



---

## DATA SHEET

---

# gmZAN1

Flat Panel Monitor Controller IC

**C0021-DAT-01D**

January 2001

---

### Genesis Microchip

165 Commerce Valley Drive West • Thornhill • ON • Canada • L3T 7V8 • Tel: (905)889-5400 • Fax: (905)889-5422  
2150 Gold Street • Alviso • CA • USA • 95002 • Tel: (408)262-6599 • Fax: (408)262-6365  
4F, No. 24, Ln 123, Sec 6, Min-Chung E. Rd. • Taipei • Taiwan • Tel: (2) 2791-0118 • Fax: (2) 2791-0196  
[www.genesis-microchip.com](http://www.genesis-microchip.com)      [info@genesis-microchip.com](mailto:info@genesis-microchip.com)

**Document History:**

<b>Revision</b>	<b>Description</b>	<b>Date</b>
DAT-0021-A	Internal Release	Dec. 1999
C0021-DAT-01B	Updated Section 3	Oct. 2000
C0021-DAT-01C	Modified Table 10 in Section 3.3.1 and Table 20 in Section 3.	Dec. 2000
C0021-DAT-01D	Added On-chip TCLK Oscillator description in Section 2.9	Jan. 2001

**Related Documents:**

<b>Doc Number</b>	<b>Title</b>
C0021-PBR-01D	gmZAN1 Product Brief
DAT-0018	gmB120 Data Sheet

**Copyright 2001****Genesis Microchip Inc.****All Rights Reserved**

Genesis Microchip Inc. reserves the right to change or modify the information contained herein without notice. It is the customer's responsibility to obtain the most recent revision of the document. Genesis Microchip Inc. makes no warranty for the use of its products and bears no responsibility for any errors or omissions which may appear in this document.

## Table of Contents

<b>1. OVERVIEW</b> .....	<b>1</b>
1.1 <b>FEATURES</b> .....	<b>2</b>
1.2 <b>PIN OUT DIAGRAM</b> .....	<b>3</b>
1.3 <b>PIN DESCRIPTION</b> .....	<b>4</b>
1.4 <b>SYSTEM-LEVEL BLOCK DIAGRAM</b> .....	<b>9</b>
1.5 <b>OPERATING MODES</b> .....	<b>10</b>
1.5.1 Native.....	10
1.5.2 Slow DCLK.....	10
1.5.3 Zoom.....	11
1.5.4 Downscaling.....	11
1.5.5 Destination Stand Alone.....	11
1.5.6 Source Stand Alone.....	11
<b>2. FUNCTIONAL DESCRIPTION</b> .....	<b>12</b>
2.1 <b>OVERALL ARCHITECTURE</b> .....	<b>12</b>
2.2 <b>CLOCK RECOVERY CIRCUIT</b> .....	<b>12</b>
2.2.1 Sampling Phase Adjustment.....	14
2.2.2 Source Timing Generator.....	14
2.3 <b>ANALOG-TO-DIGITAL CONVERTER</b> .....	<b>15</b>
2.3.1 Pin Connection.....	15
2.3.2 Sync. Signal Support.....	17
2.3.3 Display Mode Support.....	17
2.4 <b>INPUT TIMING MEASUREMENT</b> .....	<b>17</b>
2.4.1 Source Timing Measurement.....	17
2.4.2 IRQ Controller.....	18
2.5 <b>DATA PATH</b> .....	<b>19</b>
2.5.1 Scaling Filter.....	20
2.5.2 Gamma Table.....	20
2.5.3 RGB Offset.....	20
2.5.4 Panel Data Dither.....	20
2.5.5 Panel Background Color.....	20
2.6 <b>PANEL INTERFACE</b> .....	<b>20</b>
2.6.1 TFT Panel Interface Timing Specification.....	21
2.6.2 Power Manager.....	24
2.6.3 Panel Interface Drive Strength.....	26
2.7 <b>HOST INTERFACE</b> .....	<b>26</b>
2.7.1 Serial Communication Protocol.....	27
2.7.2 Multi-Function Bus (MFB).....	28
2.8 <b>ON-SCREEN DISPLAY CONTROL</b> .....	<b>29</b>
2.8.1 OSD Color Map.....	29



- 2.8.2 On-Chip OSD Controller ..... 29
- 2.8.3 Built-in OSD Fonts ..... 31
- 2.8.4 External OSD Support ..... 32
- 2.9 ON-CHIP TCLK OSCILLATOR ..... 34**
- 2.9.1 External Oscillator mode ..... 34
- 2.9.2 Internal Oscillator mode ..... 35
- 3. ELECTRICAL CHARACTERISTICS ..... 39**
- 4. ORDERING INFORMATION ..... 40**
- 5. MECHANICAL DIMENSIONS ..... 41**

## Table of Figures

FIGURE 1. GMZAN1 PIN DIAGRAM.....	3
FIGURE 2. TYPICAL STAND-ALONE CONFIGURATION .....	9
FIGURE 3. BLOCK DIAGRAM FOR GMZAN1 .....	12
FIGURE 4. CLOCK RECOVERY CIRCUIT .....	13
FIGURE 5. CAPTURE WINDOW .....	15
FIGURE 6. GMZAN1 DATA PATH.....	19
FIGURE 7. TIMING DIAGRAMS OF THE TFT PANEL INTERFACE (ONE PIXEL PER CLOCK) .....	23
FIGURE 8. DATA LATCH TIMING OF THE TFT PANEL INTERFACE .....	24
FIGURE 9. PANEL POWER SEQUENCE.....	25
FIGURE 10. TIMING DIAGRAM OF THE GMZAN1 SERIAL COMMUNICATION.....	27
FIGURE 11. SERIAL HOST INTERFACE DATA TRANSFER FORMAT .....	28
FIGURE 12. ON-CHIP OSD WINDOW LOCATION .....	31
FIGURE 13. BUILT-IN OSD FONTS .....	32
FIGURE 14. EXTERNAL OSD INTERFACE DATA LATCH TIMING.....	33
FIGURE 15. USING AN EXTERNAL OSCILLATOR .....	34
FIGURE 16. USING AN INTERNAL OSCILLATOR.....	36
FIGURE 17. INTERNAL OSCILLATOR OUTPUT AT TCLK .....	36
FIGURE 18. PARASITIC CAPACITANCE SOURCES .....	37
FIGURE 19. 160 PIN PQFP PACKAGE DIMENSIONS .....	41

## List of Tables

TABLE 1. ANALOG-TO-DIGITAL CONVERTER.....	4
TABLE 2. HOST INTERFACE (HIF) / EXTERNAL ON-SCREEN DISPLAY .....	5
TABLE 3. CLOCK RECOVERY / TIME BASE CONVERSION.....	6
TABLE 4. TFT PANEL INTERFACE.....	7
TABLE 5. TEST PINS.....	8
TABLE 6. VDD / VSS FOR CORE CIRCUITRY, HOST INTERFACE, AND PANEL/MEMORY INTERFACE.....	8
TABLE 7. CLOCK RECOVERY CHARACTERISTICS .....	14
TABLE 8. PIN CONNECTION FOR RGB INPUT WITH HSYNC/VSYNC .....	15
TABLE 9. PIN CONNECTION FOR RGB INPUT WITH COMPOSITE SYNC .....	16
TABLE 10. ADC CHARACTERISTICS .....	16
TABLE 11. INPUT TIMING PARAMETERS MEASURED BY THE STM BLOCK.....	18
TABLE 12. IRQ-GENERATION CONDITIONS .....	19
TABLE 13. GMZAN1 TFT PANEL INTERFACE TIMING.....	22
TABLE 14. PANEL INTERFACE PAD DRIVE STRENGTH .....	26
TABLE 15. GMZAN1 SERIAL CHANNEL SPECIFICATION.....	28
TABLE 16. PROGRAMMABILITY OF ON-CHIP OSD LOCATIONS .....	31
TABLE 17. PIN CONNECTION BETWEEN THE GMZAN1 AND AN EXTERNAL OSD CONTROLLER .....	32
TABLE 18. EXTERNAL OSD INTERFACE TIMING PARAMETERS .....	33
TABLE 19. TCLK SPECIFICATION.....	34
TABLE 20. ABSOLUTE RATINGS .....	39
TABLE 21. DC ELECTRICAL CHARACTERISTIC .....	39

## 1. OVERVIEW

Liquid crystal displays have advanced to the point of being comparable with CRT monitors in color capabilities, size, and resolution. In many applications, remote flat panel displays are more desirable than CRTs. However, supporting the multi-frequency capability of the CRT monitor on a fixed resolution flat panel display imposes a technical challenge. The gmZAN1 chip developed by Genesis Microchip Inc. provides a flat panel monitor solution that is compatible with today's CRT standards.

As shown Figure 2, the gmZAN1 has an integrated 135MHz ADC and a gmZ2 quality scaling engine, providing a high degree of integration for a simplified, cost effective design. Because the gmZAN1 is pin-compatible with the Genesis gmB120\*, it has all the features of the gmB120 plus many enhanced image processing features including 10-bit gamma correction, Adaptive Contrast Enhancement (ACE) filtering, Sync On Green (SOG), and an enhanced OSD.

A reference design is available to demonstrate the gmZAN1 solution.

\* Note that when using the gmZAN1 as a gmB120 replacement, pin 142 (XTAL) of the gmZAN1 must be left disconnected (floating).

## 1.1 Features

The gmZAN1 device utilizes Genesis' patented third-generation Advanced Image Magnification technology as well as a proven integrated ADC/PLL to provide excellent image quality within a cost-effective SVGA / XGA LCD monitor solution.

As a pin-compatible replacement for the gmB120, the gmZAN1 incorporates all of the gmB120 features plus many enhanced features; including 10-bit gamma correction, Adaptive Contrast Enhancement (ACE) filtering, Sync On Green (SOG), and an enhanced OSD.

### Features

- Fully integrated 135MHz 8-bit triple-ADC, PLL, and pre-amplifier
- gmZ2 scaling algorithm featuring new *Adaptive Contrast Enhancement (ACE)*
- On-chip programmable OSD engine
- Integrated PLLs
- 10-bit programmable gamma correction
- Host interface with 1 or 4 data bits
- Pin-compatible with gmB120
- **Integrated Analog Front End**
  - Integrated 8-bit triple ADC
  - Up to 135MHz sampling rates
  - No additional components needed
  - All color depths up to 24-bits/pixel are supported
- **High-Quality Advanced Scaling**
  - Fully programmable zoom
  - Independent horizontal / vertical zoom
  - Enhanced and adaptive scaling algorithm for optimal image quality
  - Recovery Mode / Native Mode
- **Input Format**
  - Analog RGB up to XGA 85Hz
  - Support for Sync On Green (SOG)
  - Support for composite sync modes

- **Output Format**

- Support for 8 or 6-bit panels (with high quality dithering)
- One or two pixel output format

- **Built In High-Speed Clock Generator**

- Fully programmable timing parameters
- On-chip PLLs generate clocks for the on-chip ADC and pixel clock from a single reference oscillator

- **Auto-Configuration / Auto-Detection**

- Phase and image positioning
- Input format detection

- **Operating Modes**

- Bypass mode with no filtering
- Multiple zoom modes:
  - with filtering
  - with adaptive (ACE) filtering

- **Integrated On-Screen Display**

- On-chip character RAM and ROM for better customization
- External OSD supported for greater flexibility
- Supports both landscape and portrait fonts
- Many other font capabilities including: blinking, overlay and transparency

### Package

- 160-pin PQFP

### Applications

- Multi-synchronous LCD monitors
- Other fixed-resolution pixelated display devices



### 1.3 Pin Description

Unless otherwise stated, unused input pins must be tied to ground, and unused output pins left open.

