

VM6150E Series

2, 4 or 8-CHANNEL, 5-VOLT, MAGNETO-RESISTIVE HEAD, READ/WRITE PREAMPLIFIER with SERVO WRITE

# **PRELIMINARY**

August, 1997

## 970801

# **FEATURES**

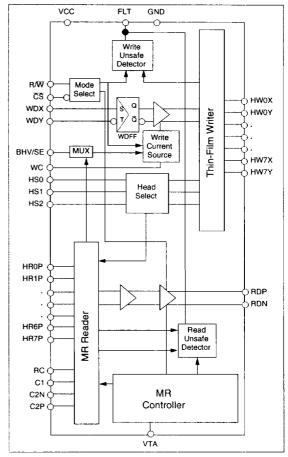
- General
  - Designed for Use With Four-Terminal MR Heads
  - Bandwidth = 160 MHz Typical
  - Operates from a Single +5 Volt Power Supply
  - Fault Detection Capability
  - Available in a Plastic TQFP Package
- · High Performance Reader
  - Current Bias / Current Sense Architecture
  - MR Bias Current Range 6- 12 mA
  - Read Voltage Gain = 250 V/V Typical (R<sub>MR</sub> = 40Ω)
  - Input Noise =  $0.75 \text{ nV}/\sqrt{\text{Hz}}$  Typical (R<sub>MR</sub> =  $40\Omega$ )
  - Thermal Asperity Detection and Fast Recovery Compensation
  - Dual Reader Input with One Side Grounded Externally
- High Speed Writer
  - Write Current Range = 10 40 mA
  - Rise Time = 2.2ns Typical (L<sub>H</sub> = 150 nH, l<sub>w</sub> = 35 mA)
  - Multi-Channel Servo Write
  - Optional WDFF

## **DESCRIPTION**

The VM6150E is a high-performance read/write preamplifier designed for use with 4-terminal magneto-resistive recording heads. The VM6150E operates from +5V power supply. This device provides write current to the write current drivers, DC bias current for the MR head, read and write fault detect, and multichannel servo write. This device also provides low voltage power supply detection, power saving idle mode, and an optional write data flip-flop for NRZ and NRZI data.

Please consult VTC for other channel-count availability.

## **BLOCK DIAGRAM**



## **ABSOLUTE MAXIMUM RATINGS**

Power Supply:
V <sub>CC</sub> 0.3V to +7V
Write Current I <sub>w</sub> 60mA
Input Voltages:
Digital Input Voltage V <sub>IN</sub> GND -0.3V to (V <sub>CC</sub> + 0.3)V
Head Port Voltage V <sub>H</sub> GND -0.3V to (V <sub>CC</sub> + 0.3)V
Output Current:
RDP, RDN: I <sub>o</sub> 10mA
Junction Temperature150°C
Storage Temperature T <sub>sig</sub> 65° to 150°C
Thermal Characteristics:
48-lead TQFP, Θ <sub>JA</sub> (Still Air)
48-lead TQFP, Θ <sub>JC</sub>

#### **RECOMMENDED OPERATING CONDITIONS**

Power Supply Voltage:	
V <sub>cc</sub>	+5V ± 10%
Junction Temperature (T <sub>J</sub> )	25°C to 125°C

## **Read Mode**

In the read mode, the circuit operates as a low noise, singleended amplifier which senses resistance changes in the MR element which correspond to flux changes on the disk.

The magnitude of the MR bias current is programmed by an external resistor with an external current source. VTC recommends that the resistor (setting some nominal I<sub>MR</sub>) be placed near the part to limit parasitics. The reader has a current gain of 20 mA/mA.

A "high" TTL level applied to R/W (along with the appropriate TTL level on the CS line) places the preamp in the read mode and activates the read unsafe detection circuitry (see Table 1).

The VM6150E uses a current bias, current sense architecture. The output of the read preamp is differential.

