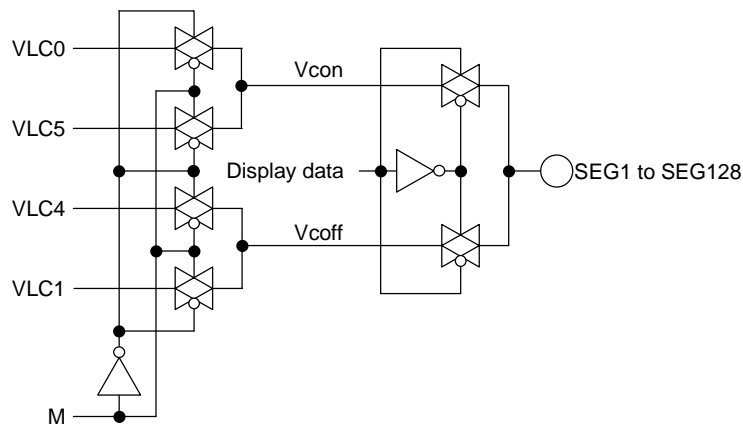
The segment driver circuit consists of 128 driver circuits. One of the four LCD driving level is selected by the combination of M (internal signal) and the display data transferred from the latch circuit. Details of segment driver circuit are shown in Figure 3.



**Figure 3**

**LCD driver circuit (common)**

The common driver circuit consists of 128 driver circuits. One of the four LCD driving level is selected by the combination of M (internal signal) and the data from the shift register. Details of common driver circuit are shown in Figure 4.



**Figure 4**

**FRC (Frame Rate Control) circuit**

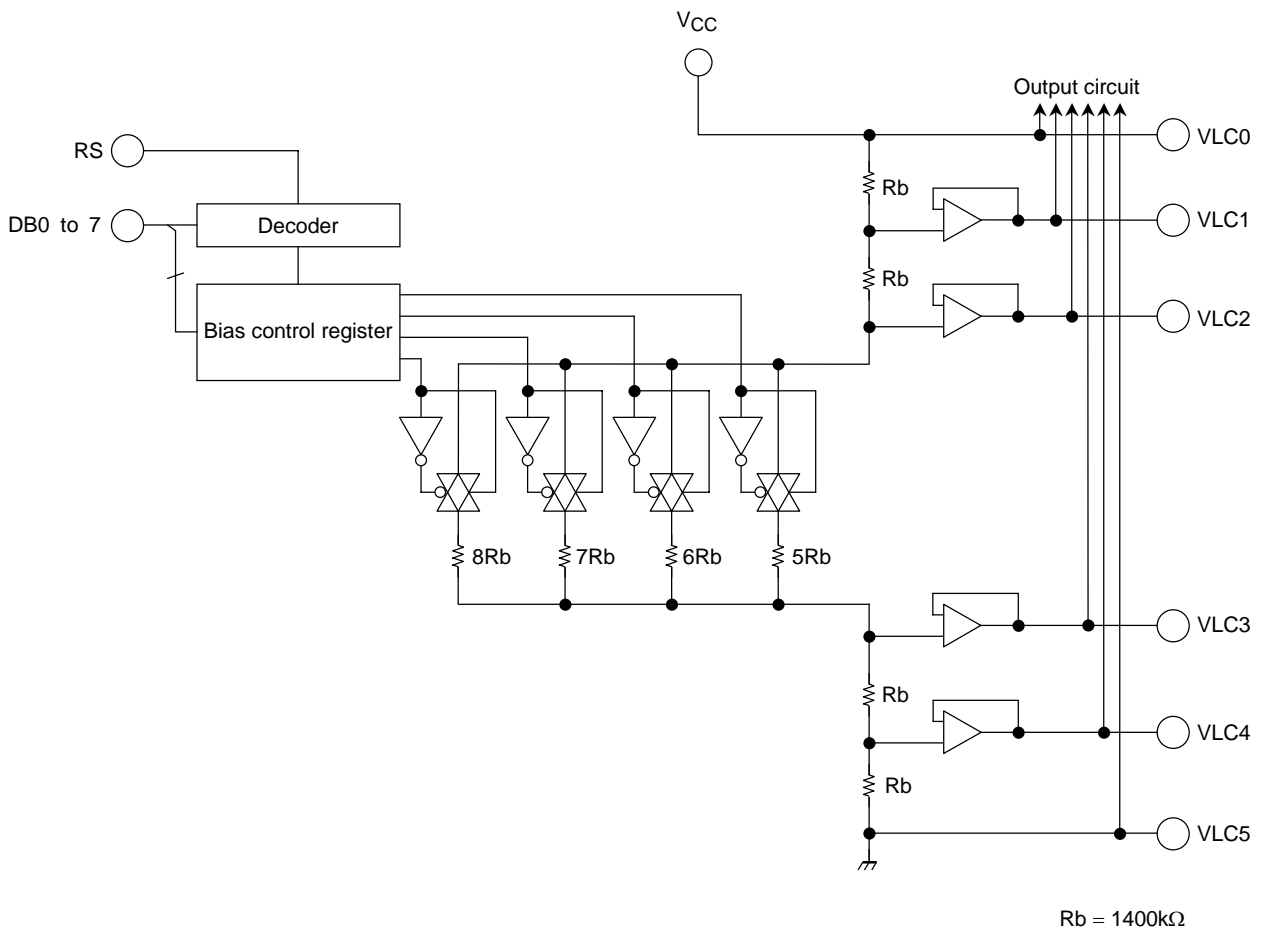
The circuit controls ON/OFF of PWM data in each frame for generating the gray scale level. PWM (Pulse Width Modulation) is performed by gray scale data (the 2-bit display RAM data correspond to gray scale data). The gray scale data also determines whether PWM data is assigned to which frame.

**Timing generation circuit**

The circuit divides the signals from the oscillator and generates display timing signals and operating clock.

**Op-Amp, Bias control circuit and Voltage divider resistors**

The T6K41 has five op-amp for supplying LCD driving levels. To maintain good LCD contrast, connect a capacitor between the op-amp output and VSS. The value of the capacitor should normally be 0.1  $\mu$ F. One of four biases can be selected by a bias control command.

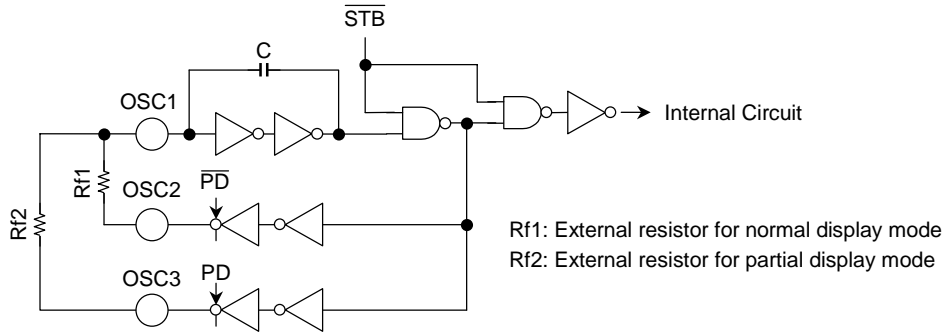


**Figure 5**

**Oscillator**

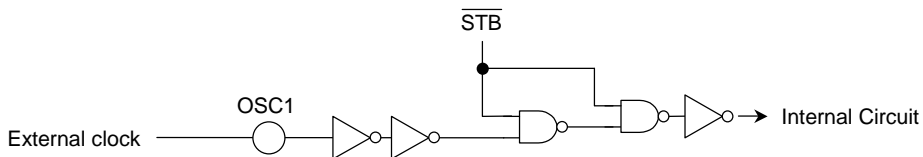
The T6K41 has two oscillators for normal display mode and partial display mode. When using internal oscillators, connect an external resistor for normal display mode between OCS1 and OSC2 and connect an external resistor for partial display mode between OSC1 and OSC3. When using external clock, input the clock to OSC1 after setting up Oscillation control resistor data, as shown in Figure 7.

<CR oscillator>



**Figure 6**

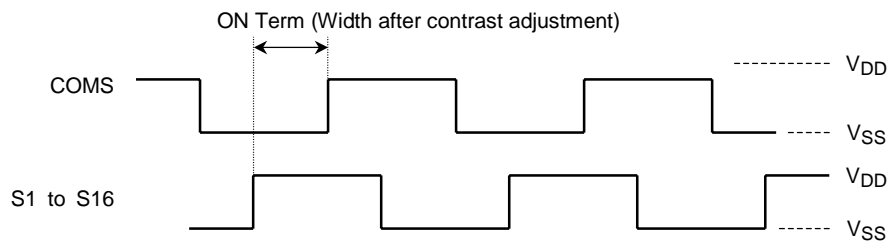
<External clock supply>



**Figure 7**

**Static icon driver circuit**

T6K41 has 16 static icons. Since this circuit is driven on logic system voltage (VDD), the terminal of S1 to S16 and COMS outputs the LCD drive waveform of the level between VDD to VSS. The static icon is driven by 1/2duty and contrast adjustment is performed by changing the phase of an output waveform, as shown in Figure 8. The ON period ratio of the drive voltage for the static icon is adjusted by changing the phase of the waveform between the COMS pin and S1 to S16 pins.