**Table 1. Analog-to-Digital Converter**

Pin	Name	In/Out	Drive Current (@10pF)	Description
77	ADC_VDD2			Digital power for ADC encoding logic. Must be bypassed with 0.1 uF capacitor to pin 78 (ADC_GND2)
78	ADC_GND2			Digital GND for ADC encoding logic. Must be directly connected to the digital system ground plane.
79	ADC_VDD1			Digital power for ADC clocking circuit. Must be bypassed with 0.1 uF capacitor to pin 80 (ADC_GND1)
80	ADC_GND1			Digital GND for ADC clocking circuit. Must be directly connected to the digital system ground plane.
81	SUB_GNDA			Dedicated pin for substrate guard ring that protects the ADC reference system. Must be directly connected to the analog system ground plane.
82	ADC_GNDA			Analog ground for ADC analog blocks that are shared by all three channels. Includes bandgap reference, master biasing and full scale adjust. Must be directly connected to analog system ground plane.
84	ADC_VDDA			Analog power for ADC analog blocks that are shared by all three channels. Includes bandgap reference, master biasing and full scale adjust. Must be bypassed with 0.1 uF capacitor to pin 82 (ADC_GNDA).
83	Reserved			For internal testing purpose only. Do not connect.
85	ADC_BGND A			Analog ground for the blue channel. Must be directly connected to the analog system ground plane.
88	ADC_BVDDA			Analog power for the blue channel. Must be bypassed with 0.1 uF capacitor to pin 85 (BGND A).
86	BLUE-	In		Negative analog input for the Blue channel.
87	BLUE+	In		Positive analog input for the Blue channel.
89	ADC_GGNDA			Analog ground for the green channel. Must be directly connected to the analog system ground plane.
92	ADC_GVDDA			Analog power for the green channel. Must be bypassed with 0.1 uF capacitor to pin 89 (ADC_GGNDA).
90	GREEN-	In		Negative analog input for the Green channel.
91	GREEN+	In		Positive analog input for the Green channel.
93	ADC_RGNDA			Analog ground for the red channel. Must be directly connected to the analog system ground plane.
96	ADC_RVDDA			Analog power for the red channel. Must be bypassed with 0.1 uF capacitor to pin 93 (ADC_RGNDA).
94	RED-	In		Negative analog input for the Red channel.
95	RED+	In		Positive analog input for the Red channel.

**Table 2. Host Interface (HIF) / External On-Screen Display**

Pin	Name	In / Out	Drive Current (@10pF)	Description
98	HFS	in		Host Frame Sync. Frames the packet on the serial channel.
103	HCLK	in		Clock signal input for the 3-wire serial communication.
99	HDATA	in/out	4 mA	Data signal for the 3-wire serial communication
100	RESETn	in		Resets the gmZAN1 chip to a known state when low.
101	IRQ	out	4 mA	Interrupt request output
115	OSD-HREF	out	4 mA	HSYNC output for an external OSD controller chip.
116	OSD-VREF	out	4 mA	VSYSN output for an external OSD controller chip.
117	OSD-Clk	out	8 mA	Clock output for an external OSD controller chip.
118	OSD-Data0	in		Data input 0 from an external OSD controller.
119	OSD-Data1	in		Data input 1 from an external OSD controller.
120	OSD-Data2	in		Data input 2 from an external OSD controller.
121	OSD-Data3	in		Data input 3 from an external OSD controller.
122	OSD-FSW	in		External OSD window display enable. Displays data from external OSD con troller when high.
123	MFB11	in/out	8 mA	Multi-Function Bus 11. One of twelve multi-function signals MFB[11:0].
124	MFB10	in/out	8 mA	Multi-Function Bus 10. One of twelve multi-function signals MFB[11:0].
102	MFB9	in/out	8 mA	Multi-Function Bus 9. One of twelve multi-function signals MFB[11:0]. Also used as HDATA3 in a 4-bit host interface configuration.
104	MFB8	in/out	8 mA	Multi-Function Bus 8. One of twelve multi-function signals MFB[11:0]. Also used as HDATA2 in a 4-bit host interface configuration.
105	MFB7	in/out	8 mA	Multi-Function Bus 7. One of twelve multi-function signals MFB[11:0]. Also used as HDATA1 in a 4-bit host interface configuration.
106	MFB6	in/out	8 mA	Multi-Function Bus 6. One of twelve multi-function signals MFB[11:0]. Internally pulled up. When externally pulled down (sampled at reset) the host interface is configured for 4 bits wide. In this configuration, MFB9:7 are used as HDATA3:1.
107	MFB5	in/out	8 mA	Multi-Function Bus 5. One of twelve multi-function signals MFB[11:0]. Internally pulled up. When externally pulled down (sampled at reset) the chip uses an external crystal resonator across pins 141 and 142, instead of an oscillator.
109	MFB4	in/out	8 mA	Multi-Function Bus 4. One of twelve multi-function signals MFB[11:0].
110	MFB3	in/out	8 mA	Multi-Function Bus 3. One of twelve multi-function signals MFB[11:0].
111	MFB2	in/out	8 mA	Multi-Function Bus 2. One of twelve multi-function signals MFB[11:0].
112	MFB1	in/out	8 mA	Multi-Function Bus 1. One of twelve multi-function signals MFB[11:0].
113	MFB0	in/out	8 mA	Multi-Function Bus 0. One of twelve multi-function signals MFB[11:0].

**Table 3. Clock Recovery / Time Base Conversion**

Pin	Name	In / Out	Drive Current (@10pF)	Description
125	DVDD			Digital power for Destination DDS (direct digital synthesizer). Must be bypassed with a 0.1 uF capacitor to digital ground plane.
127	DAC_DGND			Analog ground for Destination DDS DAC. Must be directly connected to the analog system ground plane.
128	DAC_DVDD			Analog power for Destination DDS DAC. Must be bypassed with a 0.1 uF capacitor to pin 127 (DAC_DGND)
129	PLL_DVDD			Analog power for the Destination DDS PLL. Must be bypassed with a 0.1 uF capacitor to pin 131 (PLL_DGND)
130	Reserved			For testing purposes only. Do not connect.
131	PLL_DGND			Analog ground for the Destination DDS PLL. Must be directly connected to the analog system ground plane.
132	SUB_DGND			Dedicated pin for the substrate guard ring that protects the Destination DDS. Must be directly connected to the analog system ground plane.
133	SUB_SGND			Dedicated pin for the substrate guard ring that protects the Source DDS. Must be directly connected to the analog system ground plane.
134	PLL_SGND			Analog ground for the Source DDS PLL. Must be directly connected to the analog system ground.
135	Reserved			For testing purposes only. Do not connect.
136	PLL_SVDD			Analog power for the Source DDS PLL. Must be bypassed with a 0.1 uF capacitor to pin 134 (PLL_SGND)
137	DAC_SVDD			Analog power for the Source DDS DAC. Must be bypassed with a 0.1 uF capacitor to pin 138 (DAC_SGND)
138	DAC_SGND			Analog ground for the Source DDS DAC. Must be directly connected to the analog system ground.
139	SVDD			Digital power for the Source DDS. Must be bypassed with a 0.1 uF capacitor to digital ground plane.
141	TCLK	In		Reference clock (TCLK) input from the 50 Mhz crystal oscillator.
142	XTAL	Out		If using an external oscillator, leave this pin floating. If using an external crystal, connect crystal between TCLK (141) and XTAL (142). See MFB5 (pin 107).
143	PLL_RVDD			Analog power for the Reference DDS PLL. Must be bypassed with a 0.1 uF capacitor to pin 144 (PLL_RGND)
144	PLL_RGND			Analog ground for the Reference DDS PLL. Must be directly connected to the analog system ground plane.
145	Reserved			For testing purposes only. Do not connect.
146	SUB_RGND			Dedicated pin for the substrate guard ring that protects the Reference DDS. Must be directly connected to the analog system ground plane.
148	VSYNC	In		CRT Vsync input. TTL Schmitt trigger input.
149	SYN_VDD			Digital power for CRT Sync input
150	HSYNC/ CSYNC	In		CRT Hsync or CRT composite sync input. TTL Schmitt trigger input.

**Table 4. TFT Panel Interface**

Pin	Name	In / Out	Drive Current (@10pF)	Description				
				2pxl/clock 8-bit	2pxl/clock 6-bit	1pxl/clock 8-bit	1pxl/clock 6-bit	TFT
6	PD47	out	2 mA ~ 20 mA	OB1	-	-	-	
7	PD46	out	2 mA ~ 20 mA	OB0	-	-	-	
9	PD45	out	2 mA ~ 20 mA	OG1	-	-	-	
10	PD44	out	2 mA ~ 20 mA	OG0	-	-	-	
13	PD43	out	2 mA ~ 20 mA	OR1	-	-	-	
14	PD42	out	2 mA ~ 20 mA	OR0	-	-	-	
15	PD41	out	2 mA ~ 20 mA	EB1	-	B1	-	
16	PD40	out	2 mA ~ 20 mA	EB0	-	B0	-	
17	PD39	out	2 mA ~ 20 mA	EG1	-	G1	-	
19	PD38	out	2 mA ~ 20 mA	EG0	-	G0	-	
20	PD37	out	2 mA ~ 20 mA	ER1	-	R1	-	
22	PD36	out	2 mA ~ 20 mA	ER0	-	R0	-	
23	PD35	out	2 mA ~ 20 mA	OB7	OB5	-	-	
24	PD34	out	2 mA ~ 20 mA	OB6	OB4	-	-	
25	PD33	out	2 mA ~ 20 mA	OB5	OB3	-	-	
26	PD32	out	2 mA ~ 20 mA	OB4	OB2	-	-	
27	PD31	out	2 mA ~ 20 mA	OB3	OB1	-	-	
28	PD30	out	2 mA ~ 20 mA	OB2	OB0	-	-	
29	PD29	out	2 mA ~ 20 mA	OG7	OG5	-	-	
31	PD28	out	2 mA ~ 20 mA	OG6	OG4	-	-	
32	PD27	out	2 mA ~ 20 mA	OG5	OG3	-	-	
34	PD26	out	2 mA ~ 20 mA	OG4	OG2	-	-	
35	PD25	out	2 mA ~ 20 mA	OG3	OG1	-	-	
36	PD24	out	2 mA ~ 20 mA	OG2	OG0	-	-	
37	PD23	out	2 mA ~ 20 mA	OR7	OR5	-	-	
38	PD22	out	2 mA ~ 20 mA	OR6	OR4	-	-	
39	PD21	out	2 mA ~ 20 mA	OR5	OR3	-	-	
42	PD20	out	2 mA ~ 20 mA	OR4	OR2	-	-	
46	PD19	out	2 mA ~ 20 mA	OR3	OR1	-	-	
47	PD18	out	2 mA ~ 20 mA	OR2	OR0	-	-	
48	PD17	out	2 mA ~ 20 mA	EB7	EB5	B7	B5	
50	PD16	out	2 mA ~ 20 mA	EB6	EB4	B6	B4	
51	PD15	out	2 mA ~ 20 mA	EB5	EB3	B5	B3	
52	PD14	out	2 mA ~ 20 mA	EB4	EB2	B4	B2	
53	PD13	out	2 mA ~ 20 mA	EB3	EB1	B3	B1	
54	PD12	out	2 mA ~ 20 mA	EB2	EB0	B2	B0	
55	PD11	out	2 mA ~ 20 mA	EG7	EG5	G7	G5	
56	PD10	out	2 mA ~ 20 mA	EG6	EG4	G6	G4	
57	PD9	out	2 mA ~ 20 mA	EG5	EG3	G5	G3	
62	PD8	out	2 mA ~ 20 mA	EG4	EG2	G4	G2	