## BHV (Buffered Head Voltage)

An amplified representation of the MR bias voltage is presented at the BHV/SE pin (in non-servo modes only). This voltage is defined by the equation:

$$V_{BHV} = 5(I_{MR} \times R_{MR}) \tag{eq. 1}$$

## Thermal Asperity Detection and Compensation

A thermal asperity (caused by the collision of the MR element with the media) is characterized by a large amplitude disturbance in the readback signal followed by an exponential decay (See Figure 1).

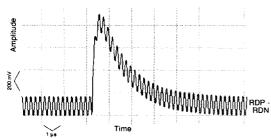


Figure 1: Thermal Asperity Event

Recovery from this large disturbance in the data path can take a relatively large amount of time (typically several microseconds) without detection and correction. The VM6150E implements both a programmable detection threshold and an automatic fast recovery for such disturbances.

#### Detection Threshold

The threshold for thermal asperity detection is programmable using the VTA pin (which sits at a nominal voltage of 2V) and is governed by the following equation:

$$V_{TADT} = k_{VTA} \times I_{VTA}$$
 (eq. 2)

 $V_{TADT}$  represents the TA detection threshold at which the RDP/RDN output exceeds the baseline level (in mV).

k<sub>VTA</sub> represents the VTA programming constant of 350 mV/mA. l<sub>VTA</sub> represents the programmed current flowing out of the VTA pin (in mA).

This threshold has a range from 100mV to 500mV (pk).

## Fast Recovery Compensation

A Fast Recovery Compensation is automatically activated after a thermal asperity is detected (the programmed threshold is exceeded). This compensation raises the nominal 250 KHz lower -3dB corner frequency to approximately 1.5 MHz until the RDP-RDN output baseline is restored (see Figure 2).

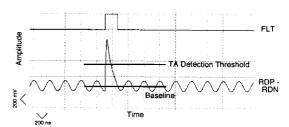


Figure 2: TA Detection and Compensation

This adjustment allows the preamp to reach its DC operating point rapidly after a thermal asperity occurrence (ensuring complete output recovery within nanoseconds rather than microseconds). After the RDP-RDN output baseline is restored, the preamp reinstates the lower -3dB corner frequency.

# Fault Detection

In the read mode, a high on the FLT line indicates a thermal asperity fault condition. The thermal asperity fault condition takes the FLT line high when the detection threshold is reached and returns low when RDP-RDN returns to within 20mV of its DC operating point.

An MR open head fault condition is detected but not reported on the FLT line. The voltage on the loop-compensation capacitor (C1) is clamped to provide MR open head protection (until another head is selected or a mode change is initiated).

#### Write Mode

In the write mode, the circuit operates as a thin film head write current switch, driving the thin film write element of the MR head. The magnitude of the write current is programmed by an external resistor with an external current source. VTC recommends that the resistor (setting some nominal  $I_w$ ) be placed near the part to limit parasitics. The writer has a current gain of 20 mA/mA.

A "low" TTL level applied to  $R/\overline{W}$  (along with the appropriate TTL level on the  $\overline{CS}$  line) places the preamp in the write mode (see Table 1). The write data (PECL) signals on the WDX and WDY lines drive the optional internal flip-flop which drives the current switch to the thin film writer. Write current polarity is defined in Figures 3 and 4.

## Fault Detection

In the write mode, a high on the FLT line indicates an open head write unsafe fault condition.

A low supply fault condition is detected but not reported on the FLT line. The write current source internal to the chip is shutdown and no current flows to any head.

## Servo Write Mode

In the servo write mode, two channels of the VM6150E are written simultaneously.

Pulling the BHV/SE pin high to VCC (along with the appropriate TTL levels on the  $\overline{CS}$ ,  $R/\overline{W}$  and HS2 lines) places the preamp in servo write mode (see Table 1). The TTL levels applied to the HS0 - HS1 pins determine which heads are written (see Table 2).