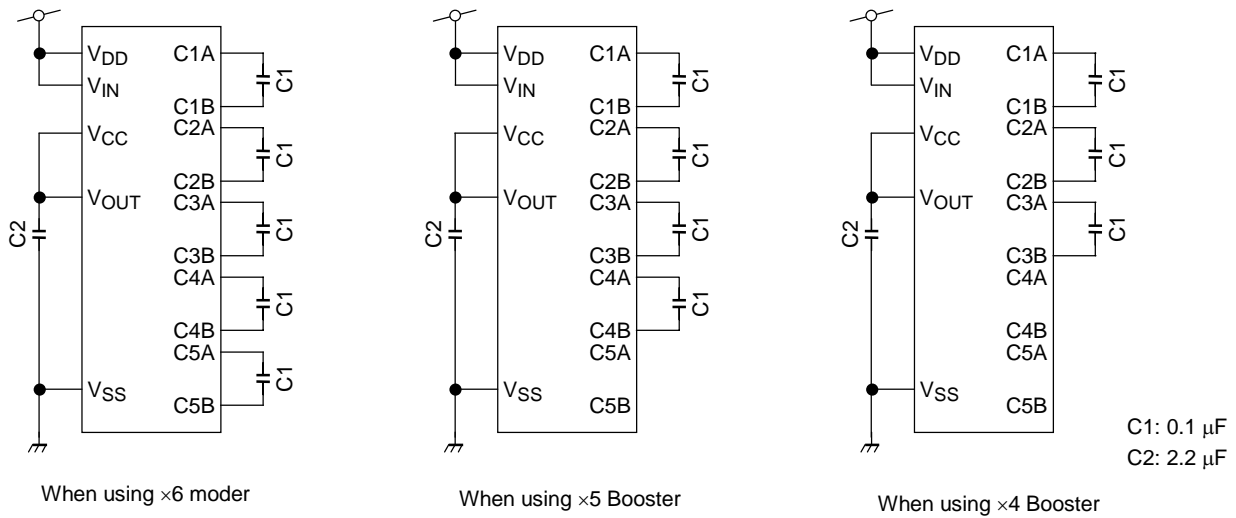
**Figure 8**

**DC-DC converter**

T6K41 contains a  $\times 4/5/6$  DC-DC converter. This circuit boosts by an external capacitor (charge pump system). By supplying voltage to  $V_{IN}$ , this circuit can generate the boosted voltage selected by the command, and outputs the voltage from  $V_{OUT}$ . The boosted voltage is fed back to DC-DC converter circuit and the voltage adjusted by contrast control circuit is again outputted from  $V_{OUT}$ .

When using a DC-DC converter, short  $V_{OUT}$  and  $V_{CC}$ . As for the output voltage of  $V_{OUT}$ , 15.4 V or 13.0 V is the maximum value after a contrast setup. Since more than 15.4 V or more than 13.0 V is not outputted, please be careful. In partial display mode, the DC-DC converter automatically changes to  $\times 2$  or  $\times 3$  mode. The output voltage of  $V_{OUT}$  is  $V_{IN}$  level in a standby state ( $/STB = "L"$ ) or a reset state ( $/RST = "L"$ ).

Refer to Figure 9 for the capacitor connection.



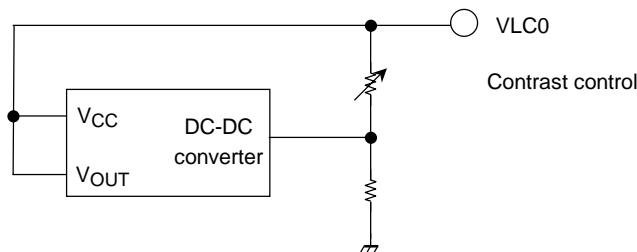
Note 6: Please set the capacitor value of C1 and C2 as the following ratio to suit the circuit characteristic.

C1:C2 = 1:More than 20

**Figure 9**

**Contrast control circuit**

The contrast control circuit feeds back the voltage outputted from  $V_{OUT}$  through built-in variable resistance, and outputs again contrast adjustment voltage to  $V_{OUT}$ . Therefore, the output voltage of  $V_{OUT}$  is the maximum of LCD drive voltage adjusted by contrast control circuit.



**Figure 10**

## Command Definition

Command	Reg. No.	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Set register	—	0	0	0	1	0	0	0	Register (0 to 31)				
Status read	—	0	0	1	0	*	*	PD	N/F	SI	DP	Y/X	U/D
Counter mode	R0	0	1	0	1	0	0	0	0	0	0	Y/X	U/D
Display mode	R1	0	1	0	1	0	CDR	SDR	0	PD	SI	N/F	DP
Set power control	R2	0	1	0	1	×6/×5/×4		×3/×2	0	0	Hi/Lo	OP	DC
Set duty/bias	R3	0	1	0	1	0	0	BIAS		0	0	DUTY	
Oscillator control	R4	0	1	0	1	0	0	0	0	0	0	EXT	OSC
Set X/Y-address	R5	0	1	0	1	1	X-address (0 to 127)						
		0	1	0	1	0	0	0	Y-address (0 to 31)				
Set Z-address	R6	0	1	0	1	0	Z-address (0 to 127)						
Set normal display contrast	R7	0	1	0	1	Contrast control for normal display (0 to 255)							
Set static icon contrast	R8	0	1	0	1	0	0	Contrast control for static icon display (0 to 63)					
Set static icon register (1)	R9	0	1	0	1	S4 state		S3 state		S2 state		S1 state	
Set static icon register (2)	R10	0	1	0	1	S8 state		S7 state		S6 state		S5 state	
Set static icon register (3)	R11	0	1	0	1	S12 state		S11 state		S10 state		S9 state	
Set static icon register (4)	R12	0	1	0	1	S16 state		S15 state		S14 state		S13 state	
Set partial display mode	R13	0	1	0	1	BIAS		Partial area size		Partial start area (0 to 15)			
Set alternating period	R14	0	1	0	1	0	0	0	0	0	FRS Control (0 to 7)		
Gray scale pallet for normal display	R15	0	1	0	1	Gray scale data for normal display (1)							
	R16	0	1	0	1	GS data to RAM data "00"							
	R17	0	1	0	1	Gray scale data for normal display (2)							
	R18	0	1	0	1	GS data to RAM data "01"							
	R19	0	1	0	1	Gray scale data for normal display (3)							
	R20	0	1	0	1	GS data to RAM data "10"							
	R21	0	1	0	1	Gray scale data for normal display (4)							
R22	0	1	0	1	GS data to RAM data "11"								
Test mode	R23 to R31	0	1	0	1	Test mode (Do not access these registers.)							
Data write	—	1	1	0	1	Write data							
Data read	—	1	1	1	0	Read data							

- Set register  
T6K41 has registers for command (R0 to R31). But, R23 to R31 registers are provided for LSI test. Do not access these registers. If you access these registers inadvertently, you must be execute a re-setup of a register after executing reset function of T6K41.

- R0: Counter mode

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	0	0	0	0	0	0	Y/X	U/D

Y/X: Selects Y-Counter or X-Counter.

Y/X = 1: Y-Counter is selected.

Y/X = 0: X-Counter is selected.

U/D: Selects Up mode or Down mode.

U/D = 1: Up mode is selected.

U/D = 0: Down mode is selected.

- R1: Display mode

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	0	CDR	SDR	0	PD	SI	N/F	DP

CDR: Sets the common data scanning direction.

CDR = 1: Data is scanned in the direction COM1 → COM128.

CDR = 0: Data is scanned in the direction COM128 → COM1.

SDR: Sets the segment data direction.

SDR = 1: SEG1 → SEG4 with respect to the data direction DB7 → DB0.

SDR = 0: SEG1 → SEG4 with respect to the data direction DB0 → DB7.

Note 7: For details, see Figure 11 on Function Description.

PD: Turns partial display ON or OFF.

DP = 1: Partial display is turned ON

DP = 0: Partial display is turned OFF. (Normal display)

SI: Turns static icons ON or OFF.

SI = 1: Static icons are turned ON.

SI = 0: Static icons are turned OFF.

N/F: Selects between normal display and icon display modes.

N/F = 1: Normal display mode is selected.

N/F = 0: Icon display mode is selected.

## Display mode

Display Mode	Normal Display	Static Icons
Normal display mode	valid	valid
Power save mode	invalid	valid

Note 8: When power save mode (icon display mode) is selected, only static icon can be displayed.

DP: Turns display ON or OFF.

DP = 1: Display is turned ON.

DP = 0: Display is turned OFF.

- R2: Set power control

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	
Code	0	1	0	1	×6/×5/×4		×3/×2		0	0	Hi/Lo	OP	DC

×6/×5/×4: Selects booster level in Normal Display mode

DB7	DB6	Booster
1	0	×6
0	1	×5
0	0	×4

×3/×2: Selects booster level in Partial Display mode.

×3/×2 = 1: ×3 booster

×3/×2 = 0: doubler

Hi/Lo: Selects LCD drive voltage (V<sub>OUT</sub>).

Hi/Lo = 1: V<sub>OUT</sub> = 15.4 V (typ.)

Hi/Lo = 0: V<sub>OUT</sub> = 13.0 V (typ.)

