

LM4681 Boomer® Audio Power Amplifier Series 10 Watt Stereo CLASS D Audio Power Amplifier with Stereo Headphone Amplifier and I²C/SPI Volume Control

Check for Samples: [LM4681](#)

FEATURES

- Pulse-width Modulator
- I²C/SPI (Selectable) Volume Control
- Stereo Headphone Amplifier
- “Click and Pop” Suppression Circuitry
- Micropower Shutdown Mode
- 48-Lead WQFN package (No Heatsink Required)

APPLICATIONS

- Flat Panel Displays
- Televisions
- Multimedia Monitors

KEY SPECIFICATIONS

- PO at THD+N =10%, AV = 30dB, VDD = 14V 10W (typ)
- THD+N at 1kHz at 1W into 8Ω (Power Amp) 0.43% (typ)
- Efficiency at 7W into 8Ω 85% (min)
- Total Quiescent Power Supply Current 50mA (typ)
- THD+N 1kHz, 20mW, 32Ω (Headphone) 0.02% (typ)
- Single Supply Range 9.0V to 15.5V

DESCRIPTION

The LM4681 is a fully integrated single supply, CLASS D audio power amplifier solution. The LM4681 utilizes a proprietary balanced pulse-width modulation technique that lowers output noise and THD and improves PSRR when compared to conventional pulse width modulators.

The LM4681 also features a stereo headphone amplifier that delivers 80mW into a 32Ω headset with less than 0.5% THD.

The LM4681's I²C/SPI (selectable) volume control has a +30dB to –48dB range when speakers are driven and a range of +13dB to –65dB when headphones are connected. All amplifiers are protected by thermal shutdown. Additionally, the high efficiency power amplifiers have output current limit.

With a 8Ω load, the IC's efficiency for a 6W power level is 85%. The IC features click and pop reduction circuitry that minimizes audible popping during device turn-on and turn-off. The LM4681 is available in a 48-lead WQFN package, ideal for portable and desktop computer applications.



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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

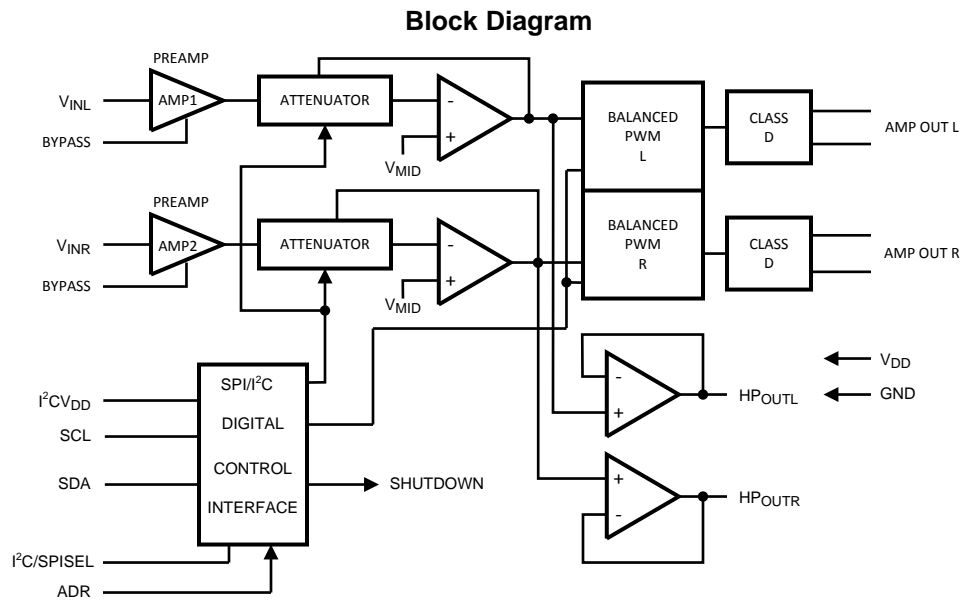
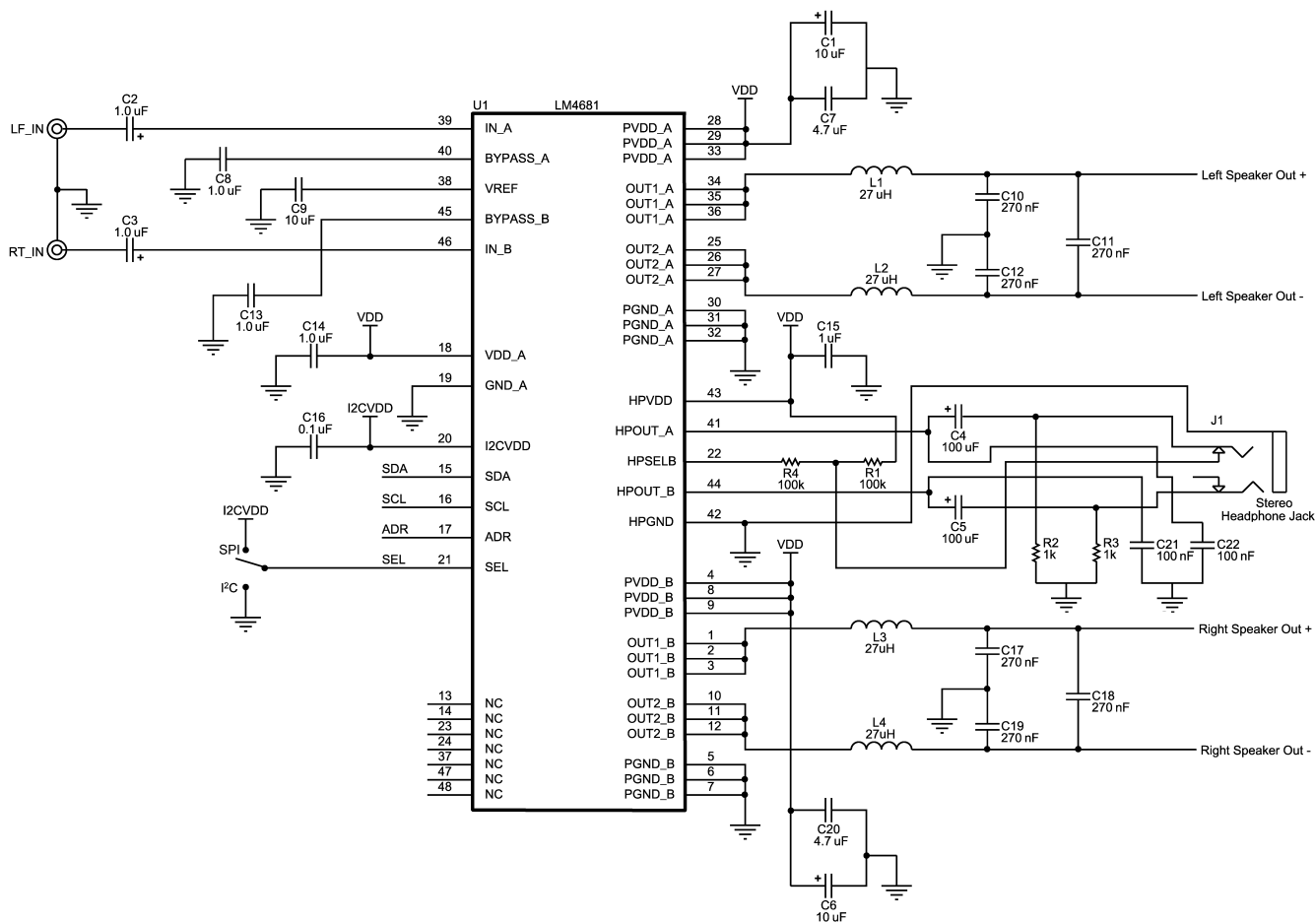