Note: The servo write function cannot be used to do a DC erase or the maximum power dissipation will be exceeded.

# Servo Verify Read Mode

In the servo verify read mode, the R/W pin is pulled high (read mode) to allow the VM6150E to read while still in servo mode (see Table 1). This allows verification of a servo write without leaving servo mode. Note that the standard (non-servo) head select table is used in this mode.

Table 1: Mode Select

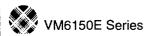
CS	R/W	HS2	BHV/SE	DESCRIPTION
0	1	Х	monitor	Read mode
0	0	х	monitor if desired	Write mode
0	0	1	pulled high (to VCC)	Servo mode
0	1	x	pulled high (to VCC)	Servo Verify Read mode (reference the non-servo head select table)
1	Х	Х	X	Idle mode

Table 2: Servo Mode Head Select

HS1	HS0	HEADS
0	0	0 and 1
0	1	2 and 3
1	0	4 and 5
1	1	6 and 7

Table 3: Head Select (non-servo)

HS2	HS1	HS0	HEAD
0	0	0	0
0	0	1	1
0	1	0	2
0	1	1	3
1	0	0	4
1	0	1	5
1	1	0	6
1	1	1	7



# PIN\_FUNCTION LIST AND DESCRIPTION

1)	CS	(1)	Chip Select: A TTL low level enables the device. Pin defaults high (disabled).
2)	R∕W	(I*)	Read/Write:
			A TTL low level enables write mode. Pin defaults high (read mode).
3)	HS0-HS2	(1*)	Head Select:
			Selects one of the eight heads.
4)	BHV/SE	(I/O)	Buffered Head Voltage/Servo Enable:
			In non-servo mode, the preamp drives this pin to an analog voltage representing the buffered head voltage (BHV).
			When externally pulled to VCC, the preamp enters servo write mode.
5)	FLT	(O)	Fault/Thermal Asperity Detect:
٠,		(0)	In Write mode, a high level indicates an open head write fault (write unsafe condition).
			In Read mode, a high level indicates a thermal asperity fault.
6)	VTA	(1)	Thermal Asperity programmable input.
7)	WDX, WDY	(!*)	Differential Pseudo-ECL write data inputs.
8)	HR0P-HR7P	(1)	MR head connections, positive end.
9)	HW0X-HW7X	(O)	Thin-Film write head connections, positive end.
10)	HW0Y-HW7Y	(O)	Thin-Film write head connections, negative end
11)	RDP, RDN	(O)	Read Data:
			Differential read signal outputs.
12)	WC	(*)	Write current reference pin:
			Sets the magnitude of write current.
13)	RC	(*)	MR bias current reference pin:
			Sets the magnitude of MR bias current.
,	C2	-	Noise bypass capacitors.
,	C1	•	Compensation capacitor for the MR head bias current loop.
,	GND	-	Ground
17)	VCC	-	+5.0V supply

<sup>\*</sup> When more than one device is used, these signals can be wire OR'ed together

I = Input pin

O = Output pin

STATIC (DC) CHARACTERISTICS
Recommended operating conditions apply unless otherwise specified.