OP: Controls op-amp for driving LCD.

OP = 1: Op-amp for driving LCD ON

OP = 0: Op-amp for driving LCD OFF

(Externally supply V<sub>CC</sub> and VLC1 to VLC4 via op-amp.)

DC: Controls booster (DC-DC converter).

DC = 1: Booster ON

DC = 0: Booster OFF

- R3: Set Duty/Bias

Sets duty/bias in Normal Display mode.

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	0	0	BIAS (0 to 3)		0	0	DUTY (0 to 3)	

BIAS: Sets a power supply bias for LCD drive.

DB5	DB4	
1	1	Set to 1/12 bias.
1	0	Set to 1/11 bias.
0	1	Set to 1/10 bias.
0	0	Set to 1/9 bias.

DUTY : Sets a display duty cycle.

DB1	DB0	
1	1	Set to 1/128 duty
1	0	Set to 1/100 duty
0	1	Set to 1/80 duty
0	0	Set to 1/72 duty

• R4: Oscillation control

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	0	0	0	0	0	0	EXT	OSC

EXT: Switches input.

EXT = 1: Inputs external clock.

EXT = 0: Uses internal oscillator.

OSC: Controls internal oscillator.

OSC = 1: Internal oscillator ON

OSC = 0: Internal oscillator OFF

Switching between Normal Display and Partial Display modes switches oscillator resistor when an internal oscillator is used (EXT = 0).

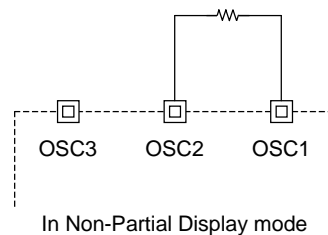
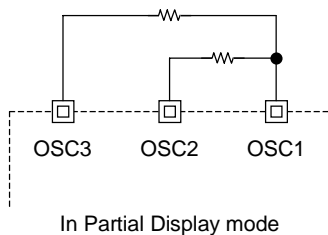
Normal Display mode: resistor between OSC1 and OSC2

Partial Display mode: resistor between OSC1 and OSC3

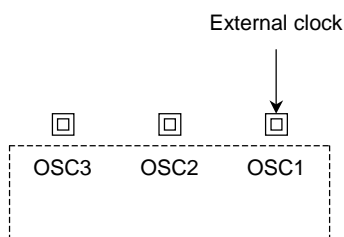
Divides the frequency from the selected oscillator to obtain the static icon clock.

To switch between Normal Display and Partial Display modes using external clock input, the clock frequency must be changed according to the display mode.

**<Example when internal oscillator is used>**



**<External clock input>**



**Recommended frequency**  
( $V_{DD} = 3.0\text{ V}$ ,  $FR = 70\text{ Hz}$ ,  $T_a = 25^\circ\text{C}$ )

Display Mode	Duty	Frequency (typ.)
Normal display	1/128	Fosc2 = 80.64 kHz
	1/100	Fosc2 = 63.0 kHz
	1/80	Fosc2 = 50.4 kHz
	1/72	Fosc2 = 45.36 kHz
Partial display mode	1/32	Fosc3 = 20.16 kHz
	1/24	Fosc3 = 15.12 kHz
	1/16	Fosc3 = 10.08 kHz
	1/8	Fosc3 = 5.04 kHz

- R5: Set X/Y-address

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	1	X-address (0 to 127)						
					0	0	0	Y-address (0 to 31)				

- (1) Set X-address

Setting DB7 to 1 acknowledges an X-address. The address is controlled as a vertical address of the screen image. Using the X-up/down counter automatically enables write and read. The X-up/down counter counts addresses on the specified horizontal line only.

- (2) Set Y-address

Setting DB7 to 0 acknowledges a Y-address. The address is controlled as a horizontal address of the screen image. Using the Y-up/down counter automatically enables write and read. The Y-up/down counter counts addresses on the specified vertical line only.

- R6: Set Z-address

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	0	Z-address (0 to 127)						

Sets the start line of display RAM. Setting this address enables vertical scrolling. For the scroll function, see the detailed description.

- R7: Set normal display contrast

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	Contrast control (0 to 255)							

Sets contrast control of the Normal Display area. When set to 0, contrast is the minimum. When set to 255, contrast is the maximum.

Note 9: that if a doubler is selected in Partial Display mode, set DB7 = 1 and set a step from 1 to 128.

- R8: Set static icon contrast

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	0	0	Contrast control (0 to 63)					

Sets contrast control of the static icon area. When set to 0, contrast is the minimum. When set to 63, contrast is the maximum. The ON period ratio of the drive voltage for the static icon area is adjusted by changing the phase of the waveform between the COMS pin and pins S1 to S16.

- R9: Set static icon register (1)

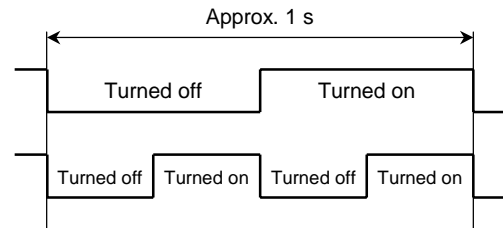
	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	S4 state		S3 state		S2 state		S1 state	

Sets ON/OFF of static icons S1 to S4. When a static icon is ON (R1: SI = 1), S1 to S4 are turned on according to the setting of this register. When a static icon is OFF (R1: SI = 0), the display is off regardless of the setting of this register.

Static icon states vary as shown below according to the 2-bit data.

### S1 to S16 state

0	0	OFF
0	1	ON (Blinks at intervals of about 1 second)
1	0	ON (Blinks at intervals of about 0.5 seconds)
1	1	ON



- R10: Set static icon register (2)

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	S8 state		S7 state		S6 state		S5 state	

Sets ON/OFF of the static icons S5 to S8. When a static icon is ON (R1: SI = 1), S5 to S8 are turned on according to the setting of this register. When a static icon is OFF (R1: SI = 0), the display is off regardless of the setting of this register.

- R11: Set static icon register (3)

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	S12 state		S11 state		S10 state		S9 state	

Sets ON/OFF of the static icon S9 to S12. When a static icon is ON (R1: SI = 1), S9 to S12 are turned on according to the setting of this register. When a static icon is OFF (R1: SI = 0), the display is off regardless of the setting of this register.

- R12: Set static icon register (4)

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	S16 state		S15 state		S14 state		S13 state	

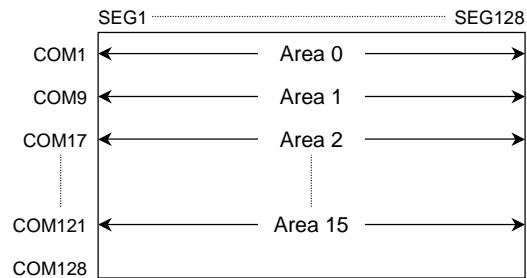
Sets ON/OFF of the static icon S13 to S16. When a static icon is ON (R1: SI = 1), S13 to S16 are turned on according to the setting of this register. When a static icon is OFF (R1: SI = 0), the display is off regardless of the setting of this register.

- R13: Set partial display mode

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	Bias		Partial area size		Partial start area			

### Set partial start area

DB3	DB2	DB1	DB0	Start Area
0	0	0	0	0
0	0	0	1	1
0	0	1	0	2
0	0	1	1	3
0	1	0	0	4
0	1	0	1	5
0	1	1	0	6
0	1	1	1	7
1	0	0	0	8
1	0	0	1	9
1	0	1	0	10
1	0	1	1	11
1	1	0	0	12
1	1	0	1	13
1	1	1	0	14



Sets the partial display start area. The partial display start area can be specified in units of 8 lines (8 COMs).

### Set partial area size

DB5	DB4	Partial Area Size
0	0	8 lines mode
0	1	16 lines mode
1	0	24 lines mode
1	1	32 lines mode

Sets the partial display area size. A partial display area of the set size is displayed from the partial display start area.

### Set bias

DB7	DB6	BIAS
0	0	1/4 bias
0	1	1/5 bias
1	0	1/6 bias
1	1	1/7 bias

Sets bias in Partial Display mode.

- R14: Set alternating period

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	0	0	0	0	0	FRS Control (0 to 7)		

This command sets the number of lines at which intervals the polarity of the frame signal (alternating signal) is switched over.

DB2	DB1	DB0	
1	1	1	FR signal inverts on every 19 lines.
1	1	0	FR signal inverts on every 17 lines.
1	0	1	FR signal inverts on every 13 lines.
1	0	0	FR signal inverts on every 11 lines.
0	1	1	FR signal inverts on every 7 lines.
0	1	0	FR signal inverts on every 5 lines.
0	0	1	FR signal inverts on every 3 lines.
0	0	0	In case 1/n duty is selected by R3, FR signal inverts on every n lines.

- R15 to R22: Gray scale pallet for normal display

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	R15/16: Gray scale data for normal display (1)							
					R17/18: Gray scale data for normal display (2)							
					R19/20: Gray scale data for normal display (3)							
					R21/22: Gray scale data for normal display (4)							

This register stores the data for generating the gray scale level. The gray scale is created by pulse width modulation (PWM) and frame rate control (FRC). Use two registers for each gray scale level. Set the PWM data for the first to fourth frames in these registers. Four bits of PWM data are eliminated from a frame. Four frames are used to display one gray scale level. Frames (1) to (4) above correspond to display data 00, 01, 10 and 11, respectively. Any gray scale level is assigned to the display data values (00, 01, 10 and 11).