Pin	Name	In / Out	Drive Current (@10pF)	Description				
				2pxl/clock 8-bit	2pxl/clock 6-bit	1pxl/clock 8-bit	1pxl/clock 6-bit	TFT
63	PD7	out	2 mA ~ 20 mA	EG3	EG1	G3	G1	
64	PD6	out	2 mA ~ 20 mA	EG2	EG0	G2	G0	
66	PD5	out	2 mA ~ 20 mA	ER7	EG5	R7	R5	
67	PD4	out	2 mA ~ 20 mA	ER6	ER4	R6	R4	
68	PD3	out	2 mA ~ 20 mA	ER5	ER3	R5	R3	
69	PD2	out	2 mA ~ 20 mA	ER4	ER2	R4	R2	
70	PD1	out	2 mA ~ 20 mA	ER3	ER1	R3	R1	
71	PD0	out	2 mA ~ 20 mA	ER2	ER0	R2	R0	
43	PDispE	out	2 mA ~ 20 mA	This output provides a panel display enable signal that is active when flat panel data is valid.				
74	PHS	out	2 mA ~ 20 mA	This output provides the panel line clock signal.				
73	PVS	out	2 mA ~ 20 mA	This output provides the frame start signal.				
44	PCLKA	out	2 mA ~ 20 mA	This output is used to drive the flat panel shift clock.				
45	PCLKB	out	2 mA ~ 20 mA	Same as PCLKA above. The polarity and the phase of this signal are independently programmable.				
75	Pbias	out	8 mA	This output is used to turn on / off the panel bias power or controls back-light.				
76	Ppwr	out	8 mA	This output is used to control the power to a flat panel.				

NOTE: Drive current of the panel output pins are programmable.

**Table 5. Test Pins**

Pin	Name	In/Out	Drive Current	Description
3	PSCAN	In		Enable automatic PCB assembly test. When this input is pulled high, the automatic PCB assembly test mode is entered. An internal pull-down resistor drives this input low for normal operation.
155	SCAN_IN1	In		Scan input 1 used for automatic PCB assembly testing.
157	SCAN_IN2	In		Scan input 2 used for automatic PCB assembly testing.
159	SCAN_OUT1	Out		Scan output 1 used for automatic PCB assembly testing.
160	SCAN_OUT2	Out		Scan output 2 used for automatic PCB assembly testing.
153	Reserved			
154	Reserved			

**Table 6. VDD / VSS for Core Circuitry, Host Interface, and Panel/Memory Interface**

Pins	Description
65, 40, 33, 12	PVDD4 ~ PVDD1 for panel / memory interface. Connect to +3.3V. Must be the same voltage as the CVDD's.
149, 108, 58, 21, 11	SRVDD2-1, CVDD4, CVDD2-1 for core circuitry. Connect to +3.3V. Must be the same voltage as the PVDD's.
158, 151, 140, 126, 114, 72, 61, 49, 41, 30, 18, 8, 1	Digital grounds for core circuitry and panel / memory interface.

1.4 System-level Block Diagram

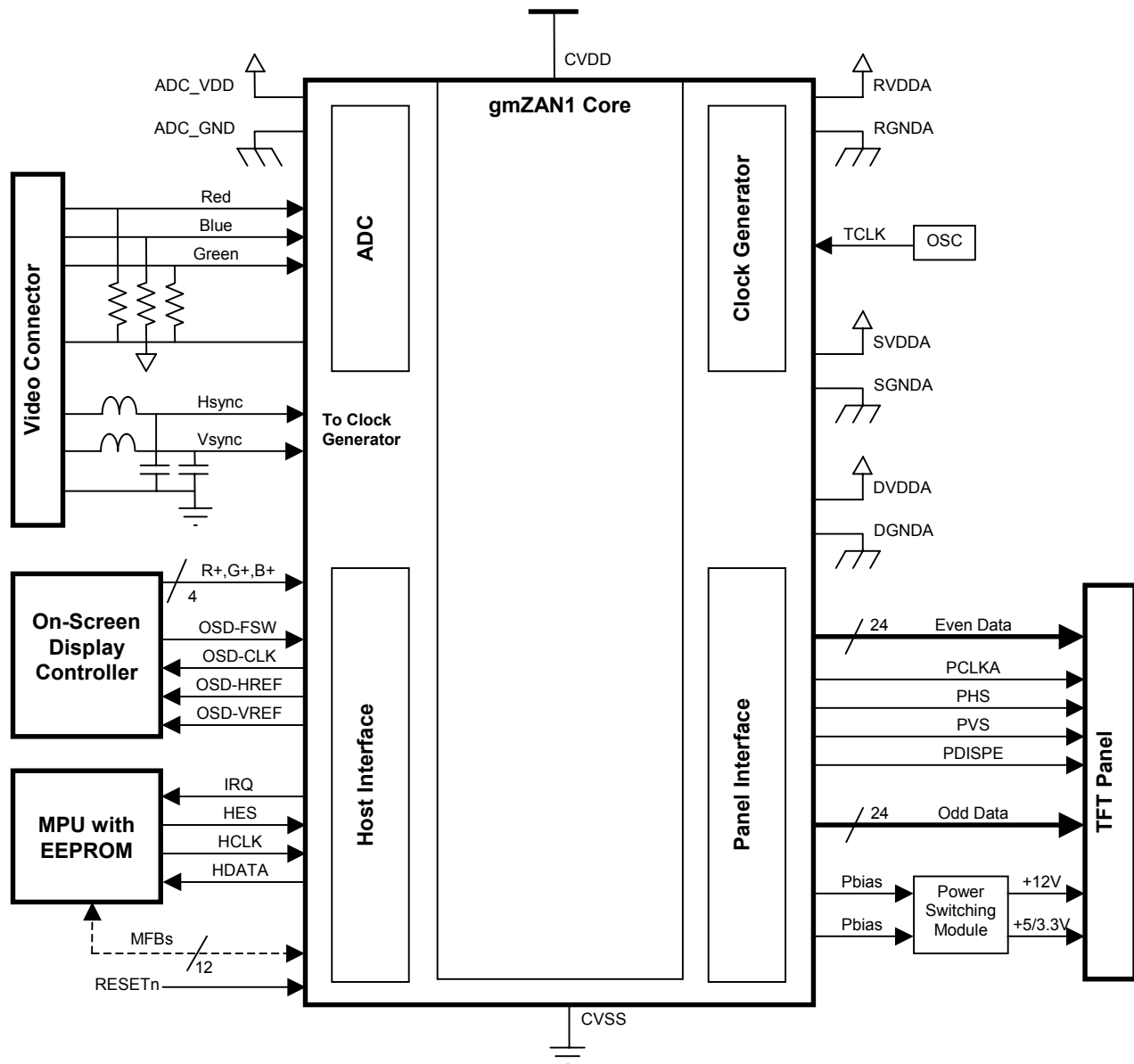


Figure 2. Typical Stand-alone Configuration

## 1.5 Operating Modes

The Source Clock (also called SCLK in this document) and the Panel Clock are defined as follows:

- The Source Clock is the sample clock regenerated from the input Hsync timing (called clock recovery) by SCLK DDS (direct digital synthesis) and the PLL.
- The Panel Clock is the timing clock for panel data at the single pixel per clock rate. The actual PCLK to the panel may be one-half of this frequency for double-pixel panel data format. When its frequency is different from that of source clock, the panel clock is generated by Destination Clock (or DCLK) DDS / PLL.

There are six display modes: Native, Slow DCLK, Zoom, Downscaling, Destination Stand Alone, and Source Stand Alone.

Each mode is unique in terms of:

- input video resolution vs. panel resolution,
- Source Clock frequency / Panel Clock frequency ratio,
- Source Hsync frequency / Panel Hsync frequency ratio,
- data source (analog RGB, panel background color, on-chip pattern generator)

### 1.5.1 Native

Panel Clock frequency = Source Clock frequency

Panel Hsync frequency = Input Hsync frequency

Panel Vsync frequency = Input Vsync frequency

This mode is used when the input resolution is the same as the panel resolution and the input data clock frequency is within the panel clock frequency specification of the panel being used.

### 1.5.2 Slow DCLK

Panel Clock frequency < Source Clock frequency

Panel Hsync frequency = Input Hsync frequency

Panel Vsync frequency = Input Vsync frequency

This mode is used when the input resolution is the same as the panel resolution, but the input data clock frequency exceeds the panel clock frequency specification of the panel being used. The panel clock is scaled to the Source Clock, and the internal data buffers are used to spread out the timing of the input data by making use of the large CRT blanking time to extend the panel horizontal display time.

### 1.5.3 Zoom

Panel Clock frequency > Source Clock frequency

Panel Hsync frequency > Input Hsync frequency

Panel Vsync frequency = Input Vsync frequency

This mode is used when the input resolution is less than the panel resolution. The input data clock is then locked to the panel clock, which is at a higher frequency. The input data is zoomed to the panel resolution.

### 1.5.4 Downscaling

Panel Clock frequency < Source Clock frequency

Panel Hsync frequency < Input Hsync frequency

Panel Vsync frequency = Input Vsync frequency

This mode is used when the input resolution is greater than the panel resolution, to provide enough of a display to enable the user to recover to a supported resolution. The input clock is operated at a frequency less than that of the input pixel rate (under-sampled horizontally) and the scaling filter is used to drop input lines. In this mode, zoom scaling must be disabled.

### 1.5.5 Destination Stand Alone

Panel Clock = DCLK in open loop (not locked)

Panel Hsync frequency = DCLK frequency / (Destination Htotal register value)

Panel Vsync frequency = DCLK frequency / (Dest. Htotal register value \* Dest. Vtotal register value)

This mode is used when the input is changing or not available. The OSD may still be used as in all other display modes and stable panel timing signals are produced. This mode may be automatically set when the gmZAN1 detects input timing changes that could cause out-of-spec operation of the panel.