PARAMETER	SYM	CONDITIONS	MIN	TYP	MAX	UNITS
		Read Mode, I <sub>MR</sub> = 10mA		90	120	
	,	Write Mode, I <sub>w</sub> = 20mA (read bias active)		105	160	4
V <sub>CC</sub> Power Supply Current	lcc	Idle Mode		8	15	mA
		Servo Mode, I <sub>w</sub> = 20mA, One bank of two heads		135	175	
		Read Mode, I <sub>MR</sub> = 10mA		450	660	
		Write Mode, I <sub>w</sub> = 20mA		600	880	
Power Dissipation	P <sub>d</sub>	Idle Mode		40	83	mW
		Servo Mode, I <sub>w</sub> = 20mA, One bank of two heads		675	965	
Input High Voltage	V <sub>IH</sub>	PECL	V <sub>cc</sub> - 1.0		V <sub>cc</sub> - 0.7	٧
input High voitage		TTL	2.0		V <sub>cc</sub> + 0.3	V
Input Low Voltage		PECL	V <sub>IH</sub> - 1.5		V <sub>IH</sub> - 0.25	٧
input Low voltage	V <sub>IL</sub>	TTL	-0.3		0.8	٧
Input High Current	,	PECL			120	μА
Input High Current	I <sub>iH</sub>	TTL, V <sub>H</sub> = 2.7V			80	μΑ
Innut Low Current		PECL			100	μА
Input Low Current	I <sub>IL</sub>	TTL, V <sub>IL</sub> = 0.4V	-160			μА
Output High Voltage	V <sub>OH</sub>	FLT: I <sub>OH</sub> = -400μA	2			٧
Output Low Voltage	V <sub>OL</sub>	FLT: I <sub>OL</sub> = 400μA			0.5	٧
V <sub>cc</sub> Fault Threshold	V <sub>DTH</sub>	l <sub>w</sub> < 200μA	3.5	3.9	4.2	V



# **READ CHARACTERISTICS**

Recommended operating conditions apply unless otherwise specified.

PARAMETER	SYM	CONDITIONS	MIN	TYP	MAX	UNITS
MR Head Current Range	I <sub>MR</sub>		6	9	12	mA
MR Bias Reference Voltage	V <sub>RC</sub>	$2k < R_{RC} < 4k\Omega$		2.0		V
IRC to MR Bias Current Gain	A <sub>IMR</sub>	6mA < I <sub>MR</sub> < 12mA	18.4	20	21.6	mA/mA
Unselected MR Head Current					100	μА
Differential Voltage Gain	Av	$\begin{split} &V_{\text{IN}} = 1 \text{mV}_{pp} \text{ @ } 10 \text{MHz, R}_{\text{L}}(\text{RDP,}\\ &\text{RDN)} = 1 \text{k}\Omega, \text{I}_{\text{MR}} = 9 \text{mA,}\\ &\text{R}_{\text{MR}} = 40 \Omega \end{split}$		250		V/V
Passband Upper -3dB Frequency Limit	f <sub>HA</sub>	R <sub>MR</sub> = 40Ω; L <sub>MR</sub> = 10nH		160		MHz
Passband Lower -3dB Frequency Limit	f <sub>LR</sub>	$R_{MR} = 40\Omega; C_1 = 0.022 \mu F$		625		KHz
Equivalent Input Noise	e <sub>n</sub>	R <sub>MR</sub> = 40Ω; I <sub>MR</sub> = 9mA; 1 < f < 40 MHz		0.75		nV/√ <del>Hz</del>
I <sub>MR</sub> · R <sub>MR</sub>	V <sub>MR</sub>		240		450	mV
Input Resistance	R <sub>IN</sub>	I <sub>MR</sub> = 9mA		3.2		Ω
Dynamic Range	DR	AC input V where A <sub>V</sub> falls to 90% of its value at V <sub>IN</sub> = 1mV <sub>pp</sub> @ f = 5 MHz	TBD	5		mV <sub>pp</sub>
Power Supply Rejection Ratio	PSRR	$100 \text{mV}_{pp}$ on $V_{CC}$ or GND, $I_{MR} = 9 \text{mA}$ , $R_{MR} = 40 \Omega$ , $1 < f < 30 \text{ MHz}$		33		dB
Channel Separation	cs	Unselected Channels: V <sub>IN</sub> = 100mV <sub>pp</sub> , 1 < f < 40 MHz	40			dB
Output Offset Voltage	Vos	$I_{MR} = 9mA, R_{MR} = 40\Omega$	-300		300	mV
Common Mode Output Voltage	V <sub>OCM</sub>	Read Mode		V <sub>cc</sub> - 2.7		V
Common Mode Output Voltage Difference	ΔV <sub>OCM</sub>	V <sub>OCM</sub> (READ) - V <sub>OCM</sub> (WRITE)			300	mV
Single-Ended Output Resistance	R <sub>SEO</sub>	Read Mode			50	Ω
Output Current	l <sub>o</sub>	AC Coupled Load, RDP to RDN	1.5		×	mA
MD Used to Disk Contact Correct		Extended Contact, R <sub>DISK</sub> = 10MΩ			TBD	μА
MR Head-to-Disk Contact Current	DISK	Maximum Peak Discharge, $C_{DISK} = 300$ pF, $R_{DISK} = 10$ MΩ			TBD	mA
Buffered Head Voltage Gain	A <sub>BHV</sub>	Output range =  A <sub>BHV</sub> I <sub>MR</sub> R <sub>MR</sub> = 500mV to 2.5V;  BHV Source Current = 0-500μA	4.5	5.0	5.5	V/V
Thermal Asperity Reference Voltage	V <sub>VTA</sub>	0 < I <sub>VTA</sub> < 1.5mA		2		V
Thermal Asperity Programming Constant	k <sub>VTA</sub>	Threshold of 100mV to 500mV over baseline level of RDP/RDN		350		mV/mA