Figure 1. Block Diagram for LM4681

Figure 1. Typical Application



Absolute Maximum Ratings⁽¹⁾⁽²⁾

Supply Voltage		16V
Input Voltage		-0.3V to $V_{DD} + 0.3V$
Power Dissipation ⁽³⁾		Internally Limited
ESD Susceptibility ⁽⁴⁾		2000V
ESD Susceptibility ⁽⁵⁾		200V
Junction Temperature ⁽⁶⁾		150°C
Storage Temperature		$-65^{\circ}\text{C} \leq T_A \leq 150^{\circ}\text{C}$
Soldering Information		
WQFN Package	Vapor Phase (60 sec.)	215°C
	Infrared (15 sec.)	220°C

- (1) “Absolute Maximum Ratings” indicate limits beyond which damage to the device may occur. “Operating Ratings” indicate conditions for which the device is functional, but do not ensure specific performance limits. “Electrical Characteristics” state DC and AC electrical specifications under particular test conditions which specify performance limits. This assumes that the device is within the Operating Ratings. Specifications are not ensured for parameters where no limit is given, however, the typical value is a good indication of device performance.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) For operating at case temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of $\theta_{JA} = 80^{\circ}\text{C}/\text{W}$ (junction to ambient).
- (4) Human body model, 100pF discharged through a 1.5k Ω resistor.
- (5) Machine Model 220pF – 240pF discharged through all pins.
- (6) The operating junction temperature maximum is 150°C.

Operating Ratings⁽¹⁾

Temperature Range	$T_{MIN} \leq T_A \leq T_{MAX}$	$-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$
Supply Voltage		$9V \leq V_{DD} \leq 15.5V$
Thermal Resistance (WQFN Package)	θ_{JA}	28°C/W
	θ_{JC}	20°C/W

- (1) All voltages are measured with respect to the ground pin, unless otherwise specified.

Electrical Characteristics⁽¹⁾⁽²⁾

The following specifications apply for $V_{DD} = 12V$, $I^2CV_{DD} = 5V$, $R_L = 8\Omega$, LC filter values as shown in Figure 36, unless otherwise specified.

Limits apply for $T_A = 25^{\circ}\text{C}$.

Symbol	Parameter	Conditions	LM4681		Units
			Typical	Limit	
V_{DD}	Operating Supply Voltage Range		12	15.5 9	V (max) V (min)
I_S	Quiescent Power Supply Current, Class D Mode	$V_{IN} = 0V_{RMS}$, $V_{HPSEL} = 0V$	50	70	mA (max)
I_S	Quiescent Power Supply Current, Headphone Mode	$V_{IN} = 0V_{RMS}$, $V_{HPSEL} = V_{DD}$	22	30	mA (max)
I_{SD}	Quiescent Power Supply Current, Shutdown Mode	$V_{SD} = 5V$	0.1		mA
R_{IN}	Input Resistance in Both Modes		8		k Ω
I^2CV_{DD}	I^2C / SPI Logic Supply Voltage			5.5 3	V (max) V (min)
V_{IH}	Minimum High Level Input Voltage	I^2C/SPI Interface pins		$0.7 \times I^2CV_{DD}$	V (min)
V_{IL}	Maximum Low Level Input Voltage		$0.3 \times I^2CV_{DD}$	V (max)	
V_{HPIH}	HP Sense High Input Voltage			$V_{DD} - 1$	V (min)
V_{HPIL}	HP Sense Low Input Voltage			$V_{DD}/2$	V (max)

- (1) All voltages are measured with respect to the ground pin, unless otherwise specified.
- (2) Limits are specified to AOQL (Average Outgoing Quality Level).

Electrical Characteristics⁽¹⁾⁽²⁾ (continued)

The following specifications apply for $V_{DD} = 12V$, $I^2CV_{DD} = 5V$, $R_L = 8\Omega$, LC filter values as shown in [Figure 36](#), unless otherwise specified.

Limits apply for $T_A = 25^\circ C$.

Symbol	Parameter	Conditions	LM4681		Units
			Typical	Limit	
Power Amplifiers					
P_O	Maximum Output Power, Per Channel	THD+N $\leq 1\%$, $f_{IN} = 1kHz$	6.0	5.3	W (min)
		THD+N $\leq 10\%$, $V_{DD} = 14V$, $f_{IN} = 1kHz$	10		W
P_{D1}	Power Dissipation	$P_O = 6W/Chan$, $f_{IN} = 1kHz$	1.17		W
E_{FF1}	Efficiency	$P_O = 6W/Chan$, $f_{IN} = 1kHz$	85		%
THD+N	Harmonic Distortion + Noise	$P_O = 1W/Chan$, $f_{IN} = 1kHz$	0.11		%
V_{NOISE}	Output Noise Voltage	$R_{SOURCE} = 50\Omega$, $C_{IN} = 1\mu F$, BW = 8Hz to 22kHz, A-weighted, input referred	10		μV
PSRR	Power Supply Rejection Ratio	$V_{RIPPLE} = 200mV_{P-P}$, $C_{BYPASS1} = 10\mu F$, input referred			dB
		$f = 50Hz$	82		
		$f = 60Hz$	84		
		$f = 100Hz$	92		
		$f = 120Hz$	95		
	$f = 1kHz$	95			
Headphone Amplifiers					
P_O	Maximum Power Output Per Channel	THD+N $\leq 1\%$, $R_L = 32\Omega$, $f_{IN} = 1kHz$	94	70	mW (min)
THD+N	Distortion + Noise	$P_O = 20mW$, $R_L = 32\Omega$, $f_{IN} = 1kHz$	0.02		%
V_{NOISE}	Output Noise Voltage, RMS	$R_{IN} = 50\Omega$, $C_{IN} = 1\mu F$, BW = 20Hz to 20kHz, $R_L = 32\Omega$ A-weighted, Input referred	22		μV
PSRR	Power Supply Rejection Ratio (Referred to Input)	200mV, 1kHz, $V_{IN} = 0$, $R_L = 32\Omega$	77		dB

Electrical Characteristics for Volume Control⁽¹⁾

The following specifications apply for $V_{DD} = 12V$. Limits apply for $T_A = 25^\circ C$.