### 1.5.6 Source Stand Alone

Panel Clock = DCLK in open loop (not locked to input Hsync)

Panel Hsync frequency = SCLK frequency / (Source Htotal register value)

Panel Vsync frequency = SCLK frequency / (Source Htotal register value \* Source Vtotal register value)

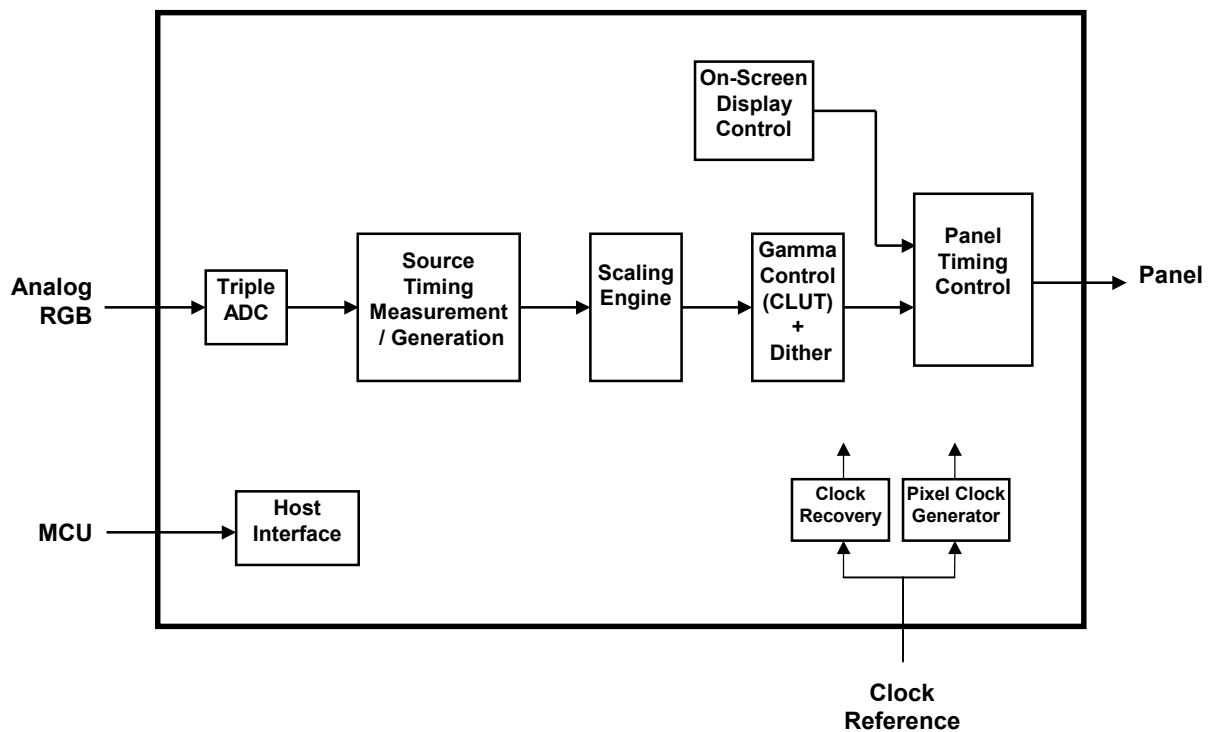
This mode is used to display the pattern generator data. This mode may be useful for testing an LCD panel on the manufacturing line (color temperature calibration, etc.).

## 2. FUNCTIONAL DESCRIPTION

Figure 3 below shows the main functional blocks inside the gmZAN1.

### 2.1 Overall Architecture

**Figure 3. Block Diagram for gmZAN1**



### 2.2 Clock Recovery Circuit

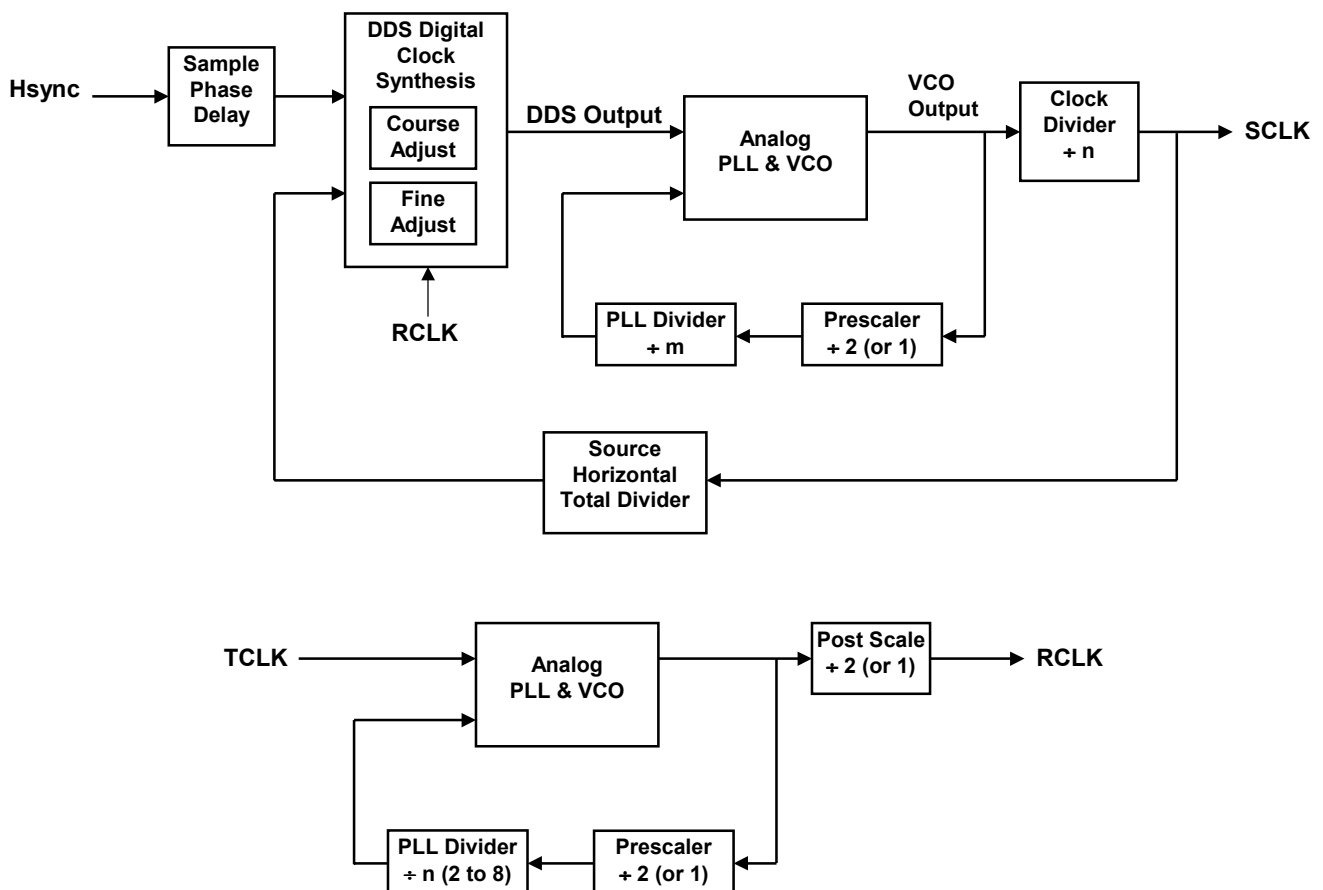
The gmZAN1 has a built-in clock recovery circuit. This circuit consists of a digital clock synthesizer and an analog PLL. The clock recovery circuit generates the clock used to sample analog RGB data (SCLK or source clock). This circuit is locked to the HSYNC of the incoming video signal. The RCLK generated from the TCLK input is used as a reference clock.

The clock recovery circuit adjusts the SCLK period so that the feedback pulse generated every SCLK period multiplied by the Source Horizontal Total value (as programmed into the registers) locks to the rising edge of the Hsync input. Even though the initial SCLK frequency and the final SCLK frequency are as far apart as 60MHz, locking can be achieved in less than 1ms across the operating voltage/temperature range.

The SCLK frequency (1/SCLK period) can be set to the range of 10- to 135-MHz. Using the DDS (direct digital synthesis) technology the clock recovery circuit can generate any SCLK clock frequency within this range.

The pixel clock (DCLK or destination clock) is used to drive a panel when the panel clock is different from SCLK (or SCLK/2). It is generated by a circuit virtually identical to the clock recovery circuit. The difference is that DCLK is locked to SCLK while SCLK is locked to the Hsync input. DCLK frequency divided by N is locked to SCLK frequency divided by M. The value M and N are calculated and programmed in the register by firmware. The value M should be close to the Source Htotal value.

**Figure 4. Clock Recovery Circuit**



The table below summarizes the characteristics of the clock recovery circuit.

**Table 7. Clock Recovery Characteristics**

	Minimum	Typical	Maximum
SCLK Frequency	10 MHz		135 MHz
Sampling Phase Adjustment		0.5 ns/step, 64 steps	

Patented digital clock synthesis technology makes the gmZAN1 clock circuits very immune to temperature/voltage drift.

### 2.2.1 Sampling Phase Adjustment

The ADC sampling phase is adjusted by delaying the Hsync input at the programmable delay cell inside the gmZAN1. The delay value can be adjusted in 64 steps, 0.5 ns/step. The accuracy of the sampling phase is checked by the gmZAN1 and the “score” can be read in a register. This feature will enable accurate auto-adjustment of the ADC sampling phase.

### 2.2.2 Source Timing Generator

The STG module defines a capture window and sends the input data to the data path block. The figure below shows how the window is defined.

For the horizontal direction, it is defined in SCLKs (equivalent to a pixel count). For the vertical direction, it is defined in lines.

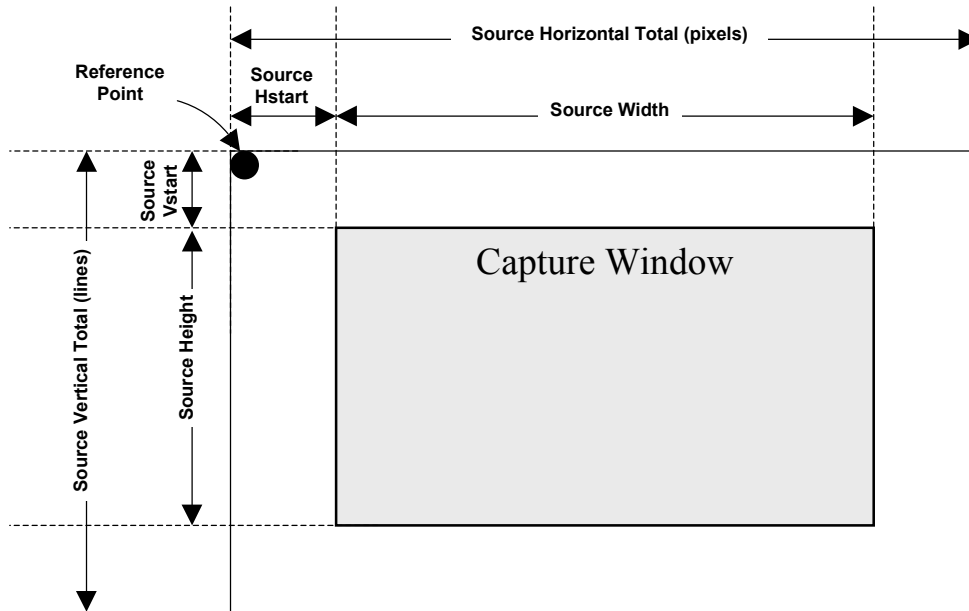
All the parameters in the figure that begin with “Source” are programmed into the gmZAN1 registers. Note that the vertical total is solely determined by the input.

The reference point is as follows:

- The first pixel of a line: the pixel whose SCLK rising edge sees the transition of the HSYNC polarity from low to high.
- The first line of a frame: the line whose HSYNC rising edge sees the transition of the VSYNC polarity from low to high.

The gmZAN1 also supports the use of analog composite sync and digital sync signals as described in Section 2.3.2.

Figure 5. Capture Window



## 2.3 Analog-to-Digital Converter

### 2.3.1 Pin Connection

The RGB signals are to be connected to the gmZAN1 chip as described in Table 8 and Table 9.

Table 8. Pin Connection for RGB Input with HSync/Vsync

gmZAN1 Pin Name (Pin Number)	CRT Signal Name
Red+ (#95)	Red
Red- (#94)	N/A (Tie to Analog GND for Red on the board)
Green+ (#91)	Green
Green- (+90)	N/A (Tie to Analog GND for Green on the board)
Blue+ (#87)	Blue
Blue- (#86)	N/A (Tie to Analog GND for Blue on the board)
HSYNC/CS (#150)	Horizontal Sync
VSYNC (#148)	Vertical Sync

**Table 9. Pin Connection for RGB Input with Composite Sync**

gmZAN1 Pin Name (Pin Number)	CRT Signal Name
Red+ (#95)	Red
Red- (#94)	N/A (Tie to Analog GND for Red on the board)
Green+ (#91)	Green When using Sync-On-Green this signal also carries the sync pulse.
Green- (#90)	N/A (Tie to Analog GND for Green on the board)
Blue+ (#87)	Blue
Blue- (#86)	N/A (Tie to Analog GND for Blue on the board)
HSYNC/CS (#150)	Digital composite sync. Not applicable for Sync-On-Green

The gmZAN1 chip has three ADC's (analog-to-digital converters), one for each color (red, green, and blue). Table 10 summarizes the characteristics of the ADC.