### Frame Rate control (FRC) setting

The T6K41 determines the gray scale level by specifying the PWM to be performed in the four frames. The correspondence between frame control order and the registers is shown in the table below.

Register	Data Bus							
	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
R15/R17/R19/R21	Data eliminated from second frame				Data eliminated from first frame			
R16/R18/R20/R22	Data eliminated from fourth frame				Data eliminated from third frame			

Note 10: Eliminated data are PWM data.

## PWM (pulse width modulation) setting

The T6K41 determines the gray scale level by dividing the segment data ON waveform by nine. The data to be written to the register are selected from the gray scale levels listed below.

BIN	HEX	PWM (on width)	Note
0000	00	0 (0/9)	
0001	01	1/9	
0010	02	2/9	
0011	03	3/9	
0100	04	4/9	
0101	05	5/9	
0110	06	6/9	
0111	07	7/9	
1000	08	8/9	
1001	09	1 (9/9)	
1010 to 1111	0A to 0F	0 (0/9)	These data select off level (0 level).

Note 11: Optimization by combination of PWM and FRC data depends on the characteristics of the LCD.

- R23 to R31: Test mode

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	Test mode							

This command selects a test mode, so do not use it. If you've used this test command inadvertently, deassert it by pulling the  $\overline{RST}$  input low

- Data Write

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	1	0	1	Write data							

Writes 8-bit data to display RAM. Using the X/Y counter automatically counts up/down addresses after specifying the start address so that data can be written.

- Data Read

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	1	1	1	0	Read data							

Reads 8-bit data from display RAM. Using the X/Y counter automatically counts up/down addresses after specifying the start address so that data can be read.

- Status read

	D/I	RS	$\overline{WR}$	$\overline{RD}$	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
Code	0	0	1	0	*	*	*	N/F	SI	DP	Y/X	U/D

N/F (DB4): Identifies Normal Display mode or Power Save mode.

N/F = 1: Indicates Normal Display mode.

N/F = 0: Indicates Power Save mode.

SI (DB3): Identifies static icon ON/OFF.

SI = 1: Static icon ON

SI = 0: Static icon OFF

DP (DB2): Identifies display ON/OFF.

DP = 1: Display ON

DP = 0: Display OFF

Y/X (DB1): Identifies Y or X counter.

Y/X = 1: Y counter is selected.

Y/X = 0: X counter is selected.

U/D (DB0): Identifies Counter Up or Down mode.

U/D = 1: Counter Up mode

U/D = 0: Counter Down mode

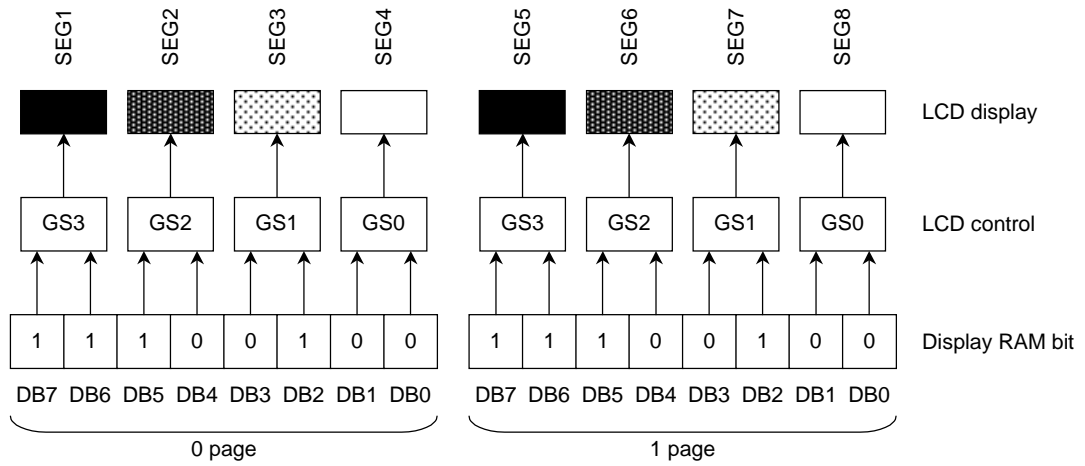
## Reset Function

The T6K41 has a  $\overline{\text{RST}}$  pin. When input to this pin is pulled low, the T6K41 is reset, with its internal circuits (register contents) initialized as shown below.

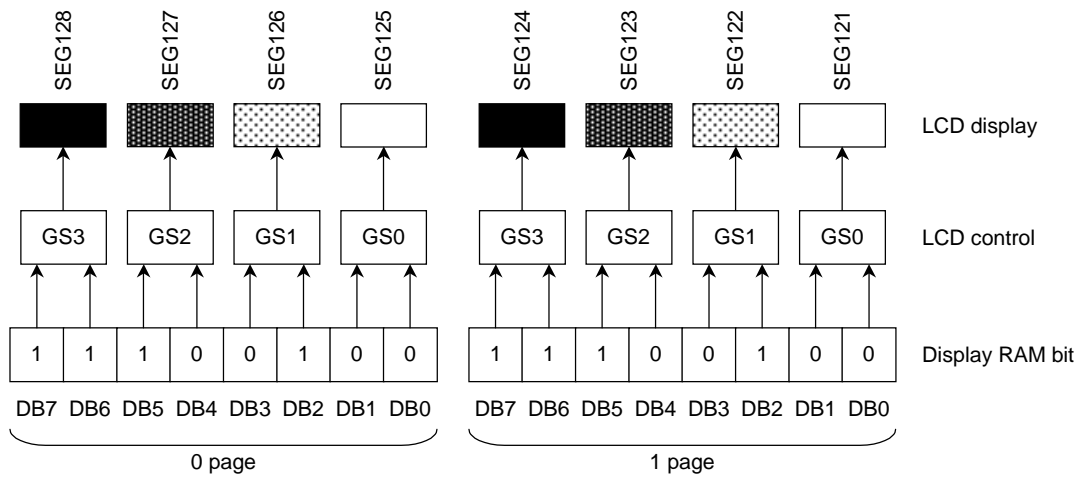
Command	Reg. No.	D7	D6	D5	D4	D3	D2	D1	D0
Counter mode	R0	0	0	0	0	0	0	1	1
		*	*	*	*	*	*	Y/X	U/D
Display mode	R1	0	1	1	0	0	0	1	0
		*	CDR	SDR	*	PD	SI	N/F	DP
Power control	R2	1	0	0	0	0	1	0	0
		×6/×5/×4		×3/×2		*	*	Hi/Lo	OP
Set Duty/Bias	R3	0	0	1	1	0	0	1	1
		*	*	BIAS			*	*	DUTY
Oscillator setting	R4	0	0	0	0	0	0	1	1
		*	*	*	*	*	*	EXT	OSC
Set X/Y-address	R5	0	0	0	0	0	0	0	0
		*	X-address/Y-address						
Set Z-address	R6	0	0	0	0	0	0	0	0
		*	Z-address						
Contrast setting in Normal Display mode	R7	0	0	0	0	0	0	0	0
		Contrast control data for normal display							
Contrast setting for static icon	R8	0	0	0	0	0	0	0	0
		*	*	Contrast control for static icon					
Static icon setting	R9 to R12	0	0	0	0	0	0	0	0
		S1 to S16 states (specify in two bits)							
Partial display setting	R13	0	0	0	0	0	0	0	0
		BIAS			Area size	Display start area			
Alternating current signal setting	R14	0	0	0	0	0	0	0	0
		*	*	*	*	*	Alternating current signal		
Setting of gray scale pallet for normal display	R15 to R22	0	0	0	0	0	0	0	0
		Gray scale data for normal display							

**Function Description**

- Display data bit
  - (1) When SDR = 1



- (2) When SDR = 0



**Figure 11**

- The relationship between the Duty and the LCD drive common signal output  
T6K41 can change Duty by command setup. When CDR = 1, assignment of LCD drive common signal output (COM) pins are as shown below.

Duty	Assignment of COM pins	Number of using pins
1/128 duty	COM1...COM128	128
1/100 duty	COM1 ... COM50, COM65 ... COM114	100
1/80 duty	COM1 ... COM40, COM65 ... COM104	80
1/72 duty	COM1 ... COM36, COM65 ... COM100	72

- Partial Display function  
The T6K41 has the partial display function for displaying arbitrary area by command setup. The partial display area size can be selected from 8 lines, 16 lines, 24 lines, or 32 lines. The partial start area (start line) can be selected from the following table.

R13	Partial Start Area No	Display Start Line	R13	Partial Start Area	Display Start Line
x0H	0	COM1	x8H	8	COM65
x1H	1	COM9	x9H	9	COM73
x2H	2	COM17	xAH	10	COM81
x3H	3	COM25	xBH	11	COM89
x4H	4	COM33	xCH	12	COM97
x5H	5	COM41	xDH	13	COM105
x6H	6	COM49	xEH	14	COM113
x7H	7	COM57	xFH	15	COM121

Note 12: x: Invalid

Z address determines the effective display RAM area. For instance, when the partial display area size is set to 16 lines and the partial start area no. is set to 0, the data of effective display RAM area shown below by Z-address setup is displayed on 16 lines from COM1.