Symbol	Parameter	Conditions	LM4681		Units (Limits)
			Typical ⁽²⁾	Limit ⁽³⁾	
C_{RANGE}	Gain Range	Digital Code = Full Scale, No Load Power Amplifier	30	29	dB (min)
		Headphone Amplifier	13	12	dB (min)
		Digital Code = +1LSB, No Load Power Amplifier	-48	-46	dB (min)
		Headphone Amplifier	-65	-63	dB (min)
A_M	Mute Gain	Digital Code = 0, No Load Power Amplifier		-74	dB (max)
		Headphone Amplifier	-76	-74	dB (max)

(1) All voltages are measured with respect to the ground pin, unless otherwise specified.

(2) Typicals are measured at $25^\circ C$ and represent the parametric norm.

(3) Limits are specified to AOQL (Average Outgoing Quality Level).

Table 1. I²C/SPI Interface Controls

	B7	B6	B5	B4	B3	B2	B1	B0
I ² C Address	1	1	0	1	1	0	ADR	0
Mode Control Register	0	X	0	X	X	X	0 Mute Active	0 Shutdown Active
Volume Control Register (See Table 4)	1	0	0	V4	V3	V2	V1	V0

Table 2. Headphone Control

HP Sense Pin (HPSEL, pin 22)	Output Stage Configuration
0	Class D Amps Active
1 (V_{DD})	Class D Amps inactive

Table 3. Logic Controls

Logic Level (SEL, pin 21)	I ² C/SPI Select
0	I ² C mode
1	SPI mode

Typical Performance Characteristics

(Volume control at maximum, unless otherwise stated.)

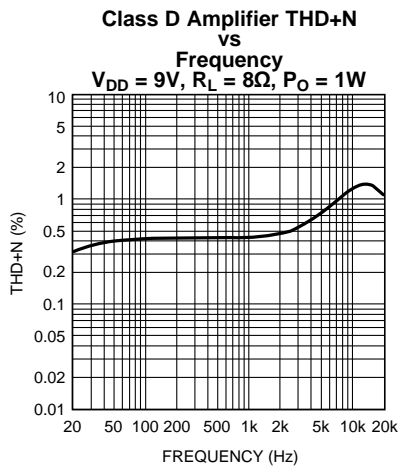


Figure 3.

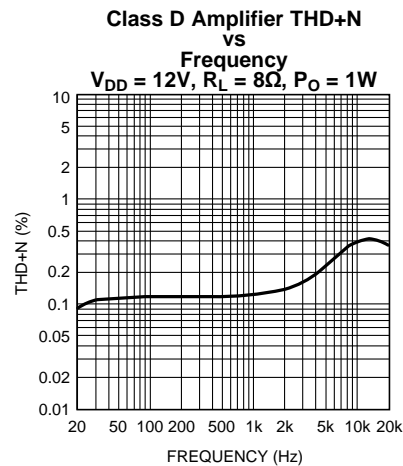


Figure 4.

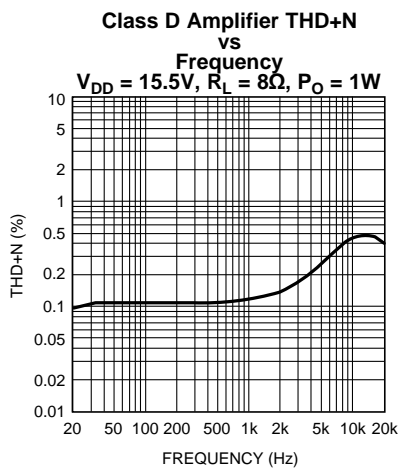


Figure 5.

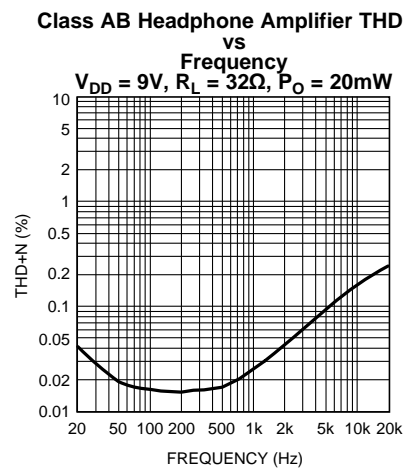


Figure 6.

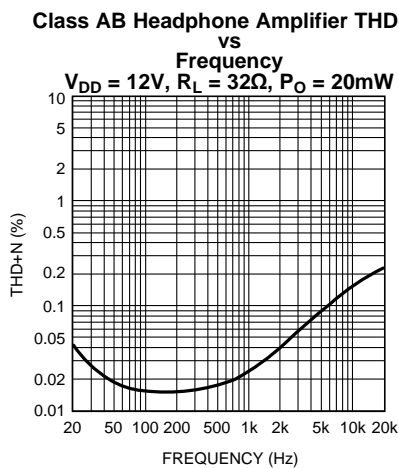


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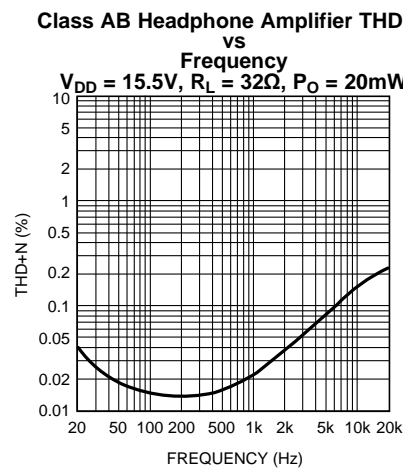


Figure 8.

Typical Performance Characteristics (continued)

(Volume control at maximum, unless otherwise stated.)

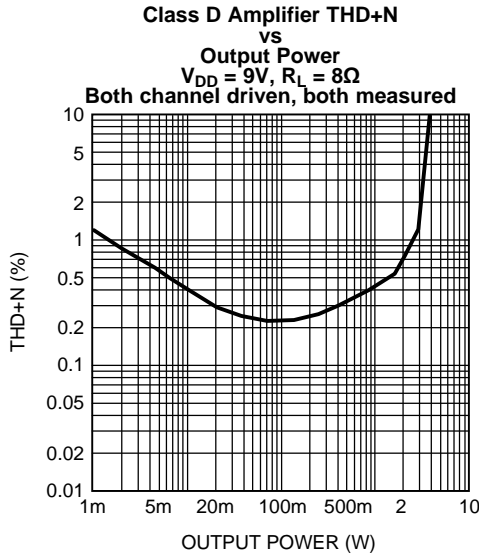


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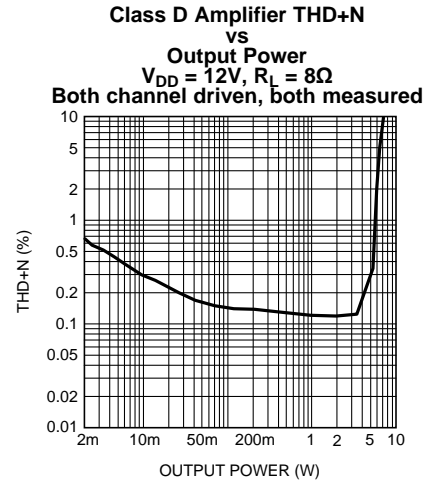


Figure 10.