**Table 10. ADC Characteristics**

	MIN	TYP	MAX	NOTE
<b>RGB Track &amp; Hold Amplifiers</b>				
Band Width		160 MHz		
Settling Time to 1/2 %		8.5 ns		Full Scale Input = 0.75V, BW=160MHz (*)
Full Scale Adjust Range @ R,G,B Inputs	0.60 V		0.95 V	
Full Scale Adjust Sensitivity		+/- 1 LSB		Measured @ ADC Output (**)
Zero Scale Adjust Range				For a larger DC offset from an external video source, the AC coupling feature is used to remove the offset.
Zero Scale Adjust Sensitivity		+/- 1 LSB		Measured @ ADC Output
<b>ADC + RGB Track &amp; Hold Amplifiers</b>				
Sampling Frequency (fs)	20 MHz		135 MHz	
DNL			+/- 0.9 LSB	fs = 80 MHz
INL		+/- 1.5 LSB		fs = 80 MHz
Channel to Channel Matching		+/- 0.5 LSB		
Effective Number of Bits (ENOB)		7 Bits		fin = 1 MHz, fs = 80 MHz Vin= -1 db below full scale = 0.75V
Power Dissipation		400 mW		fs = 110 MHz, Vdd = 3.3V
Shut Down Current			100uA	

(\*) Guaranteed by design    (\*\*) Independent of full scale R,G,B input

The gmZAN1 ADC has a built-in clamp circuit. By inserting series capacitors (about 10 nF) the DC offset of an external video source can be removed. The clamp pulse position and width are programmable.

### 2.3.2 Sync. Signal Support

The gmZAN1 chip supports digital separate sync (Hsync/Vsync), digital composite sync, and analog composite sync (also known as sync-on-green). All sync types are supported without external sync separation / extraction circuits.

#### **Digital Composite Sync**

The types of digital composite sync inputs supported are:

- OR/AND type: No Csync pulses toggling during the vertical sync period
- XOR type: Csync polarity changes during the vertical sync period

The gmZAN1 provides enough sync status information for the firmware to detect the digital composite sync type.

#### **Sync-On-Green (Analog Composite Sync)**

The voltage level of the sync tip during the vertical sync period can be either -0.3V or 0V.

### 2.3.3 Display Mode Support

A mode calculation utility (MODECALC.EXE) provided by Genesis Microchip may be run before compilation of the firmware to determine which input modes can be supported. Refer to firmware documents for more details.

## 2.4 Input Timing Measurement

As described in section 2.2.2 above, input data is sent from the analog-to-digital converter to the source timing generator (STG) block. The STG block defines a capture window (Figure 5).

The input timing measurement block consists of the source timing measurement (STM) block and interrupt request (IRQ) controller. Input timing parameters are measured by the STM block and stored in registers. Some input conditions will generate an IRQ to an external micro-controller. The IRQ-generating conditions are programmable.

### 2.4.1 Source Timing Measurement

When it receives the active CRT signal (R, G, B and Sync signals) the Source Timing Measurement unit begins measuring the horizontal and vertical timing of the incoming signal using the sync signals and TCLKi as a reference. Horizontal measurement occurs by measuring a minimum and a maximum value for each parameter to account for TCLKi sampling granularity. The measured value is updated every line. Vertical parameters are measured in terms of horizontal lines. The trailing edge of the Hsync input is used to check the polarity of the Vsync input.

The table below lists all the parameters that may be read in the source timing measurement (STM) registers of the gmZAN1.

**Table 11. Input Timing Parameters Measured by the STM Block**

Parameter	Unit	Updated at:
HSYNC Missing	N/A	Every 4096 TCLKs and every 80ms (2-bits)
VSYNC Missing	N/A	Every 80 ms
HSYNC / VSYNC Timing Change	N/A	When the horizontal period delta or the vertical period delta to the previous line / frame exceeds the threshold value (programmable).
HSYNC Polarity	Positive / Negative	After register read
VSYNC Polarity	Positive / Negative	Every frame
Horizontal Period Min / Max	TCLKs and SCLKs	After register read
HSYNC High Period Min / Max	TCLKs	After register read
Vertical Period	Lines	Every frame
VSYNC High Period	Lines	Every frame
Horizontal Display Start	SCLKs	Every frame
Horizontal Display End	SCLKs	Every frame
Vertical Display Start	Lines	Every frame
Vertical Display End	Lines	Every frame
Interlaced Input Detect	N/A	Every frame
CRC Data / Line Data	N/A	Every frame
CSYNC Detect	N/A	Every 80 ms

The display start / end registers store the first and the last pixels / lines of the last frame that have RGB data above a programmed threshold.

The reference point of the STM block is the same as that of the source timing generator (STG) block:

- The first pixel: the pixel whose SCLK rising edge sees the transition of the HSYNC polarity from low to high.
- The first line: the line whose HSYNC rising edge sees the transition of the VSYNC polarity from low to high.

The CRC data and the line data are used to detect a test pattern image sent to the gmZAN1 input port.

#### 2.4.2 IRQ Controller

Some input timing conditions can cause the gmZAN1 chip to generate an IRQ. The IRQ-generating conditions are programmable, as given in the following table.

**Table 12. IRQ-Generation Conditions**

IRQ Event	Remark
Timing Event	One of the three events: <ul style="list-style-type: none"> <li>• Leading edge of Vsync input,</li> <li>• Panel line count (the line count is programmable),</li> <li>• Every 10 ms</li> </ul> Only one event may be selected at a time.
Timing Change	Any of the following timing changes: <ul style="list-style-type: none"> <li>• Sync loss,</li> <li>• DDS tracking error beyond threshold,</li> <li>• Horizontal / vertical timing change beyond threshold.</li> </ul> Threshold values are programmable.

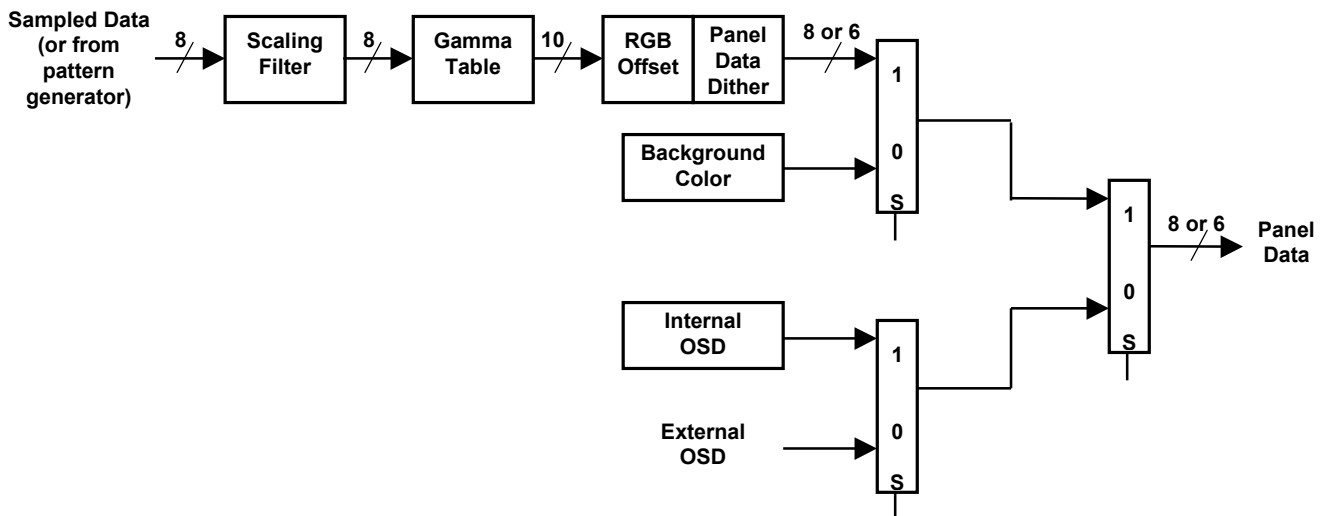
Reading the IRQ status flags will not affect the STM registers.

Note that if a new IRQ event occurs while the IRQ status register is being read, the IRQ signal will become inactive for a minimum of one TCLK period and then get re-activated. The polarity of the IRQ signal is programmable.

**2.5 Data Path**

The data path block of gmZAN1 is shown in Figure 6.

**Figure 6. gmZAN1 Data Path**



### 2.5.1 Scaling Filter

The gmZAN1 scaling filter uses an advanced adaptive scaling technique proprietary to Genesis Microchip Inc. and provides high quality scaling of real time video and graphics images. This is Genesis' third generation scaling technology that benefits from the expertise and feedback gained by supporting a wide range of solutions and applications.

### 2.5.2 Gamma Table

The gamma table is used to adjust the RGB data for the individual display characteristics of the TFT panel. The overall gamma of the display may be set, as well as separate corrections for each of the three display channels. In addition, the gamma table may be used for contrast, brightness, and white balance (temperature) adjustments. The lookup table has an 8-bit input (256 different RGB entries) and produces a 10-bit output.

### 2.5.3 RGB Offset

The RGB offsets provide a simple shift (positive or negative) for each of the three color channels. This may be used as a simple brightness adjustment within a limited range. The data is clamped to zero for negative offsets, and clamped to FFh for positive offsets. This adjustment is much faster than recalculating the gamma table, and could be used with the OSD user controller to provide a quick brightness adjust. An offset range of plus 127\*4 to minus 127\*4 is available.

### 2.5.4 Panel Data Dither

For TFT panels that have fewer than eight bits for each R, G, B input, the gmZAN1 provides ordered and random dithering patterns to help smoothly shade colors on 6-bit panels.

### 2.5.5 Panel Background Color

A solid background color may be selected for a border around the active display area. The background color is most often set to black.

## 2.6 Panel Interface

The gmZAN1 chip interfaces directly with all of today's commonly used active matrix flat panels with 640x480, 800x600 and 1024x768 resolutions. The resolution and the aspect ratio are NOT limited to specific values.

### 2.6.1 TFT Panel Interface Timing Specification

The TFT panel interface timing parameters are listed in Table 13 below. Refer to three timing diagrams of Figure 7 and Figure 8 for the timing parameter definition. All aspects of the gmZAN1 interface are programmable. For horizontal parameters, Horizontal Display Enable Start, Horizontal Display Enable End, Horizontal Sync Start and Horizontal Sync End are programmable. Vertical Display Enable Start, Vertical Display Enable End, Vertical Sync Start and Vertical Sync End are also fully programmable. In order to maximize panel data setup and hold time, the panel clock (PCLKA, PCLKB) output skew is programmable. In addition, the current drive strength of the panel interface pins is programmable.