When Z-address (ZAD) is set to 0, the range of XAD = 0 to XAD = 15 are effective

When Z-address (ZAD) is set to 30, the range of XAD = 30 to XAD = 46 are effective.

- Expansion function

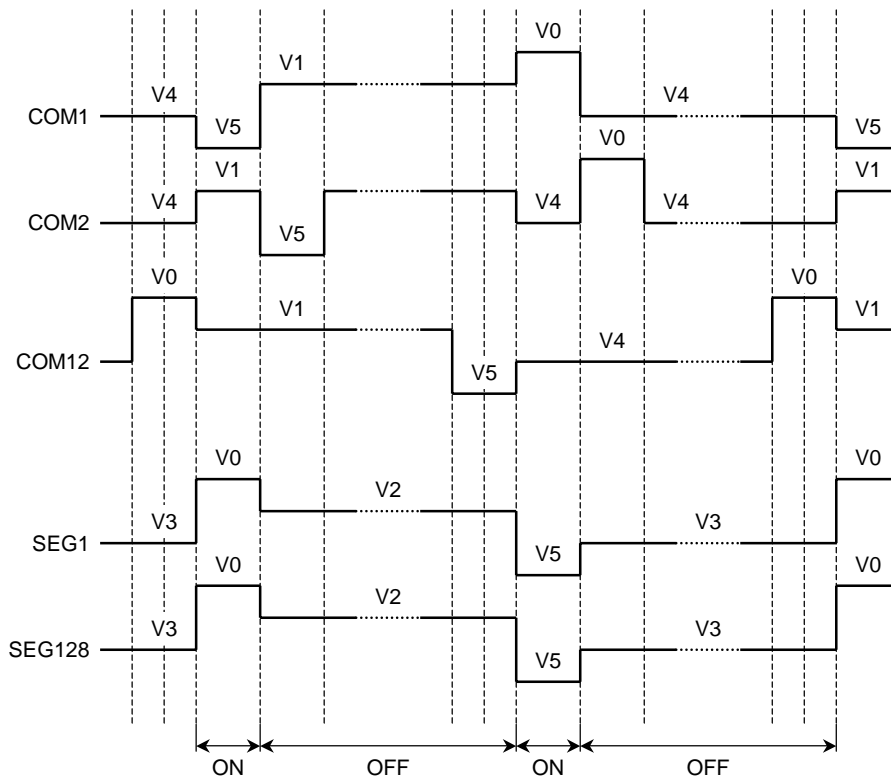
The T6K41's expansion function, allows two, T6K41s to drive an LCD panel of up to 256 by 128 dots. The table below shows the timing signals state by using M/S pin.

M/S	Timing signal output/input for Expansion					
	CL	PM	FR	CK	SYNC	BLNK
H	Output	Output	Output	Output	Output	Output
L	Input	Input	Input	Input	Input	Input

The table below shows the selectable function by using M/S pin.

M/S	
H	L
<ul style="list-style-type: none"> <li>Single-chip mode Disable expansion mode</li> <li>Two-chip mode (Master chip) Timing signals and power voltage supply to Slave chip.</li> </ul>	<ul style="list-style-type: none"> <li>Two-chip mode (Slave chip) Timing signals and power voltage are supplied from Master chip.</li> </ul>

## LCD Drive Waveform (Normal Display mode)



**LCD Drive Timing Chart (1/128 duty)**

## Maximum Ratings

Characteristics	Symbol	Rating	Unit
Power supply voltage (1)	$V_{DD}, V_{IN}$ (Note 13)	-0.3 to 6.0	V
Power supply voltage (2)	VLC0, 1, 2, 3, 4, 5, $V_{CC}, V_{OUT}$	$V_{SS} + 18.0$ to $V_{SS} - 0.3$	V
Input voltage	$V_{inp}$ (Note 13, 14)	-0.3 to $V_{DD} + 0.3$	V
Operating temperature	$T_{opr}$	-30 to 85	°C
Storage temperature	$T_{stg}$	-55 to 125	°C

Note 13: Value based on  $V_{SS} = 0$  V

Note 14: Applies to input and data bus excluding  $V_{CC}, V_{OUT}, VLC0, VLC1, VLC2, VLC3, VLC4$  and  $VLC5$ .

## Electrical Characteristics (1)

(Test Conditions: Unless Otherwise Noted,  $V_{SS} = 0\text{ V}$ ,  $V_{DD} = 2.7\text{ to }3.3\text{ V}$ ,  $V_{CC} = 15.5\text{ V}$ ,  $T_a = 25^\circ\text{C}$ )

Characteristics	Symbol	Test Circuit	Test Condition	Min	Typ.	Max	Unit	Applicable
Operating voltage (1)	$V_{DD}$	—	—	2.4	—	3.3	V	$V_{DD}$
Operating voltage (2)	$V_{IN}$	—	—	2.7	—	3.3	V	$V_{IN}$
Operating voltage (3)	Normal display	$V_{CC}$	—	$6.0 - V_{SS}$	—	$16.5 - V_{SS}$	V	$V_{CC}, V_{OUT}$
	Partial display	$V_{CC}$	—	$4.0 - V_{SS}$	—	$16.5 - V_{SS}$	V	$V_{CC}, V_{OUT}$
Input voltage	High level	$V_{IH}$	—	$0.8 \times V_{DD}$	—	$V_{DD}$	V	DB0 to DB7, D/I, WR, RD, CS1, CS2, RS, P/S, 68/80, SI, SCK, RST, STB, CL, PM, FR, SYNC, CK, BLNK
	Low level	$V_{IL}$	—	0	—	$0.2 \times V_{DD}$	V	
Output voltage	High level	$V_{OH}$	—	$I_{OH} = -400\ \mu\text{A}$	$V_{DD} - 0.2$	$V_{DD}$	V	DB0 to DB7, SO, CL, PM, FR, SYNC, CK
	Low level	$V_{OL}$	—	$I_{OL} = 400\ \mu\text{A}$	0	0.2	V	
Segment driver on-resistance	Normal Display mode	Rcol	—	(Note 15)	—	7.5	k $\Omega$	SEG1 to SEG128
Common driver on-resistance	Normal Display mode	Rrow	—	(Note 15)	—	1.5	k $\Omega$	COM1 to COM128
Static icon on-resistance	Low Power Consumption mode	Ricon	—	(Note 16)	—	7.5	k $\Omega$	COMS, S1 to S16
Input leakage current	$I_{IL}$	—	$V_{inp} = V_{DD}\text{ to GND}$	-1	—	1	$\mu\text{A}$	DB0 to DB7, D/I, WR, RD, CS1, CS2, RS, P/S, 68/80, SI, SCK, RST, STB, CL, PM, FR, SYNC, CK, BLNK
Operating frequency	fosc	—	(Note 22)	—	80.64	—	kHz	OSC1
External clock input frequency	fex	—	(Note 22)	—	80.64	—	kHz	OSC1
External clock duty	fduty	—	—	45	50	55	%	OSC1
External clock rise/fall time	$t_r/t_f$	—	—	—	—	50	ns	OSC1
Current consumption (1)	$I_{SS1}$	—	(Note 17)	—	300	450	$\mu\text{A}$	$V_{SS}$
Current consumption (2)	$I_{SS2}$	—	(Note 18)	—	60	90	$\mu\text{A}$	$V_{SS}$
Current consumption (3)	$I_{SS3}$	—	(Note 19)	—	4	6	$\mu\text{A}$	$V_{SS}$
Current consumption (4)	$I_{SS4}$	—	(Note 20)	—	500	700	$\mu\text{A}$	$V_{SS}$
Current consumption (5)	$I_{SSSTB}$	—	(Note 21)	-1	—	1	$\mu\text{A}$	$V_{SS}$

Note 15:  $V_{CC} = 10.3\text{ V}$ , Load current  $\pm 100\ \mu\text{A}$ , 1/9 bias

Note 16:  $V_{DD} = 3.0\text{ V}$ , Load current  $\pm 100\ \mu\text{A}$ , 1/4 bias

Note 17:  $V_{DD} = 3.0\text{ V}$ ,  $V_{OUT} = 15.4\text{ V}$  ( $\times 6$  booster), no data access, internal clock (OSC = 80.64 kHz), no load, 1/12 bias, 1/128 duty, op-amp on, regulator on, Normal Display mode (Gray Scale), display pattern: check

Note 18:  $V_{DD} = 3.0\text{ V}$ ,  $V_{OUT} = 5.2\text{ V}$  (doubler), no data access, internal clock (OSC = 5 kHz), no load, 1/4 bias, 1/8 duty, op-amp on, regulator on, Partial Display mode, display pattern: check

Note 19:  $V_{DD} = 3.0\text{ V}$ , no data access, internal clock (OSC = 5.04 kHz), no load, op-amp off, regulator off, Low Power Consumption mode