## WRITE CHARACTERISTICS

Recommended operating conditions apply unless otherwise specified.  $I_W = 35mA$ ,  $L_H = 150nH$ ,  $R_H = 25\Omega$ ,  $f_{DATA} = 5MHz$ .

PARAMETER	SYM	CONDITIONS	MIN	TYP	MAX	UNITS
Write Current Range	l <sub>w</sub>	(base to peak)	10		40	mA
WC Pin Voltage	V <sub>wc</sub>			2.0		V
I <sub>wc</sub> to Write Current Gain	Aı		18	20	22	mA/mA
Differential Head Voltage Swing	V <sub>DH</sub>	Open Head, V <sub>CC</sub> = 4.5V	6	7.5		V <sub>pp</sub>
Unselected Head Transition Current	I <sub>UH</sub>				50	μA <sub>pk</sub>
Differential Output Resistance	Ro	Internal Damping*		450*		Ω

<sup>\*</sup> An 800 Ohm damping resistor is a metal option.

# **SWITCHING CHARACTERISTICS**

Recommended operating conditions apply unless otherwise specified.

 $I_W = 35$ mA,  $L_H = 150$ nH,  $R_H = 25\Omega$ ,  $f_{DATA} = 5$ MHz.

PARAMETER	SYM	CONDITIONS	MIN	TYP	MAX	UNITS
Read to Write Mode	t <sub>RW</sub>	To 90% of write current		50		ns
Write to Read Mode	twn	RDP/RDN to within ± 30mV of final value			0.5	μѕ
CS to Read Mode	t <sub>CS</sub>	RDP/RDN to within ± 30mV of final value			10	μs
HS0 - HS3 to Any Head	t <sub>HS</sub>	RDP/RDN to within ± 30mV of final value; read mode		12	20	μs
CS to Unselect	t <sub>RI</sub>	To 10% of read envelope or write current			0.5	μs
Head Current Propagation Delay	t <sub>D3</sub>	From 50% points, WDX to I <sub>w</sub>		20	30	ns
Asymmetry	A <sub>SYM</sub>	Write Data has 50% duty cycle & 1ns rise/fall time; L <sub>H</sub> = 0; R <sub>H</sub> = 0	<u></u>		0.5	ns
Rise/Fall Time	t <sub>r</sub> / t <sub>f</sub>	I <sub>w</sub> = 35mA; L <sub>H</sub> = 150nH; 10 - 90%		2.2	3	ns

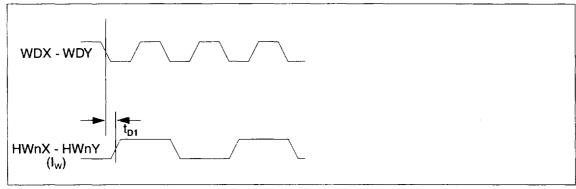


Figure 3: Write Mode Timing Diagram with Flip-Flop Active

Note: The write current polarity is toggled on each high to low transition of the expression (WDX - WDY).