**Table 13. gmZAN1 TFT Panel Interface Timing**

Signal Name			min	Typical	Max	unit
PVS	Period	t1	0	16.67	2048	lines ms
	Frequency			60	-	Hz
	front porch	t2	0		2048	lines
	back porch	t3	0		2048	lines
	pulse width	t4	0		2048	lines
	PdispE	t5	0	Panel height	2048	lines
	Disp. start from VS	t6	0		2048	lines
	PVS set up to PHS	t18	1		2048	PCLK *1
	PVS hold from PHS	t19	1		2048	PCLK *1
PHS	Period	t7	0		2048 [1024]	PCLK *1
	front porch	t8	0		2048	PCLK *1
	back porch	t9	0		2048	PCLK *1
	pulse width	t10	0		2048	PCLK *1
	PdispE	t11	0	Panel width	2048 [1024]	PCLK *1
	Disp. start from HS	t12	0		2048	PCLK *1
PCLKA, PCLKB*4	Frequency	t13			120 [60]	MHz
	Clock (H) *2	t14	DCLK/2 - 3 [DCLK - 3]		DCLK/2 - 2 [DCLK - 2]	ns
	Clock (L) *2	t15	DCLK/2 - 3 [DCLK - 3]		DCLK/2 - 2 [DCLK - 2]	ns
	Type		-	One pxl/clock [two pxl/clock]	-	
Data	set up *3	t16	DCLK/2 - 5 [DCLK - 5]		DCLK/2 - 2 [DCLK - 2]	ns
	hold *3	t17	DCLK/2 - 5 [DCLK - 5]		DCLK/2 - 2 [DCLK - 2]	ns
	Width		3 bits	18bits [36 bits]	24bits [48bits]	bits/pixel

NOTE: Numbers in [ ] are for two pixels/clock mode.

NOTE: The drive current of the panel interface signals is programmable as shown in Table 1 on page 4. The drive current is to be programmed through the API upon chip initialization. Output current is programmable from 2 mA to 20 mA in increments of 2 mA. Drive strength should be programmed to match the load presented by the cable and input of the panel. Values shown are based on a loading of 20 pF and a drive strength of 8 mA.

NOTE \*1: The PCLK is the panel shift clock.

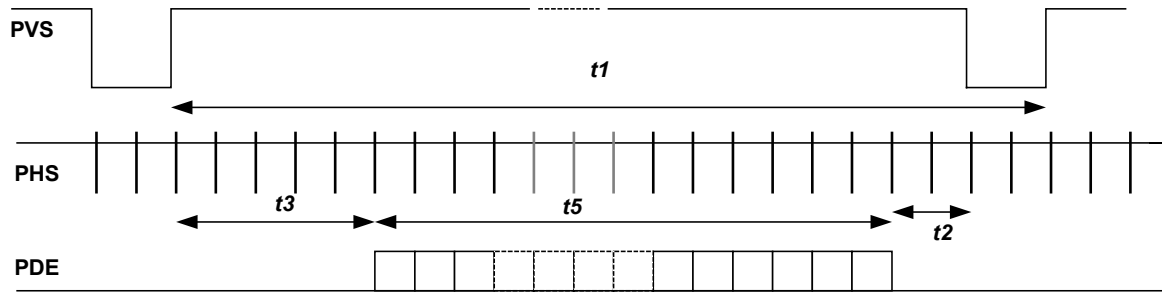
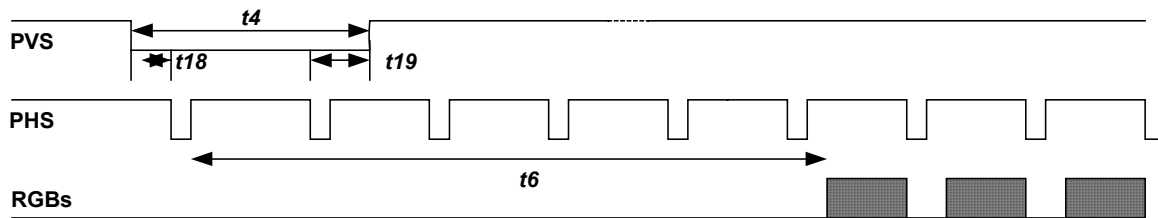
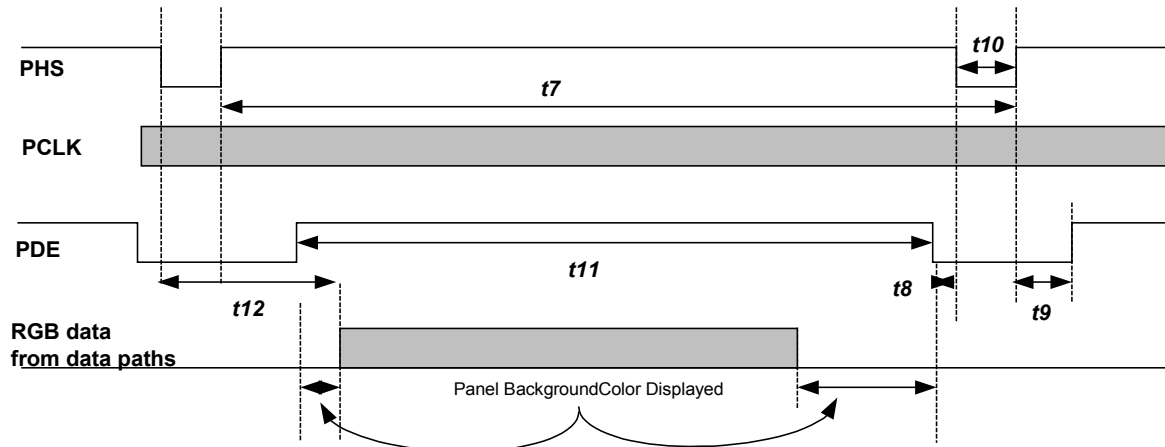
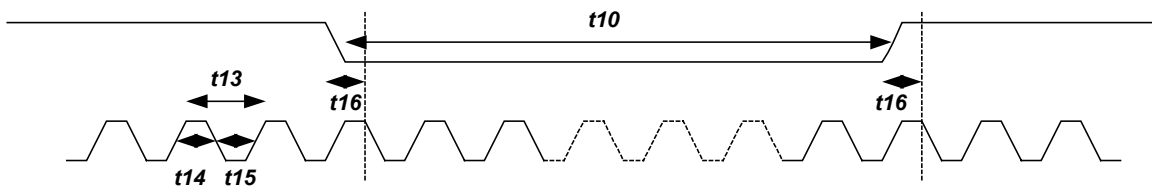
NOTE \*2: The DCLK stands for Destination Clock (DCLK) period. is equal to:

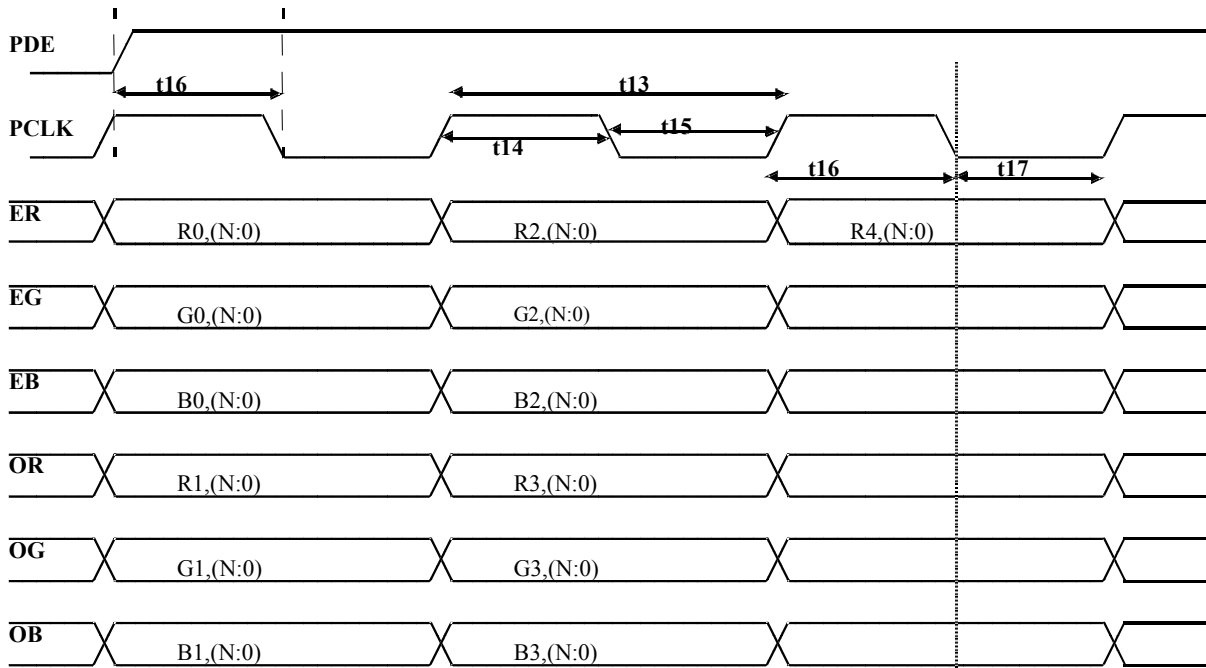
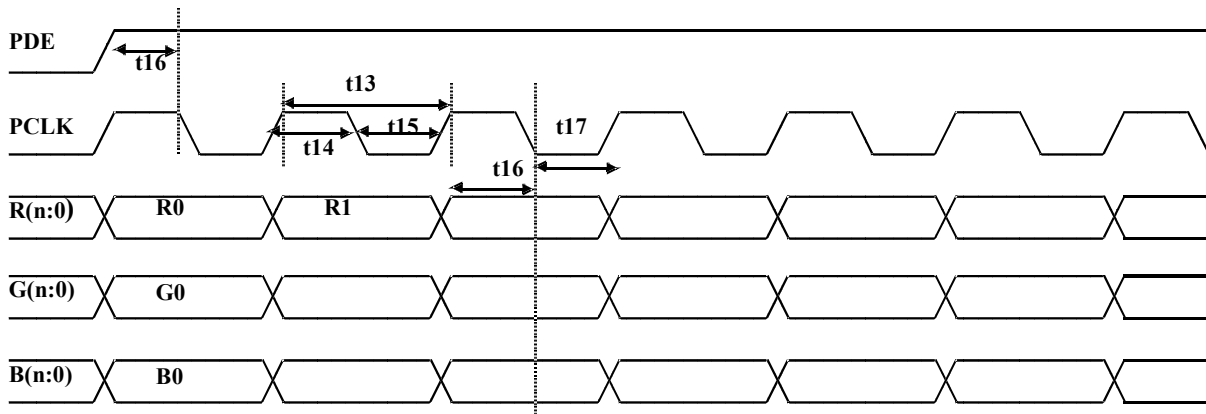
- PCLK period in one pixel/clock mode,
- twice the PCLK period in two pixels/clock mode.

NOTE \*3: The setup/hold time spec. for PCLK also applies to PHS and PDispE. The setup time (t16) and the hold time (t17) listed in this table are for the case in which no clock-to-data skew is added. The PVS/PHS/ PDispE/PData signals are asserted on the rising edge of the PCLK. The polarity of the PCLK and its skew are programmable. Clock to Data skew can be adjusted in sixteen 800-ps increments. In combination with the PCLK polarity inversion, the clock-to-data phase can be adjusted in total of 31 steps.

NOTE \*4: The polarity of the PCLKA and the PCLKB are independently programmable.