Note 20:  $V_{DD} = 3.0\text{ V}$ ,  $V_{OUT} = \times 6$  booster, data access cycle ( $f/CE = 1\text{ MHz}$ ), internal clock (OSC = 82 kHz), no load, 1/12 bias, 1/128 duty, op-amp on, regulator on

Note 21:  $V_{DD} = 3.3\text{ V}$ ,  $V_{CC} - V_{SS} = 16.0\text{ V}$ ,  $\overline{\text{STB}} = \text{“L”}$

Note 22: 1/128 duty,  $f_{FR} = 70\text{ Hz}$

**Electrical Characteristics (2)**

(Test Conditions: Unless Otherwise Noted,  $V_{SS} = 0\text{ V}$ ,  $V_{DD} = V_{IN} = 2.7\text{ to }3.3\text{ V}$ ,  $V_{CC} = 15.5\text{ V}$ ,  $T_a = 25^\circ\text{C}$ )

Characteristics	Symbol	Test Circuit	Test Condition	Min	Typ.	Max	Unit	Applicable
Regulator reference high voltage (1) (Hi/Lo = 1)	VHR1	—	$T_a = 25^\circ\text{C}$ (Note 23)	15.3	15.4	15.5	V	$V_{OUT}$
Regulator reference high voltage (2) (Hi/Lo = 0)	VHR2	—	$T_a = 25^\circ\text{C}$ (Note 24)	12.9	13.0	13.1	V	$V_{OUT}$
Regulator reference high voltage (3) (Partial display mode)	VHR3	—	$T_a = 25^\circ\text{C}$ (Note 24)	7.9	8.0	8.1	V	$V_{OUT}$
Regulator reference high voltage temperature gradient	VHRINC	—	$T_a = -20\text{ to }60^\circ\text{C}$ (Note 23)	TBD	-0.05	TBD	%/°C	$V_{OUT}$

Note 23:  $V_{DD} = V_{IN} = 3.0\text{ V}$ , contrast = max, no display load, Normal Display mode

Note 24:  $V_{DD} = V_{IN} = 3.0\text{ V}$ , contrast = max, no display load, Partial Display mode

**Electrical Characteristics (3)**

(Test conditions: unless otherwise specified,  $V_{SS} = 0\text{ V}$ ,  $V_{DD} = 2.7\text{ to }3.3\text{ V}$ ,  $V_{CC} = 15.5\text{ V}$ ,  $T_a = 25^\circ\text{C}$ )

Characteristics	Symbol	Test Circuit	Test Condition	Min	Typ.	Max	Unit	Applicable
Op-amp output voltage offset (1)	Vopoff	—	(Note 25)	-100	—	100	mV	VLC0, VLC1, VLC2, VLC3, VLC4
Op-amp output voltage offset (2)	Vopoffs1	—	(Note 26)	-100	—	100	mV	VLC0, VLC1, VLC2, VLC3, VLC4
Op-amp output voltage offset (3)	Vopoffs2	—	load = $\pm 100\ \mu\text{A}$	-130	—	130	mV	VLC0, VLC1, VLC2, VLC3, VLC4

Note 25:  $V_{DD} = 2.7\text{ to }3.3\text{ V}$ ,  $V_{SS} = 0\text{ V}$ , 1/12 bias, 1/128 duty,  $V_{CC} = 15.4\text{ V}$ , op-amp on, no load

VLC0:  $VLC0 = Vopoff$

VLC1:  $(VLC0 \times 11/12) - VLC1 = Vopoff$

VLC2:  $(VLC0 \times 10/12) - VLC2 = Vopoff$

VLC3:  $(VLC0 \times 2/12) - VLC3 = Vopoff$

VLC4:  $(VLC0 \times 1/12) - VLC4 = Vopoff$

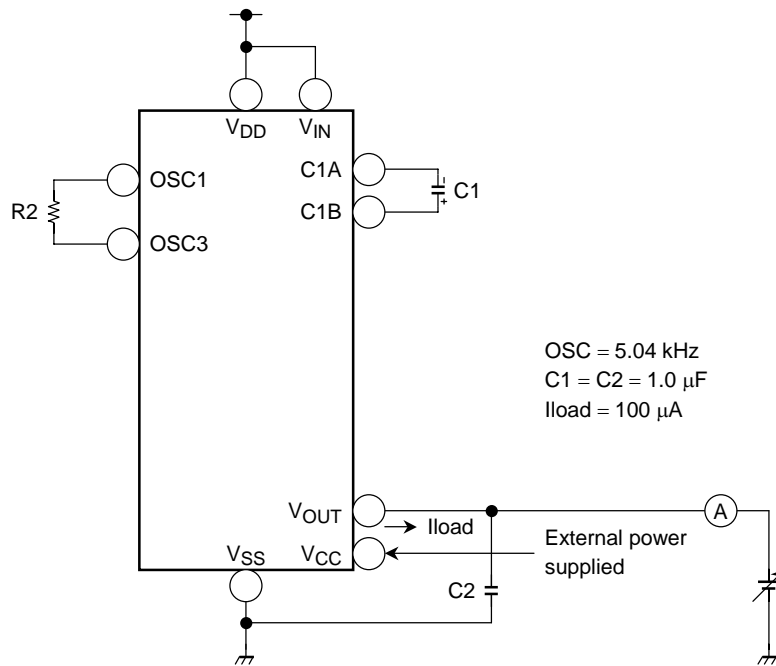
Note 26:  $V_{DD} = 2.7\text{ to }3.3\text{ V}$ ,  $V_{SS} = 0\text{ V}$ , 1/12 bias, 1/128 duty,  $V_{CC} = 16.0\text{ V}$ , op-amp on, no load

$Vopoff1 = ((VLC1 - VLC2) - (VLC0 - VLC1)) + ((VLC3 - VLC4) - (VLC4 - VLC5))$

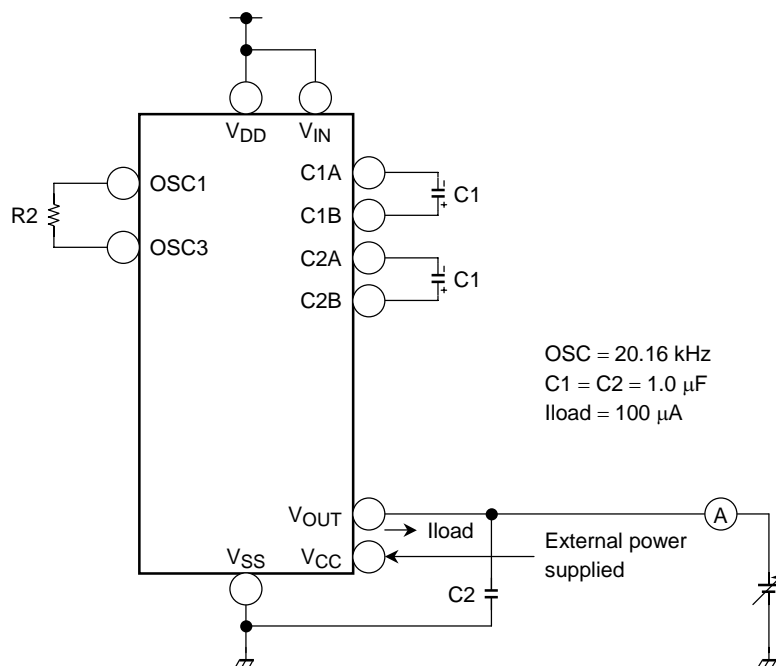
$Vopoff2 = ((VLC1 - VLC2) - (VLC0 - VLC1)) + ((VLC3 - VLC4) - (VLC4 - VLC5))$