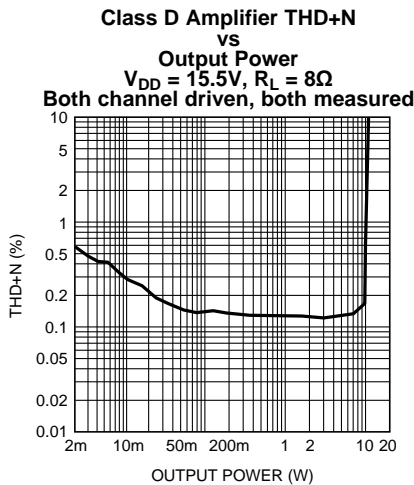


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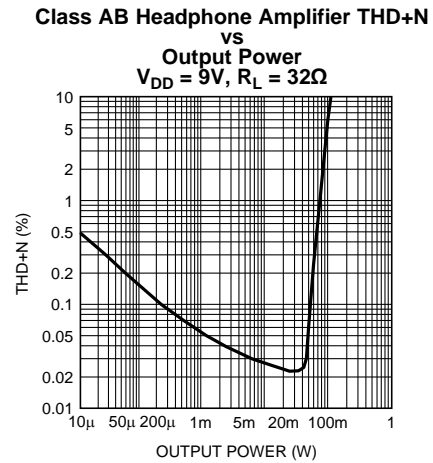


Figure 12.

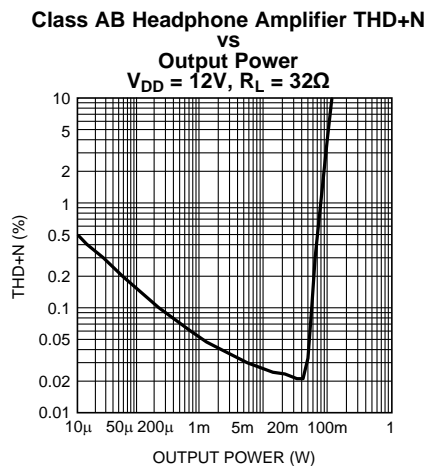


Figure 13.

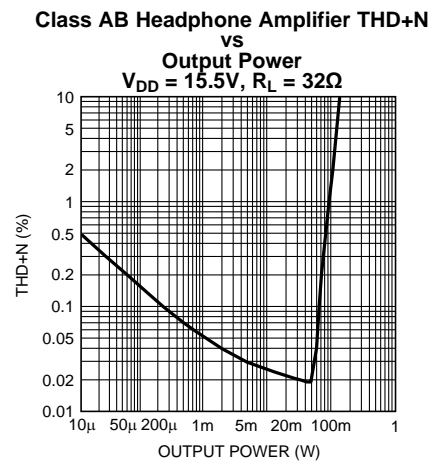


Figure 14.

Typical Performance Characteristics (continued)

(Volume control at maximum, unless otherwise stated.)

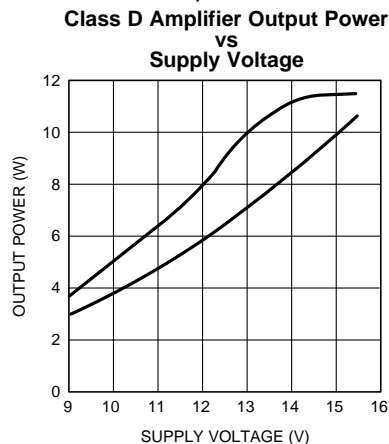


Figure 15.

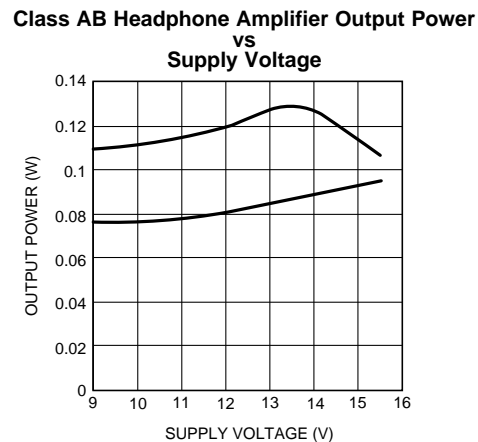


Figure 16.

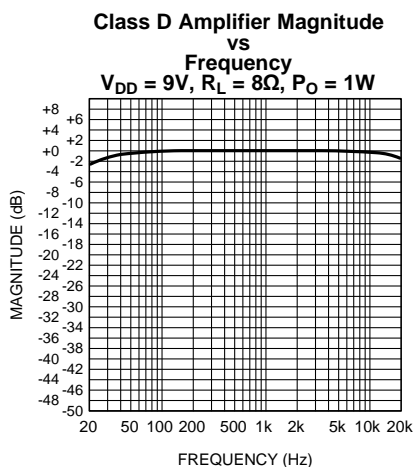


Figure 17.

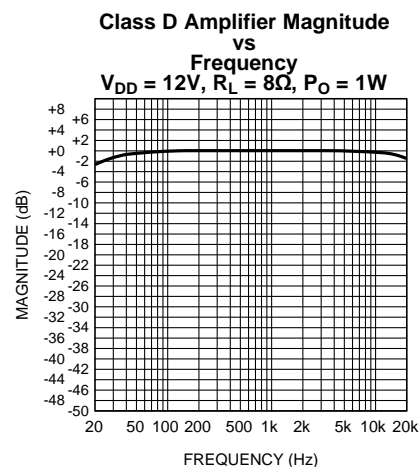


Figure 18.

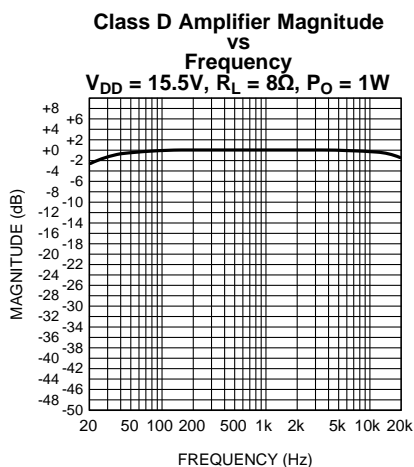


Figure 19.

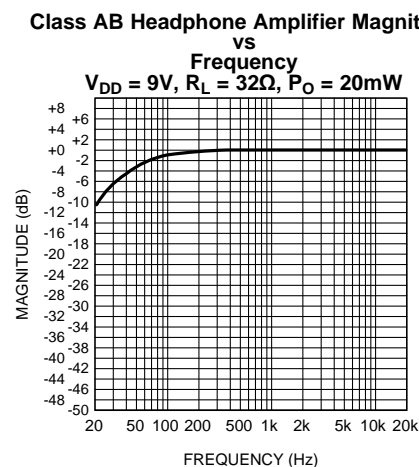


Figure 20.