A preceding read operation initializes the WDFF so that upon entering the write mode, current flows into the "X" port.

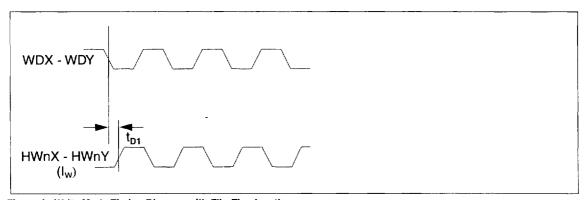
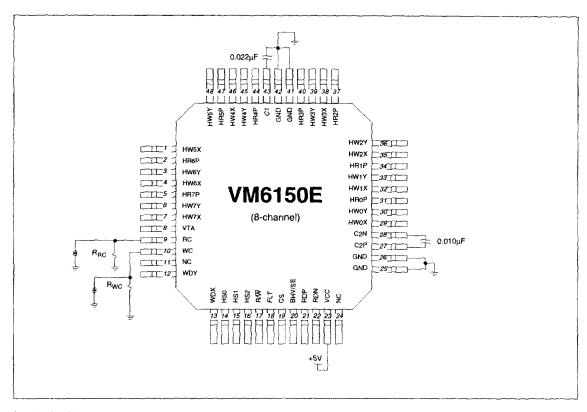


Figure 4: Write Mode Timing Diagram with Flip-Flop Inactive

Note: The write current polarity is defined by the levels of WDX and WDY (shown in the expression WDX - WDY). For WDX>WDY current flows into the "X" port; for WDX<WDY current flows into the "Y" port.



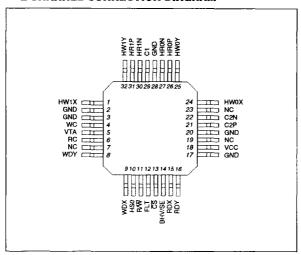
# **Application Notes:**

- $I_{MR}$  = MR Bias Current =  $20 \cdot I_{RC}$   $I_{W}$  = Write Current =  $20 \cdot I_{WC} (1 + R_H/R_D)$ 
  - R<sub>H</sub> represents the Head Series Resistance, R<sub>D</sub> represents the Damping Resistance
- $V_{CC} = +5V$ , GND = Ground



# VM6152E

## 2-CHANNEL CONNECTION DIAGRAM



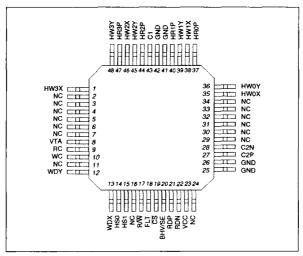
2-Channel 32-lead TQFP (.8mm pitch)

# Specific CHARACTERISTICS

See the general data sheet for common specification information.

# VM6154E

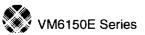
## **4-CHANNEL CONNECTION DIAGRAM**



4-Channel 48-lead TQFP

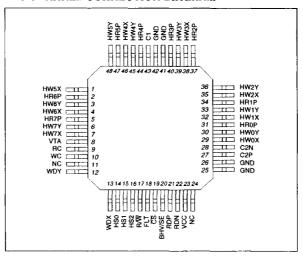
# Specific CHARACTERISTICS

See the general data sheet for common specification information.



# VM6158E

# **8-CHANNEL CONNECTION DIAGRAM**



8-Channel 48-lead TQFP

# **Specific CHARACTERISTICS**

See the general data sheet for common specification information.