## Test Circuit

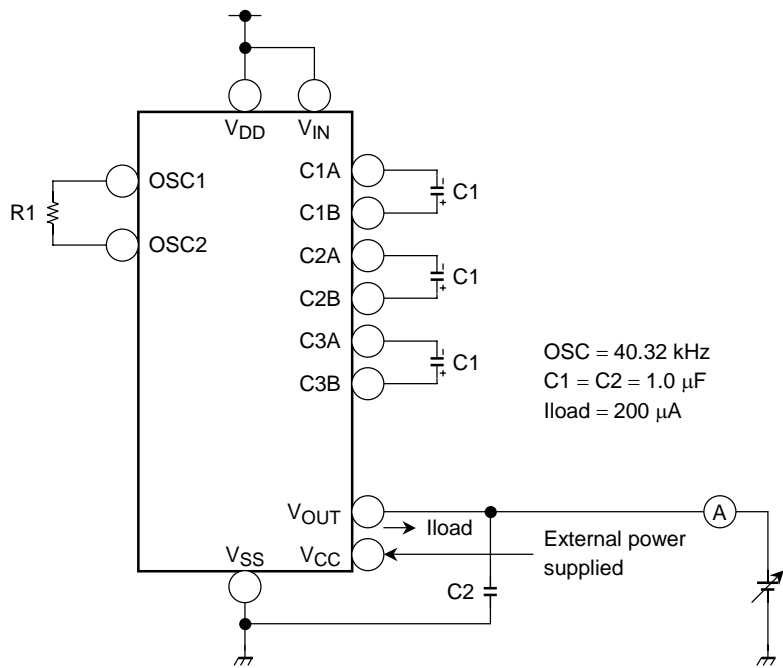
(1) With doubler



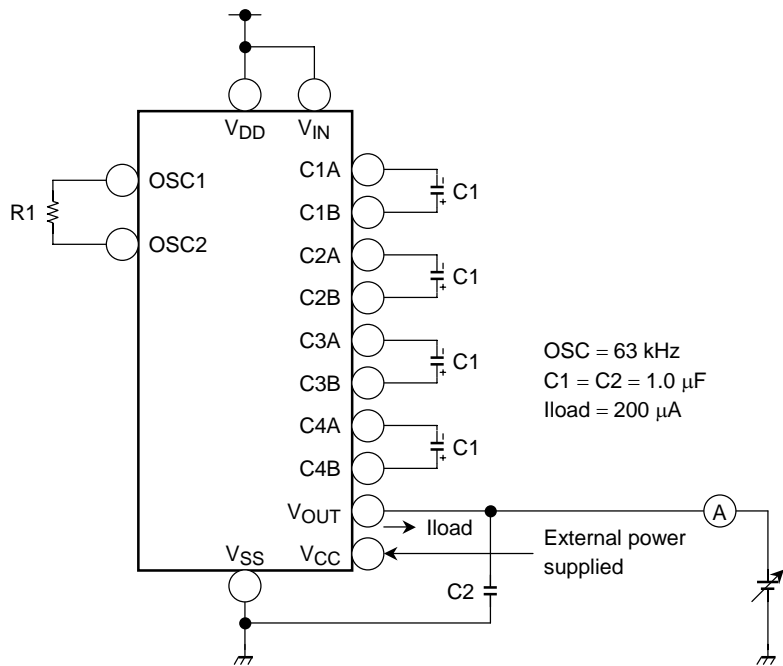
(2) With  $\times 3$  booster



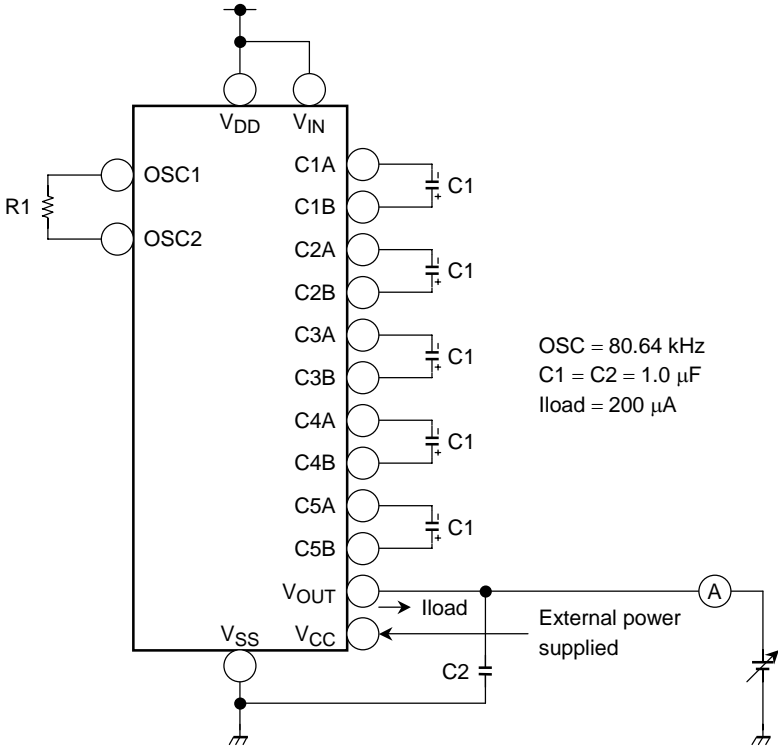
(3) With ×4 booster



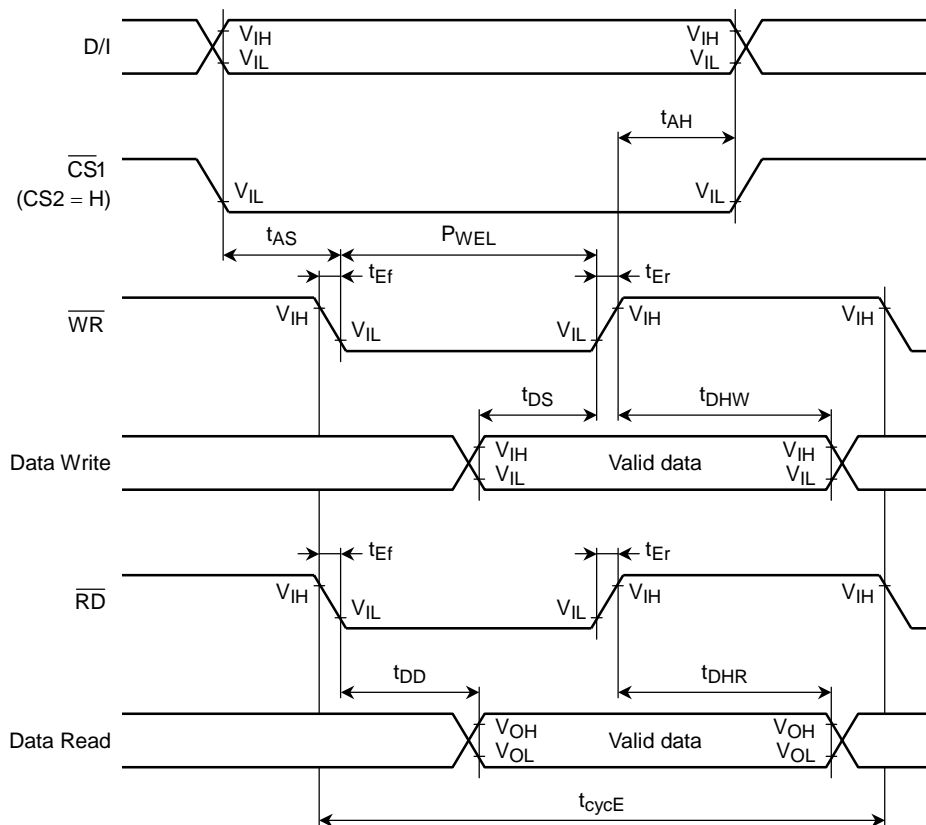
(4) With ×5 booster



(5) With x6 booster

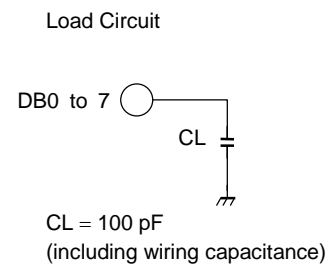


**Switching Characteristics (1) (8-bit 80 series MPU interface)**



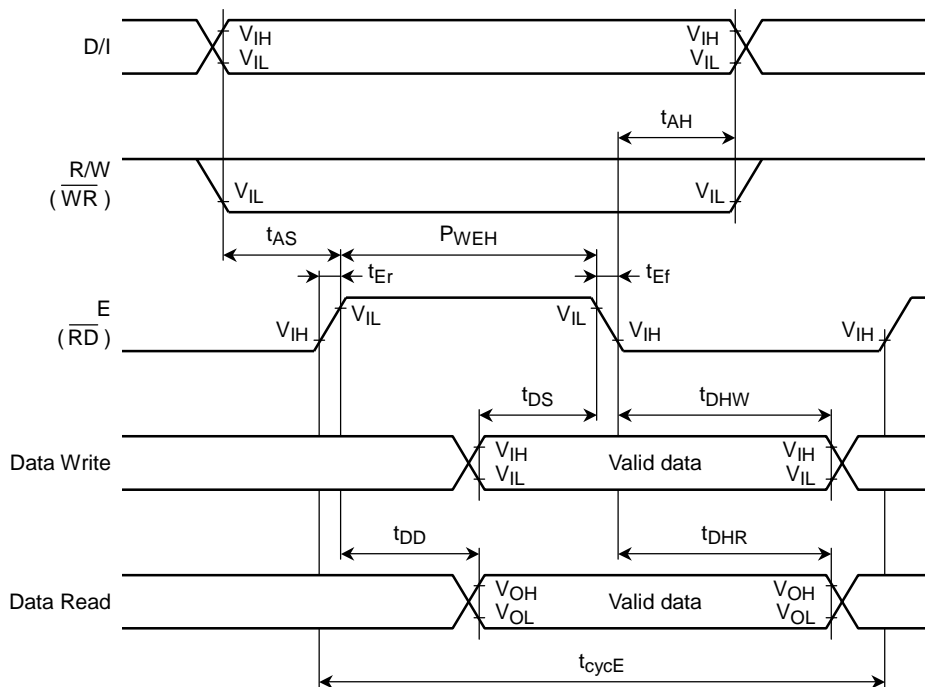
**Test Conditions (Unless Otherwise Noted,  $V_{SS} = 0\text{ V}$ ,  $V_{DD} = 2.7\text{ to }3.3\text{ V}$ ,  $V_{CC} = 15.5\text{ V}$ ,  $T_a = 25^\circ\text{C}$ )**