Typical Performance Characteristics (continued)

(Volume control at maximum, unless otherwise stated.)

Class AB Headphone Amplifier Magnitude

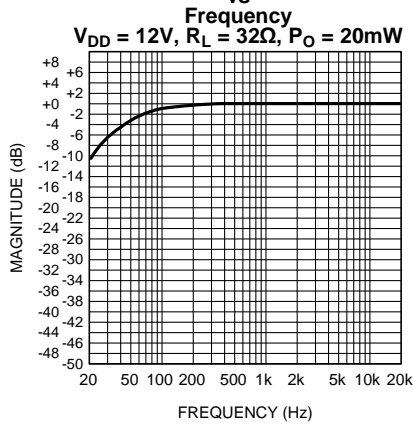


Figure 21.

Class AB Headphone Amplifier Magnitude

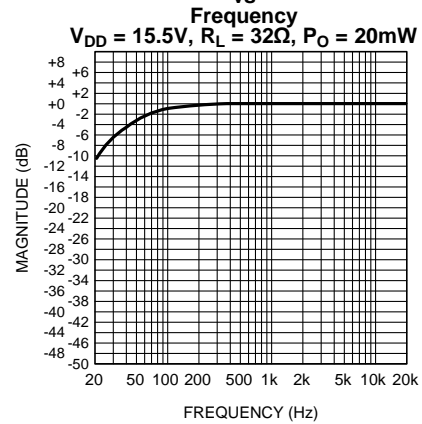


Figure 22.

PSRR
vs
Frequency
 $V_{DD} = 9V$

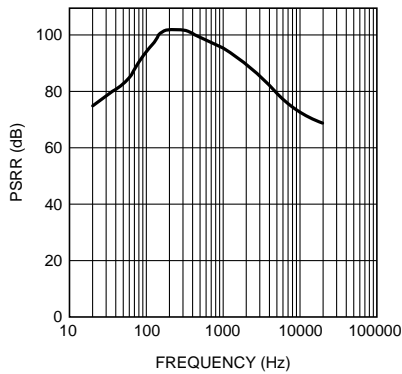


Figure 23.

PSRR
vs
Frequency
 $V_{DD} = 12V$

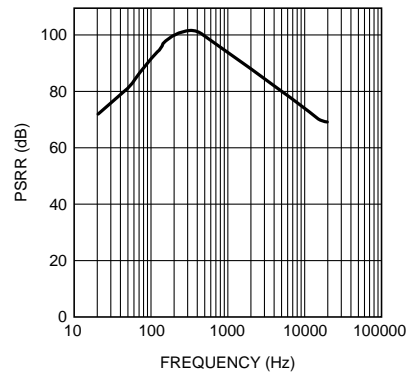


Figure 24.

PSRR
vs
Frequency
 $V_{DD} = 15.5V$

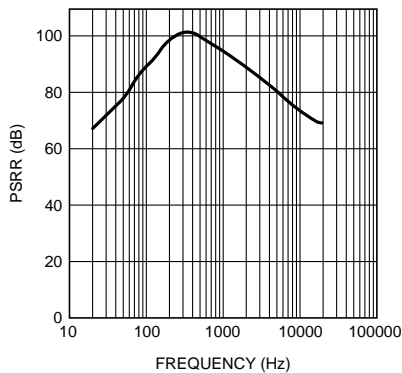


Figure 25.

Class D Amplifier Dissipation
vs
Load Dissipation
 $V_{DD} = 9V, R_L = 8\Omega$
Both channels driven and measured

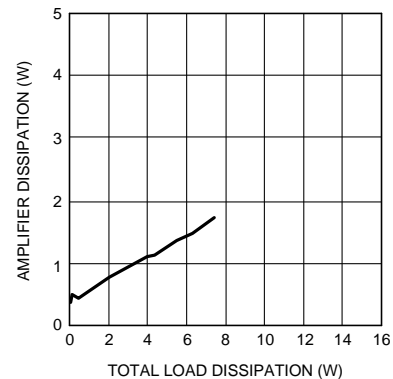


Figure 26.

Typical Performance Characteristics (continued)

(Volume control at maximum, unless otherwise stated.)

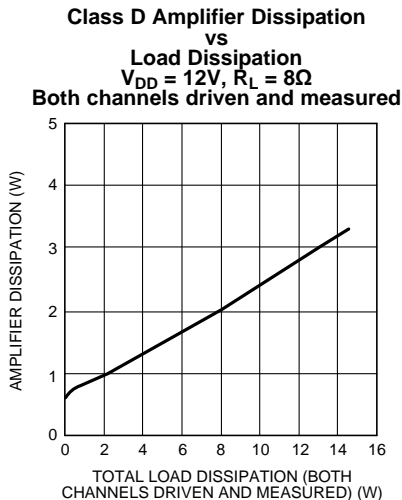


Figure 27.

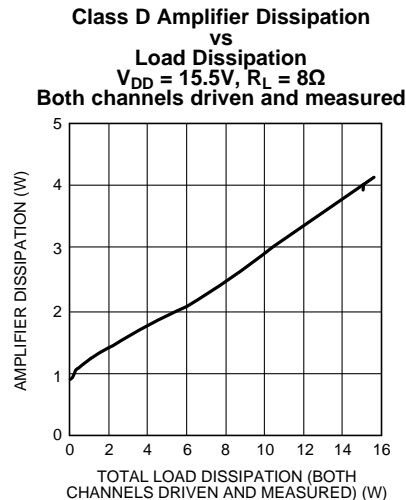


Figure 28.

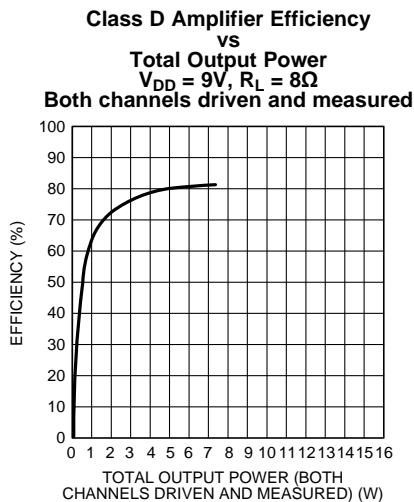


Figure 29.

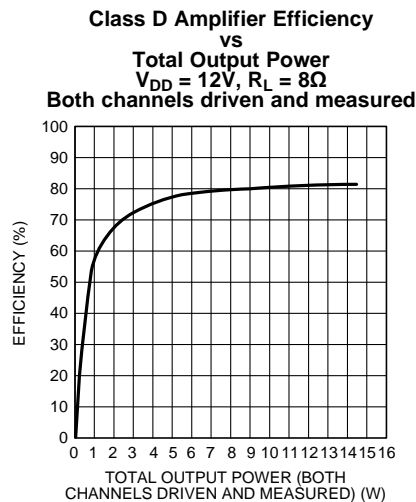


Figure 30.