The microcontroller must have all the timing parameters of the panel used for the monitor. The parameters are to be stored in a non-volatile memory. As can be seen from this table, the wide range of timing programmability of the gmZAN1 panel interface makes it possible to support various kinds of panels known today:

**Figure 7. Timing Diagrams of the TFT Panel Interface (one pixel per clock)**
**(a) Vertical size in TFT**

**(b) Vsync width and display position in TFT**

**(c) Horizontal size in TFT**

**(d) Hsync width in TFT**


**Figure 8. Data latch timing of the TFT Panel Interface**
**(a) Two pixel per clock mode in TFT**

**(b) One pixel per clock mode in TFT**


### 2.6.2 Power Manager

LCD panels require logic power, panel bias power, and control signals to be sequenced in a specific order, otherwise severe damage may occur and disable the panel permanently. The gmZAN1 has a built-in power sequencer (Power Manager) that prevents this kind of damage.

The Power Manager controls the power up/down sequences for LCD panels within the four states described below. See the timing diagram Figure 9.

**2.6.2.1 State 0 (Power Off)**

The Pbias signal and Ppower signal are low (inactive). The panel controls and data are forced low. This is the final state in the power down sequence. PM is kept in state 0 until the panel is enabled.

**2.6.2.2 State 1 (Power On)**

Intermediate step 1. The Ppower is high (active), the Pbias is low (inactive), and the panel interface is forced low (inactive).

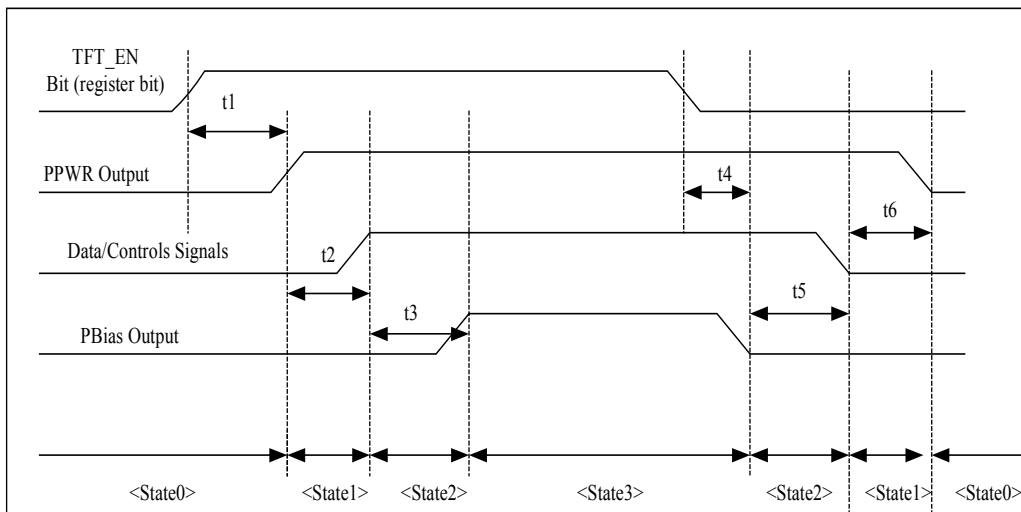
**2.6.2.3 State 2 (Panel Drive Enabled)**

Intermediate step 2. The Ppower is high (active), the Pbias is low (inactive), and the panel interface is active.

**2.6.2.4 State 3 (Panel Fully Active)**

This is the final step in the power up sequence, with Ppower and Pbias high (active), and the panel interface active. PM is kept in this state until the internal TFT\_Enable signal controlled by Panel Control register is disabled. The panel can be disabled through either an API call under program control or automatically by the gmZAN1 to prevent damage to the panel.

**Figure 9. Panel Power Sequence**



In Figure 9 above,  $t_2=t_6$  and  $t_3=t_5$ .  $t_1$ ,  $t_2$ ,  $t_3$  and  $t_4$  are independently programmable from one to eight steps in length. The length of each step is in the range of  $511 * X * (TCLK_i \text{ cycle})$  or  $(TCLK_i \text{ cycle}) * 32193 * X$ , where  $X$  is any positive integer value equal to or less than 256.  $TCLK_i$  is the reference clock to the gmZAN1 chip, and ranges from 14.318 MHz to 50 MHz in frequency. This programmability provides enough flexibility to meet a wide range of power sequencing requirements by various panels.

### 2.6.3 Panel Interface Drive Strength

As mentioned previously, the gmZAN1 has programmable output pads for the TFT panel interface. Three groups of panel interface pads (panel clock, data, and control) are independently controllable and are programmed using API calls. See the API reference manual for details.

**Table 14. Panel Interface Pad Drive Strength**

Value (4 bits)	Drive Strength in mA
0	Outputs are in tri-state condition
1	2 mA
2	4 mA
3	6 mA
4	8 mA
5	10 mA
6	12 mA
7	14 mA
8	16 mA
9	18 mA
10,11,12,13,14,15	20 mA

## 2.7 Host Interface

The host microcontroller interface of the gmZAN1 has two modes of operation: gmB120 compatible mode, and a 4-bit serial interface mode.

- gmB120 compatible mode - Four signals consisting of 1 data bit, a frame synchronization signal, a clock signal and an Interrupt Request signal (IRQ). This mode is entered when a pull-down resistor is not connected to MFB6 (pin number 106).
- 4-bit serial interface mode - Same as gmB120 compatible mode with the addition of three data bits so that four data bits are transferred on each clock edge. This mode is entered when a (10K ohm) pull-down resistor is connected to MFB6 (pin number 106).

When the chip is configured for 4-bit host interface, MFB9:7 are used as HDATA3:1 and HDATA is used as HDATA0. For Instruction, Read Data, or Write Data, the data order is D3:0, D7:4, D11:8. The burst mode operation then uses three clocks (instead of twelve) for each 12-bit data (or address) transmission.

In both modes, a reset pin sets the chip to a known state when the pin is pulled low. The RESETn pin must be low for at least 100 ns after the CVDD has become stable (between +3.15V and +3.45V) in order to reset the chip to a known state.

The gmZAN1 chip has an on-chip pull-down resistor in the HFS input pad. No external pull-up is required. The signal stays low until driven high by the microcontroller.

2.7.1 Serial Communication Protocol

In the serial communication between the microcontroller and the gmZAN1, the microcontroller always acts as an initiator while the gmZAN1 is always the target. The following timing diagram describes the protocol of the serial channel of the gmZAN1 chip.

Figure 10. Timing Diagram of the gmZAN1 Serial Communication

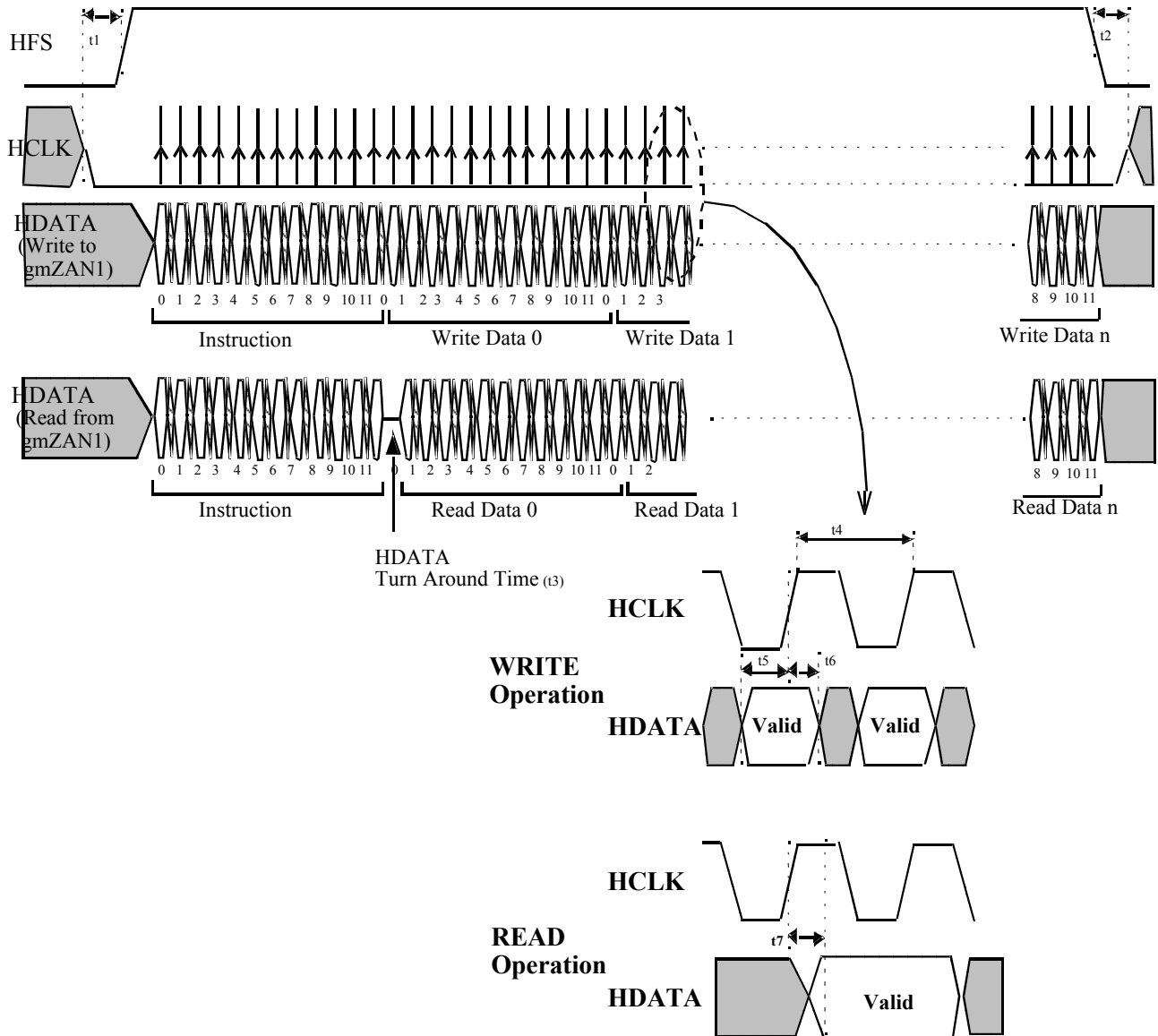


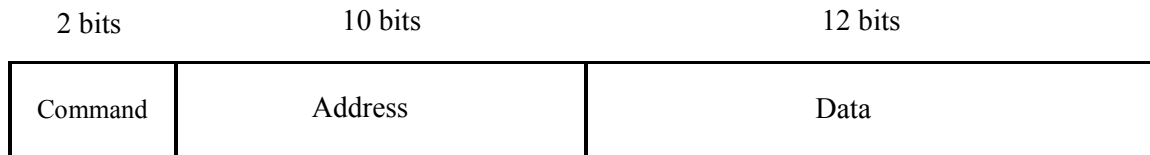
Table 15 summarizes the serial channel specification of the gmZAN1. Refer to Figure 10 for the timing parameter definition.

**Table 15. gmZAN1 Serial Channel Specification**

Parameter	min.	typ.	max.
Word Size (Instruction and Data)	---	12 bits	---
HCLK low to HFS high (t1)	100 ns		
HFS low to HCLK inactive (t2)	100 ns		
HDATA Write to Read Turnaround Time (t3)	1 HCLK cycle		1 HCLK cycle
HCLK cycle (t4)	100 ns		
Data in setup time (t5)	25 ns		
Data in hold time (t6)	25 ns		
Data out valid (t7)	5 ns		10

In the read operation, the microcontroller (Initiator) issues an instruction lasting 12 HCLKs. After the last bit of the command is transferred to the gmZAN1 on the 12th clock, the microcontroller must stop driving data before the next rising edge of HCLK at which point the gmZAN1 will start driving data. At the 13th rising edge of HCLK, the gmZAN1 will begin driving data.