Characteristics	Symbol	Min	Max	Unit
Enable cycle time	$t_{cycE}$	500	—	ns
Enable pulse width	$P_{WEL}$	410	—	
Enable rise/fall time	$t_{Er}$ , $t_{Ef}$	—	25	
Address setup time	$t_{AS}$	20	—	
Address hold time	$t_{AH}$	0	—	
Data setup time	$t_{DS}$	100	—	
Write data hold time	$t_{DHW}$	20	—	
Data delay time	$t_{DD}$ (Note 27)	—	300	
Read data hold time	$t_{DHR}$ (Note 27)	20	—	



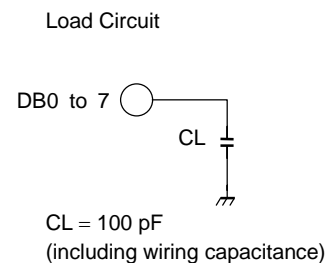
Note 27: When the load circuit shown is added

**Switching Characteristics (2) (8-bit 68 series MPU interface)**



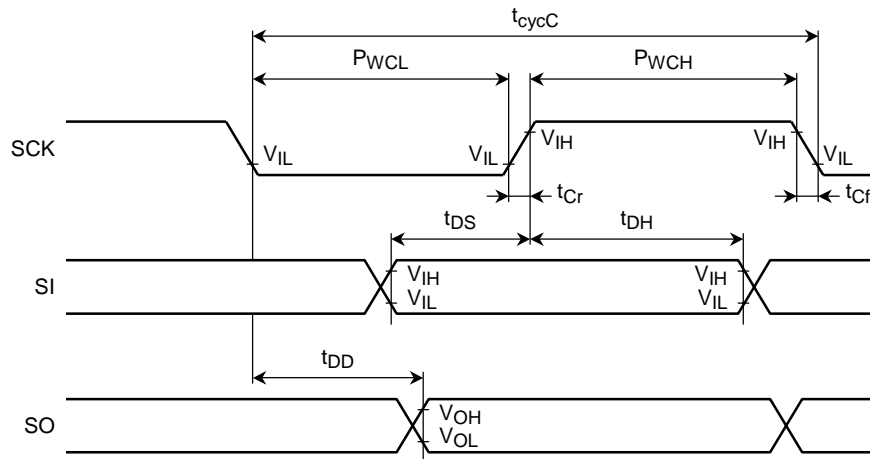
**Test Conditions (Unless Otherwise Noted,  $V_{SS} = 0\text{ V}$ ,  $V_{DD} = 2.7\text{ to }3.3\text{ V}$ ,  $V_{CC} = 15.5\text{ V}$ ,  $T_a = 25^\circ\text{C}$ )**

Characteristics	Symbol	Min	Max	Unit
Enable cycle time	$t_{cycE}$	500	—	ns
Enable pulse width	$P_{WEH}$	410	—	
Enable rise/fall time	$t_{Er}$ , $t_{Ef}$	—	25	
Address setup time	$t_{AS}$	20	—	
Address hold time	$t_{AH}$	0	—	
Data setup time	$t_{DS}$	100	—	
Write data hold time	$t_{DHW}$	20	—	
Data delay time	$t_{DD}$ (Note 28)	—	300	
Read data hold time	$t_{DHR}$ (Note 28)	20	—	



Note 28: When the load circuit shown is added

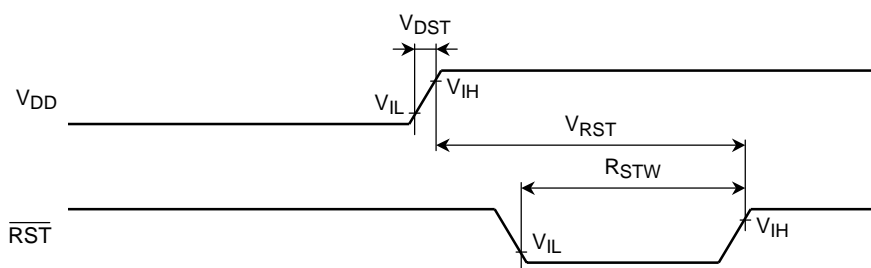
**Switching Characteristics (3) (serial interface)**



**Test Conditions (Unless Otherwise Noted,  $V_{SS} = 0\text{ V}$ ,  $V_{DD} = 2.7\text{ to }3.3\text{ V}$ ,  $V_{CC} = 15.5\text{ V}$ ,  $T_a = 25^\circ\text{C}$ )**

Characteristics	Symbol	Min	Max	Unit
Enable cycle time	$t_{cycC}$	2000	—	ns
Enable pulse width	$P_{WCL}, P_{WCH}$	900	—	
Enable rise/fall time	$t_{Cr}, t_{Cf}$	—	25	
Data setup time	$t_{DS}$	250	—	
Data hold time	$t_{DH}$	100	—	
Data delay time	$t_{DD}$	—	200	

## Switching Characteristics (4)

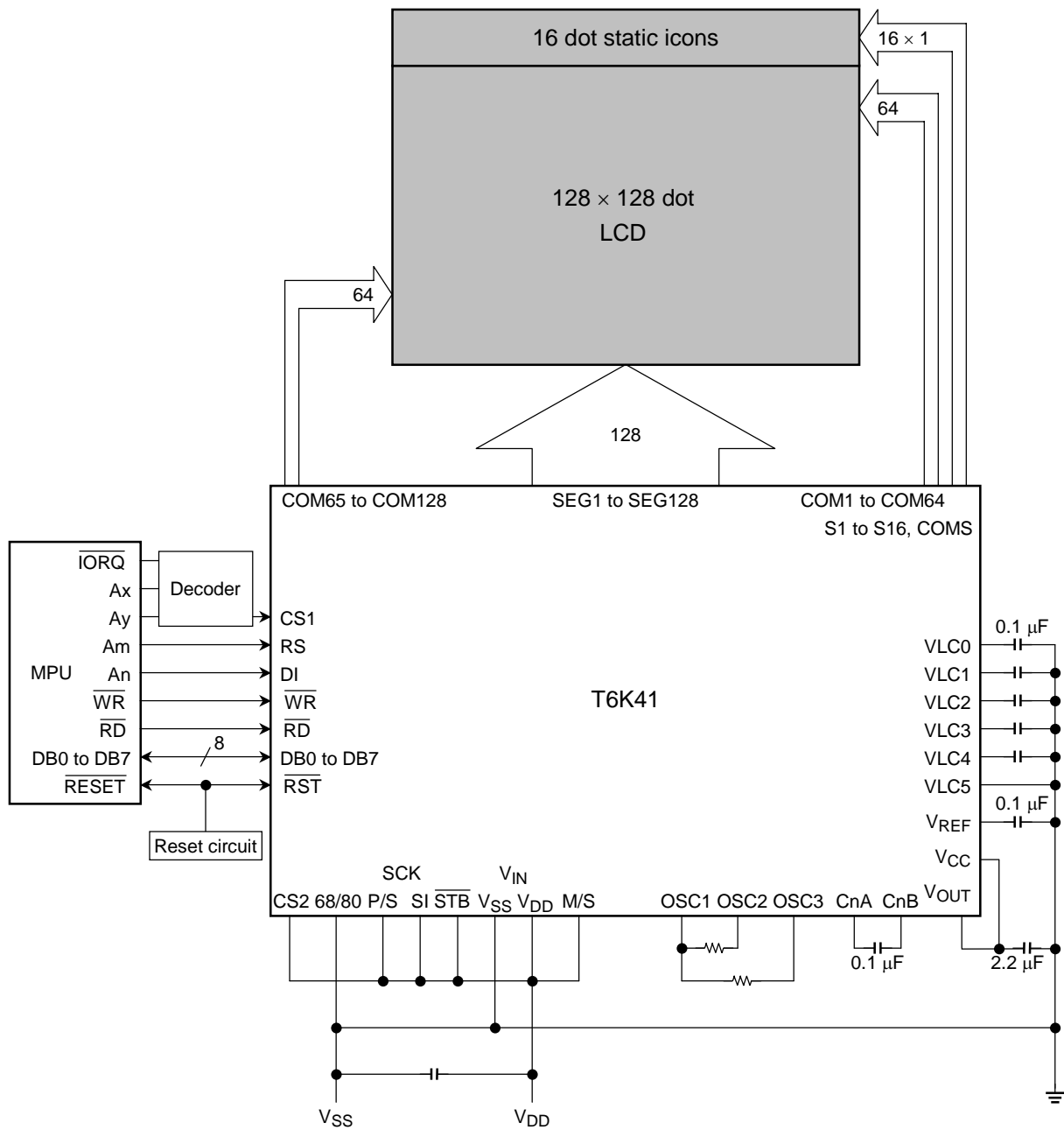


**Test Conditions (Unless Otherwise Noted,  $V_{SS} = 0$  V,  $V_{DD} = 2.7$  to  $3.3$  V,  $V_{CC} = 15.5$  V,  $T_a = 25^\circ\text{C}$ )**

Characteristics	Symbol	Min	Max	Unit
$V_{DD}$ rise time	$V_{DST}$	—	1	ms
Reset hold	$V_{RST}$	1	—	$\mu\text{s}$
Reset pulse width	$RSTW$	1	—	$\mu\text{s}$

## Application Circuit

T6K41 one chip (Master) mode



- VDD = 3.0 V
- Using DC-DC converter (x6)
- Using internal CR oscillator
- Using Op-amp
- 80-series parallel interface

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