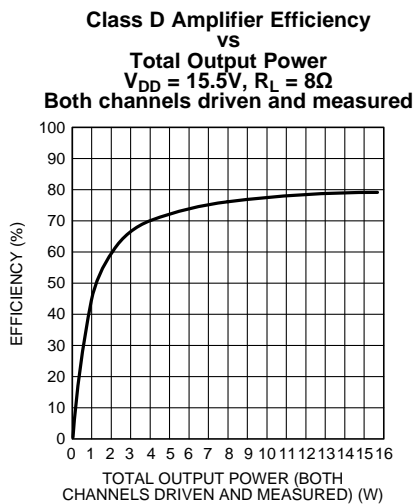


Figure 31.

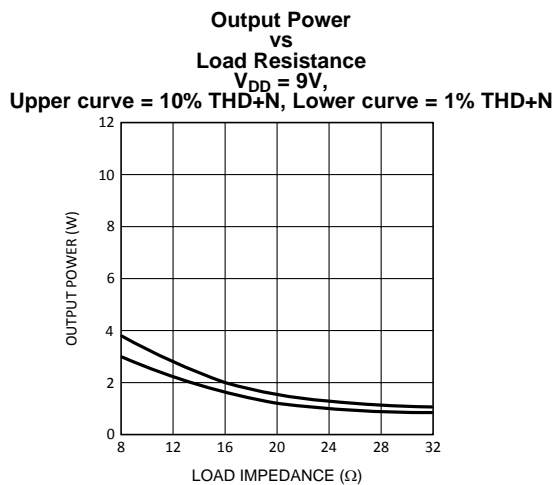


Figure 32.

Typical Performance Characteristics (continued)

(Volume control at maximum, unless otherwise stated.)

**Output Power
vs
Load Resistance**
 $V_{DD} = 12V$,
Upper curve = 10% THD+N, Lower curve = 1% THD+N

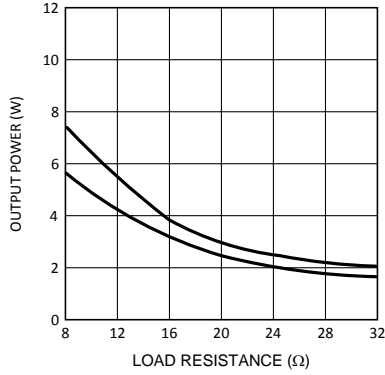


Figure 33.

**Output Power
vs
Load Resistance**
 $V_{DD} = 15.5V$,
Upper curve = 10% THD+N, Lower curve = 1% THD+N

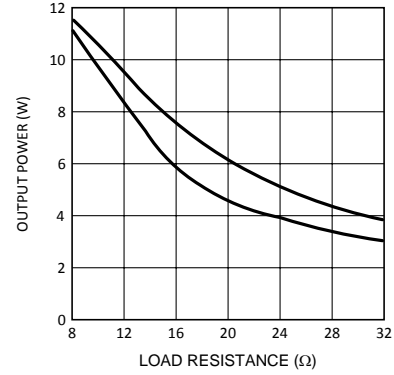


Figure 34.

**Power Supply Current
vs
Power Supply Voltage**

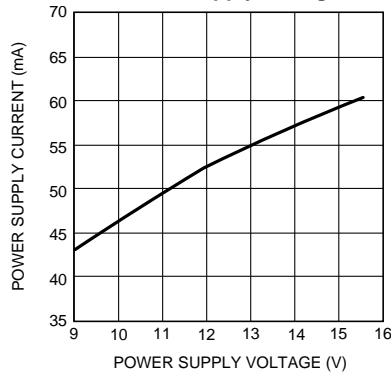


Figure 35.

GENERAL FEATURES

SYSTEM FUNCTIONAL INFORMATION

Modulation Technique

Unlike typical Class D amplifiers that use single-ended comparators to generate a pulse-width modulated switching waveform and RC timing circuits to set the switching frequency, the LM4681 uses a balanced differential floating modulator. Oscillation is a result of injecting complimentary currents onto the respective plates of a floating, on-die capacitor. The value of the floating capacitor and value of the components in the modulator's feedback network set the nominal switching frequency at 450kHz. Modulation results from imbalances in the injected currents. The amount of current imbalance is directly proportional to the applied input signal's magnitude and frequency.

Using a balanced, floating modulator produces a Class D amplifier that is immune to common mode noise sources such as substrate noise. This noise occurs because of the high frequency, high current switching in the amplifier's output stage. The LM4681 is immune to this type of noise because the modulator, the components that set its switching frequency, and even the load all float with respect to ground.

The balanced modulator's pulse width modulated output drives the gates of the LM4681's H-bridge configured output power MOSFETs. The pulse-train present at the power MOSFETs' output is applied to an LC low pass filter that removes the 450kHz energy component. The filter's output signal, which is applied to the driven load, is an amplified replica of the audio input signal.

Shutdown Function

The LM4681's digitally controlled shutdown function allows the user to place the amplifier in a shutdown mode while the system power supply remains active. Activating shutdown deactivates the output switching waveform and minimizes the quiescent current. Through the SPI/I²C digital interface, the Mode control register's Bit 0 is used to control the LM4681's shutdown function. A logic "0" activates shutdown, whereas a logic "1" returns the amplifier to its operational quiescent state. When the power supply voltage is first applied, the LM4681 is operating in the shutdown mode. For more information on the digital interface, see the section titled [Table 1](#).

Mute Function

The LM4681's digitally-controlled mute function allows the user to place the amplifier outputs in a muted mode while the amplifier's analog input signals remain active. Activating mute internally removes the analog input signal from the Class D and headphone amplifier inputs. While muted, the amplifier inputs and outputs retain their $V_{DD}/2$ operational bias. Through the SPI/I²C digital interface, the Mode control register's Bit 1 is used to control the LM4681's audio mute function. A logic "0" activates mute, whereas a logic "1" deactivates mute. When the power supply voltage is first applied, the LM4681's headphone and Class D amplifier outputs are muted. More information on the digital interface is found in the section titled [Table 1](#).

Stereo Headphone Amplifier

The LM4681's stereo headphone amplifier operates continuously, even while the Class D amplifiers are active. When using headphones to listen to program material, it is usually desirable to stop driving external speakers. This is easily achieved by using the active low HPSEL input. As shown in typical application schematic in [Figure 36](#), with no headphones connected to the headphone jack the input voltage applied to the HPSEL pin is a logic low. In this state, the Class D amplifiers are active and able to drive external speakers. When headphones are plugged into the headphone jack, the switch internal to the jack is opened. This changes the voltage applied to the HPSEL pin to a logic high, shutting off the LM4681's Class D amplifiers.

Under Voltage Protection

The under voltage protection disables the output driver section of the LM4681 while the supply voltage is below 8V. This condition may occur as power is first applied or during low line conditions, changes in load resistance, or when power supply sag occurs. The under voltage protection ensures that all of the LM4681's power MOSFETs are off. This action eliminates shoot-through current and minimizes output transients during turn-on and turn-off. The under voltage protection gives the digital logic time to stabilize into known states, further minimizing turn output transients.

