

■ Supply, V_{CC}

Supply Voltage Range	-40°C ≤ T _A ≤ 105°C	6.5		15.5	VDC
	-40°C ≤ T _A ≤ 25°C	6.5		24.0	VDC
	Transient Pulse, 100ms			35.0	VDC
Overvoltage Shutdown		16		23	V

■ Speed Sensor Input, SENSOR

Input Frequency Range			0.2	1.0	kHz
Hysteresis		300	500		mVDC
Input Voltage Range		0		V _{CC}	VDC
Input Clamp Current	I Clamp at V _{IN} = 0 VDC		-0.4	-5.0	mA

■ Divider Select Input, SELECT

Logic 0 Input Voltage				100	mVDC
Logic 0 Input Current	0V ≤ V _{IN} ≤ 100mV		-1	-100	μA

■ Coil Output Drivers

Coil Load	+25°C	198	210	222	Ω
Coil Resistance Temperature Coefficient				0.35	%/°C
De-Energized Coil Leakage Current				±100	μA

■ Short Circuit Protection

Short Circuit Threshold I Coil A + I Coil B			275	400	mA
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* Voltage across the coils shall be measured at the specific voltages, but shall also be within linearly interpolated limits.

8L PDIP

1	Gnd	Ground connection.
3	COILA-	Output stage, when active, this pin supplies current to COIL A.
5	SELECT	Selects divide by 1 or divide by 2 mode.
7	COILB+	Output stage, when active, this pin supplies current to COIL B.

Speed Sensor Input

SENSOR is a PNP comparator input which accepts a sine wave input or a square wave input. This input is protected from excursions above V_{CC} as well as any below ground, as long as the current is limited to 1.5mA. It has an active clamp set to zero volts to prevent negative input voltages from disrupting normal operation. The sensor input can withstand 150V_{DC} as long as the input current is limited to 1.5mA max using a series resistor of 100k Ω .

Coil Driver Outputs

Simultaneously energizing the source and sink on either leg is not permitted. i.e. Q1 & Q2 or Q3 & Q4 cannot be energized simultaneously.

Circuit function is not affected by inductive transients due to coil loads as specified in Transition States section.

The transition states occur as indicated in Table 1 without any intermediate states permitted.

Table 1: Transition States

Output State Table		
State	Coil A	Coil B
0	+	+
1	OFF	+
2	-	+
3	-	OFF
4	+	-
5	OFF	-
6	+	-
7	-	OFF

The polarity definition for the coil driver outputs is as follows:

Polarity	Connect Coil +	Connect Coil -
Positive (+)	V _{CC}	Gnd
Negative (-)	Gnd	V _{CC}

Coil Driver Select Input

The speed sensor input frequency is divided by one or divided by two by connecting the divider select input, (Pin 5) as follows:

- Logic 0 = divide by 2
- Logic 1 = divide by 1

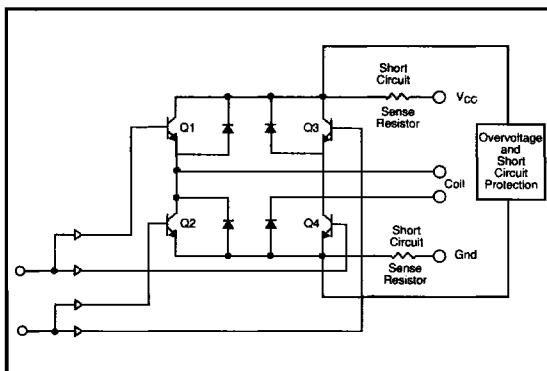


Figure 1: Coil Driver Output

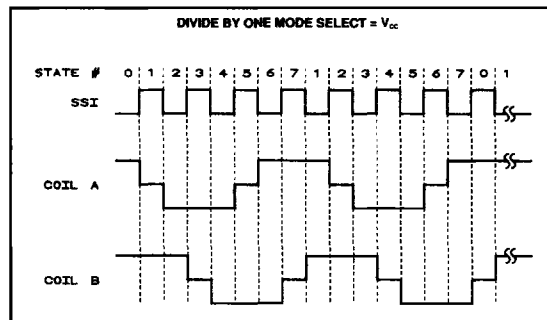


Figure 2: Divide by 1 SELECT Mode

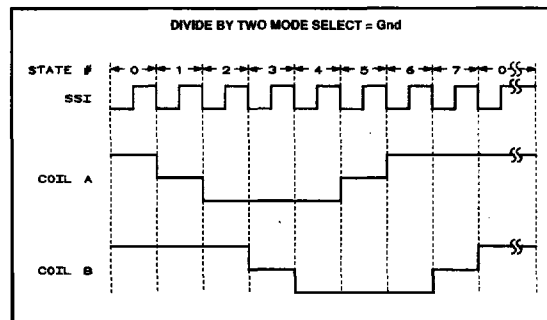
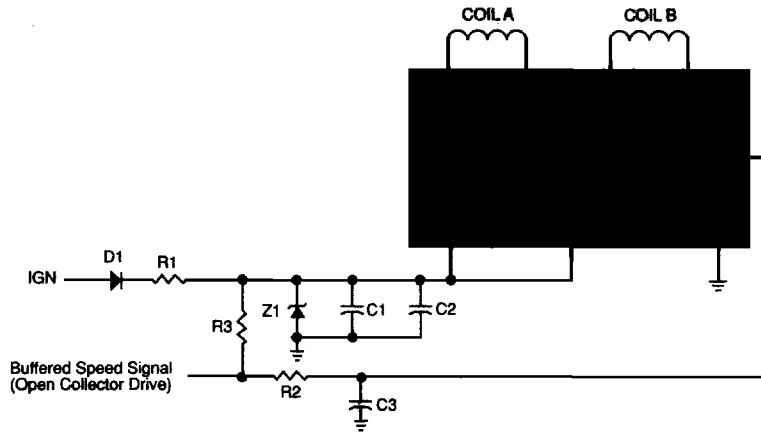


Figure 3: Divide by 2 SELECT Mode

- C1 - 10 μ F
- C2 - 0.1 μ F
- C3 - 0.01 μ F
- R1 - 3.9 Ω , 500mW
- R2 - 100k Ω
- R3 - 15k Ω
- D1 - 1A, 600PIV
- Z1 - 50V, 500mW
- COIL A - 210 \pm 12 Ω , 80mH
- COIL B - 210 \pm 12 Ω , 80mH



Package Specifications

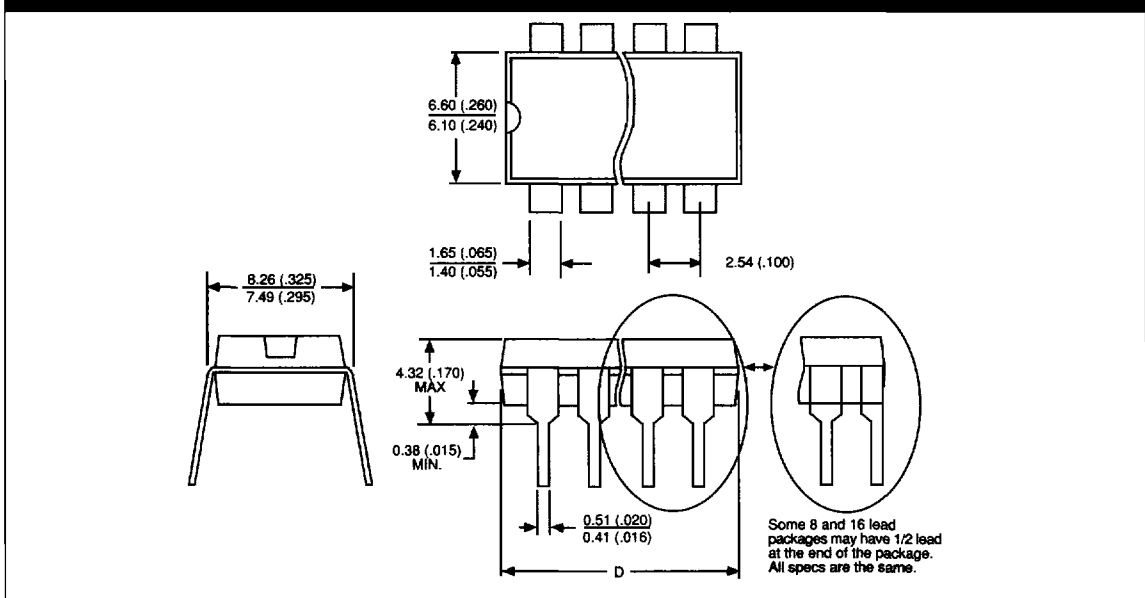
PACKAGE DIMENSIONS IN mm (INCHES)

Lead Count	D			
	Metric		English	
	Max	Min	Max	Min
8L PDIP	9.40	9.14	.370	.360

PACKAGE THERMAL DATA

Thermal Data		8 Lead PDIP	
R θ JC	typ	52	$^{\circ}$ C/W
R θ JA	typ	100	$^{\circ}$ C/W

8 Lead PDIP



Ordering Information

Part Number	Description
CS-8441N8	8 Lead PDIP