Power Supply Sequencing

To ensure best performance, please observe the following power-up sequence. The $I^2C V_{DD}$ supply voltage should be applied first. Do not send any data to the LM4681's internal registers until the V_{DD} is applied. This takes advantage of the LM4681's power-on reset, which activates the amplifier's shutdown and mute. Once $I^2C V_{DD}$ is applied, apply the V_{DD} supply voltage. Prior to removing the two supply voltages, activate shutdown and mute.

Turn-On Time

The LM4681 has an internal timer that determines the amplifier's turn-on time. After power is first applied or the part returns from shutdown, the nominal turn-on time is 600ms. This delay allows all externally applied capacitors to charge to a final value of $V_{DD}/2$. Further, during turn-on, the outputs are muted. This minimizes output transients that may occur while the part settles into its quiescent operating mode.

Output Stage Current Limit and Fault Detection Protection

The output stage MOSFETs are protected against output conditions that could otherwise compromise their operational status. The first stage of protection is output current limiting. When conditions that require high currents to drive a load, the LM4681's current limit circuitry clamps the output current at a nominal value of 2.5A. The output waveform is present, but may be clipped or its amplitude reduced. The same 2.5A nominal current limit also occurs if the amplifier outputs are shorted together or either output is shorted to V_{DD} or GND.

The second stage of protection is an onboard fault detection circuit that continuously monitors the signal on each output MOSFET's gate and compares it against the respective drain voltage. When a condition is detected that violates a MOSFET's Safe Operating Area (SOA), the drive signal is disconnected from the output MOSFETs' gates. The fault detect circuit maintains this protective condition for approximately 600ms, at which time the drive signal is reconnected. If the fault condition is no longer present, normal operation resumes. If the fault condition remains, however, the drive signal is again disconnected.

Thermal Protection

The LM4681 has thermal shutdown circuitry that monitors the die temperature. Once the LM4681 die temperature reaches 170°C, the LM4681 disables the output switching waveform and remains disabled until the die temperature falls below 140°C (typ).

Over-Modulation Protection

The LM4681's over-modulation protection is a result of the preamplifier's (AMP1 and AMP2, [Figure 1](#)) inability to produce signal magnitudes that equal the power supply voltages. Since the preamplifier's output magnitude will always be less than the supply voltage, the duty cycle of the amplifier's switching output will never reach zero. Peak modulation is limited to a nominal 95%.

I²C Compatible Interface

The LM4681 uses a serial bus, which conforms to the I²C protocol, to control the chip's functions with two wires: clock (SCL) and data (SDA). The clock line is uni-directional. The data line is bi-directional (open-collector). The maximum clock frequency specified by the I²C standard is 400kHz. In this discussion, the master is the controlling microcontroller and the slave is the LM4681.

The I²C address for the LM4681 is determined using the ADR pin. The LM4681's two possible I²C chip addresses are of the form 110110X₁0 (binary), where X₁ = 0, if ADR is logic low, and X₁ = 1, if ADR is a logic high. If the I²C interface is used to address a number of chips in a system, the LM4681's chip address can be changed to avoid possible address conflicts.

The bus format for the I²C interface is shown in [Figure 36](#). The bus format diagram is broken up into six major sections:

The "start" signal is generated by lowering the data signal while the clock signal is high. The start signal will alert all devices attached to the I²C bus to check the incoming address against their own address.

The 8-bit chip address is sent next, most significant bit first. The data is latched in on the rising edge of the clock. Each address bit must be stable while the clock level is high.

After the last bit of the address bit is sent, the master releases the data line high (through a pull-up resistor). Then the master sends an acknowledge clock pulse. If the LM4681 has received the address correctly, then it holds the data line low during the clock pulse. If the data line is not held low during the acknowledge clock pulse, then the master should abort the rest of the data transfer to the LM4681.

The 8 bits of data are sent next, most significant bit first. Each data bit should be valid while the clock level is stable high.

After the data byte is sent, the master must check for another acknowledge to see if the LM4681 received the data.

If the master has more data bytes to send to the LM4681, then the master can repeat the previous two steps until all data bytes have been sent.

The "stop" signal ends the transfer. To signal "stop", the data signal goes high while the clock signal is high. The data line should be held high when not in use.

SPI Interface

The LM4681's serial control interface is compatible with SPI signals and protocols. When using SPI signals, the ADR pin is the input for the SPI ENABLE signal, the SDA pin is the input for the SPI CLOCK signal, and the SDA pin is the SPI DATA input.

I²C/SPI Interface Power Supply Pin (I²C V_{DD})

The LM4681's I²C/SPI interface is powered up through the I²C/SPI V_{DD} pin. The LM4681's I²C/SPI interface operates at a voltage level set by the I²C/SPI V_{DD} pin which can be set independent to that of the main power supply pin V_{DD}. This is ideal whenever logic levels for the I²C/SPI interface are dictated by a microcontroller or microprocessor that is operating at a lower supply voltage than the main battery of a portable system.

I²C Timing Diagrams

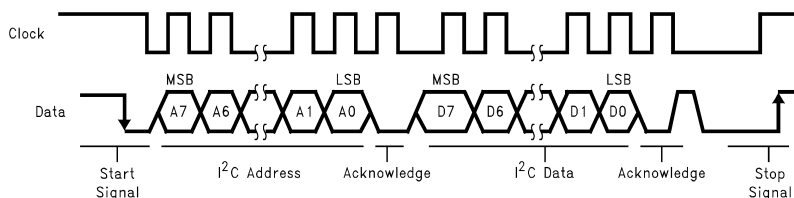


Figure 36. I²C Bus Format

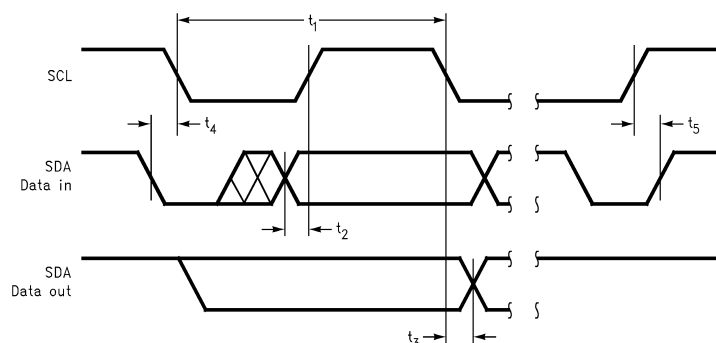
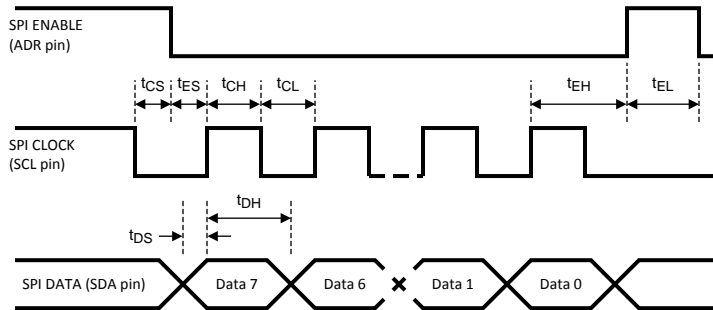


Figure 37. I²C Timing Diagram

SPI Timing Diagram



SPI Operational Requirements

1. The maximum clock rate is 5MHz for the CLK pin.
2. CLK must remain logic-high for at least 100ns (t_{CH}) after the rising edge of CLK, and CLK must remain logic-low for at least 100ns (t_{CL}) after the falling edge of CLK.
3. Data bits are written to the DATA pin with the most significant bit (MSB) first.
4. The serial data bits are sampled at the rising edge of CLK. Any transition on DATA must occur at least 50ns (t_{DS}) before the rising edge of CLK. Also, any transition on DATA must occur at least 50ns (t_{DH}) after the rising edge of CLK and stabilize before the next rising edge of CLK.
5. ENABLE should be logic-low only during serial data transmission.
6. ENABLE must be logic-low at least 50ns (t_{ES}) before the first rising edge of CLK, and ENABLE has to remain logic-low at least 50ns (t_{EH}) after the eighth rising edge of CLK.
7. If ENABLE remains logic-high for more than 50ns before all 8 bits are transmitted then the data latch will be aborted.
8. If ENABLE is logic-low for more than 8 CLK pulses then only the first 8 data bits will be latched and activated at rising edge of eighth CLK.
9. ENABLE must remain logic-high for at least 50ns (t_{EL}).
10. Coincidental rising or falling edges of CLK and ENABLE are not allowed. If CLK is to be held logic-high after the data transmission, the falling edge of CLK must occur at least 50ns (t_{CS}) before ENABLE transitions to logic-low for the next set of data.

Volume Control

The internal Stereo Volume Control is set by changing bits 0 through 4 in the SPI interface, as shown in [Table 4](#) below.

Table 4. Volume Control Settings

Gain (dB)		Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
HP Outputs	Class D Outputs					
-64.94	-48.03	0	0	0	0	0
-64.94	-48.03	0	0	0	0	1

Table 4. Volume Control Settings (continued)

Gain (dB)		Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
HP Outputs	Class D Outputs					
-56.94	-36.03	0	0	0	1	0
-47.94	-31.03	0	0	0	1	1
-42.94	-26.03	0	0	1	0	0
-37.94	-21.03	0	0	1	0	1
-33.94	-17.03	0	0	1	1	0
-31.94	-15.03	0	0	1	1	1
-28.94	-12.03	0	1	0	0	0
-25.94	-9.03	0	1	0	0	1
-22.94	-6.03	0	1	0	1	0
-20.94	-4.03	0	1	0	1	1
-18.94	-2.03	0	1	1	0	0
-16.94	-0.03	0	1	1	0	1
-14.94	1.97	0	1	1	1	0
-12.94	3.97	0	1	1	1	1
-10.94	5.97	1	0	0	0	0
-8.94	7.97	1	0	0	0	1
-6.94	9.97	1	0	0	1	0
-4.94	11.97	1	0	0	1	1
-2.94	13.97	1	0	1	0	0
-0.94	15.97	1	0	1	0	1
1.06	17.97	1	0	1	1	0
3.06	19.97	1	0	1	1	1
6.06	22.97	1	1	0	0	0
7.07	23.97	1	1	0	0	1
8.06	24.97	1	1	0	1	0
9.06	25.97	1	1	0	1	1
10.06	26.97	1	1	1	0	0
11.06	27.97	1	1	1	0	1
12.06	28.97	1	1	1	1	0
13.06	29.97	1	1	1	1	1

Application Hints

SUPPLY BYPASSING

Correct power supply bypassing has two important goals. The first is to reduce noise on the power supply lines and minimize deleterious effects that the noise may cause to the amplifier's operation. The second is to help stabilize an unregulated power supply and to improve the supply's transient response under heavy current demands. These two goals require different capacitor value ranges. Therefore, various types and values are recommended for supply bypassing. For noise de-coupling, generally small ceramic capacitors (0.01 μ F to 0.1 μ F) are recommended. Larger value (1 μ F to 10 μ F) tantalum capacitors are needed for the transient current demands. These two capacitors in parallel will do an adequate job of removing most noise from the supply rails and providing the necessary transient current. These capacitors should be placed as close as possible to each IC's supply pin(s) using leads as short as possible.

The LM4681 has two different set of V_{DD} pins: a set for power V_{DD} (PV_{DD}) and a set for signal V_{DD} (SV_{DD}). The parallel combination of the low value ceramic (0.1 μ F) and high value tantalum (10 μ F) should be used to bypass the PV_{DD} pin. A small value (0.1 μ F) ceramic or tantalum can be used to bypass the SV_{DD} pin.

OUTPUT STAGE FILTERING

The LM4681 requires a low pass filter connected between the amplifier's bridge output and the load. [Figure 1](#) shows the recommended LC filter. A minimum value of 27 μ H is recommended. As shown in [Figure 1](#), using the values of the components connected between the amplifier BTL outputs and the load achieves a 2nd-order lowpass filter response with a -3dB cutoff frequency of 25kHz.

THD+N MEASUREMENTS AND OUT OF AUDIO BAND NOISE

THD+N (Total Harmonic Distortion plus Noise) is a very important parameter by which all audio amplifiers are measured. Often it is shown as a graph where either the output power or frequency is changed over the operating range. A very important variable in the measurement of THD+N is the bandwidth-limiting filter at the input of the test equipment. Class D amplifiers, by design, switch their output power devices at a much higher frequency than the accepted audio range (20Hz - 20kHz). Alternately switching the output voltage between V_{DD} and GND allows the LM4681 to operate at much higher efficiency than that achieved by traditional Class AB amplifiers. Switching the outputs at high frequency also increases the out-of-band noise. Under normal circumstances the output lowpass filter significantly reduces this out-of-band noise. If the low pass filter is not optimized for a given switching frequency, there can be significant increase in out-of-band noise. THD+N measurements can be significantly affected by out-of-band noise, resulting in a higher than expected THD+N measurement. To achieve a more accurate measurement of THD, the test equipment's input bandwidth of the must be limited. Some common upper filter points are 22kHz, 30kHz, and 80kHz. The input filter limits the noise component of the THD+N measurement to a smaller bandwidth resulting in a more real-world THD+N value.

REVISION HISTORY

Rev	Date	Description
1.0	2/09/06	Initial release.
1.1	2/10/06	Edited the PSRR Typical values in the Elect. Char table.
1.2	3/08/06	Did few texts (Gen Desc section) clean-up, then re-released D/S to the WEB.
1.3	3/17/06	Changed the typo under PSRR (Conditions-Vripple from 20mVp-p to 200mVp-p) in the EC Char table, then re-released D/S to the WEB (per KH).
E	04/09/13	layout of National Data Sheet to TI format

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