**Figure 11. Serial Host Interface Data Transfer Format**



Command: 01 = Write                      00 = Read                      1x = Reserved

Note that when the chip is configured for a 4-bit host interface, MFB9:7 are used as HDATA3:1 and HDATA is used as HDATA0. The command and address information are transferred as Address1:0+Command1:0, Address5:2 and Address9:6. The data information is transferred as Data3:0, Data7:4, Data11:8. Thus, in this mode the HDATA pin carries Command0, Address2, Address6, Data0, Data4 and Data8.

On the gmZAN1 reference design board, the microcontroller toggles the HCLK and HDATA lines under program control. Genesis Microchip provides API calls to facilitate communication between the microcontroller and the gmZAN1. Refer to the API reference manual for details.

### 2.7.2 Multi-Function Bus (MFB)

The Multi-Function Bus provides additional 12 pins that are used as general purpose input and output (GPIO) pins. Each pin can be independently configured as input or output.

MFB pins 9 through 5 have special functions:

- When a 10K ohm pull-down resistor is connected to MFB6 (MFB6 has an internal pull-up resistor) MFB9:7 are used as host data bits HDATA3:1.

- When a 10K ohm pull-down resistor is connected to MFB5 (MFB5 has an internal pull-up resistor) a crystal can be placed between XTAL and TCLK instead of using an external oscillator for the TCLK input.

Note that all pins on the multi-function bus MFB11:0 are internally pulled-up.

## 2.8 On-Screen Display Control

The gmZAN1 chip has a built-in OSD (On-Screen Display) controller with an integrated font ROM. The chip also supports an external OSD controller for monitor vendors to maintain a familiar user interface.

The internal and external OSD windows may be displayed anywhere the panel Display Enable is active, regardless of whether the panel would otherwise display panel background color or active data.

### 2.8.1 OSD Color Map

Both the internal and external OSD display use a 16 location SRAM block for the color programming. Each color location is a twelve-bit value that defines the upper four bits of each of the 8 bit Red, Blue and Green color components as follows:

- D3:0 Blue; D7:4 of blue component of color
- D7:4 Green; D7:4 of green component of color
- D11:8 Red; D7:4 of red component of color

To extend the 4-bit color value programmed to the full 8 bits the following rule is applied: if any of the upper four color bits are a “1”, then R (G, B) data 3:0 = 1111b, otherwise R (G, B) data 3:0 = 0000b.

### 2.8.2 On-Chip OSD Controller

The internal OSD uses a block of SRAM of 1536x12 bits and a ROM of 1024x12 bits. The SRAM is used for both the font data and the character-codes while the ROM is used to store the bit data for 56 commonly used characters. The font data is for 12 pixel x 18 line characters, one bit per pixel. The font data starts at address zero. The character-codes start at any offset (with an address resolution of 16) that is greater than the last location at which font data has been written. It is the programmer’s responsibility to ensure that there is no overlap between fonts and character-codes. This implementation results in a trade-off between the number of unique fonts on-screen at any one time and the total number of characters displayed. For example, one configuration would be 98 font maps (56 fonts in ROM and 42 fonts in SRAM) and 768 characters (e.g. in a 24x32 array).

The on-chip OSD of the gmZAN1 can support a portrait mode (in which the LCD monitor screen is rotated 90 degrees). In this portrait mode, all the fonts must be loaded in the SRAM, because the ROM stores fonts for a landscape mode (typical orientation) only. The font size in the portrait mode is 12 pixels by 12 lines. As is the case in landscape mode, the SRAM is divided into a font storage area and a character code storage area. For example, 64 fonts can be stored in RAM and an OSD window of 768 characters (such as 24 x 32) can still be displayed.

The first address of SRAM to be read for the first character displayed (upper left corner of window) is also programmable, with an address resolution of 16 (8-bits as the top bits of the 12-bit SRAM address). The character-code is a 12-bit value used as follows:

- D6:0 font-map select, this is the top seven bits of the address for the first line of font bits
- D8:7 Background color, 00=bcolor0, 01=bcolor1, 10=bcolor2, 11=transparent background
- D10:9 Foreground color (0, 1, 2 or 3)
- D11 Blink enable if set to 1, otherwise no blink

Although the OSD color map has room for sixteen colors, only seven are used by the internal OSD: three background colors and four foreground colors.

The blink rate is based on either a 32 or 64 frame cycle and the duty cycle may be selected as 25/75 50/50% or 75/25%. The 2-bit foreground and background attributes directly select the color (there is no indirect “look-up”, i.e. there is no TMASK function). The 2560 addresses of the ROM/SRAM are mapped as 10 segments of 256 contiguous addresses each, to the OSD memory page of 100h – 1FFh in the host interface. A 4-bit register value selects the segment to map to the host R/W page.

The character cell height and width are programmable from 5-66 pixels or 2-65 lines. The X/Y offset of the font bit-map upper-left pixel relative to the upper-left pixel of the character cell is also programmable from 0-63 (pixels or lines). The OSD window height and width in characters/rows is programmable from 1-64.

The Start X/Y position for the upper left corner of the OSD window is programmable (in panel pixels and lines) from 0- 2047. There is an optional window border (equal width on all four sides of the window) or a window shadow (the window bottom and right side) the border is a solid color that is selected by an SRAM location as RGB444. The border width may be set as 1, 2, 4 or 8 pixels/lines. These parameters are summarized in Figure 12 and Table 16.

The Font Data D11:0 for each line is displayed with bit D11 first (leftmost) and D0 last.

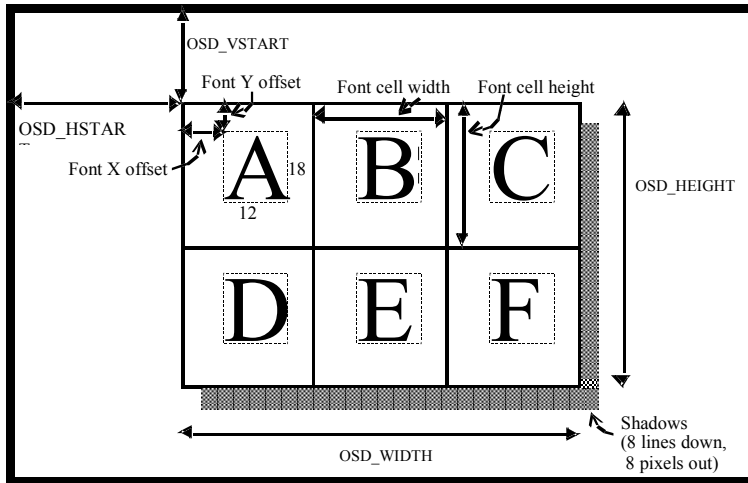
The reference point for the OSD start is always the upper left corner of the Panel display, which is the start (leading edge) of Panel Display Enable for both Horizontal and Vertical timing.

The OSD Window start position sets the location of the first pixel of the OSD to display, including any border. That is; if the border is enabled, the start of the character display of the OSD is offset from the OSD start position by the width/height of the border.

To improve the appearance and make it easy to find the OSD window on the screen, the user may select optional shadowing (3D effect). The “Shadow” feature operates in the same manner as in the B120; that is, it produces a region of half intensity (scaler data) pixels of the same width and height as the OSD window, but offset to the right and down by 8 pixels/lines (the border width setting has no effect). OSD foreground and background colors always cover the OSD window region of the “shadow”, but transparent background pixels in the OSD will show the half intensity panel data. Therefore, it is not recommended to use both the “shadow” feature and transparent background OSD pixels together. The “shadow” does **not** change the intensity of any panel background color over which it may be located. The border and shadow are mutually exclusive, only one may be selected at a time.

The OSD window is not affected by the scaling operation. The size will stay the same whether the source input data is scaled or not.

**Figure 12. On-Chip OSD Window Location**



OSD\_HSTART: Starting pixel number 0-2047  
 OSD\_VSTART: Starting line number 0-2047  
 Font X offset: Location of left pixel of font inside cell 0-63  
 Font Y offset: Location of top line of font inside cell 0-63  
 Font Cell Width: Cell width in pixels 5-66  
 Font Cell Height: Cell height in lines 2-65  
 OSD\_Width: OSD Window Width in char cells 1-64  
 OSD\_Height: OSD Window Height in char cells 1-64

OSD\_Width x OSD\_Height <= 32  
 (1x32, 2x16, 3x10, 4x8, 5x5, 6x5, etc.)

Font size = 12 pixels x 18 scanlines

**Table 16. Programmability of On-chip OSD Locations**

Parameter	Range	Reference Point
OSD Window Horizontal Start Position	0 ~ 2047 pixels	End-of-line pulse (internal signal)
OSD Window Vertical Start Position	0 ~ 2047 scanlines	End-of-frame pulse (internal signal)
Font X Offset	0 ~ 63 pixels	Upper-left corner of a screen location
Font Y Offset	0 ~ 63 scanlines	Upper-left corner of a screen location
Font Cell Width	5 ~ 66 pixels	
Font Cell Height	2 ~ 65 lines	
OSD Window Width	1 ~ 64 characters	
OSD Window Height	1 ~ 64 characters	
OSD Window Width x OSD Window Height	0 ~ 32 character locations (rectangle or square)	
Font Size	12 pixels wide x 16 scanlines high	

There is no hardware cursor supported. Character blinking can be done by changing the foreground and background colors in the character attribute table.

On-chip OSD as well as external OSD is controlled through the API calls. The external OSD is explained in section 2.8.4.

### 2.8.3 Built-in OSD Fonts

To minimize external memory requirements, the gmZAN1 has a set of commonly used characters stored on an on-chip ROM. The ROM contains bit data for the fonts shown in Figure 13. These are the set of alphanumeric characters minus the upper and lower case Q, W and Y.

**Figure 13. Built-in OSD Fonts**

Index	Font	Index	Font	Index	Font	Index	Font
00	<b>0</b>	10	<b>G</b>	20	<b>Z</b>	30	<b>P</b>
01	<b>1</b>	11	<b>H</b>	21	<b>a</b>	31	<b>r</b>
02	<b>2</b>	12	<b>I</b>	22	<b>b</b>	32	<b>s</b>
03	<b>3</b>	13	<b>J</b>	23	<b>c</b>	33	<b>t</b>
04	<b>4</b>	14	<b>K</b>	24	<b>d</b>	34	<b>u</b>
05	<b>5</b>	15	<b>L</b>	25	<b>e</b>	35	<b>v</b>
06	<b>6</b>	16	<b>M</b>	26	<b>f</b>	36	<b>x</b>
07	<b>7</b>	17	<b>N</b>	27	<b>g</b>	37	<b>z</b>
08	<b>8</b>	18	<b>O</b>	28	<b>h</b>	38	<b>w</b> *
09	<b>9</b>	19	<b>P</b>	29	<b>i</b>	39	N/A
0A	<b>A</b>	1A	<b>R</b>	2A	<b>j</b>	3A	N/A
0B	<b>B</b>	1B	<b>S</b>	2B	<b>k</b>	3B	N/A
0C	<b>C</b>	1C	<b>T</b>	2C	<b>l</b>	3C	N/A
0D	<b>D</b>	1D	<b>U</b>	2D	<b>m</b>	3D	N/A
0E	<b>E</b>	1E	<b>V</b>	2E	<b>n</b>	3E	N/A
0F	<b>F</b>	1F	<b>X</b>	2F	<b>o</b>	3F	N/A

\* Last two lines overlap into SRAM and must be cleared to use this character.

### 2.8.4 External OSD Support

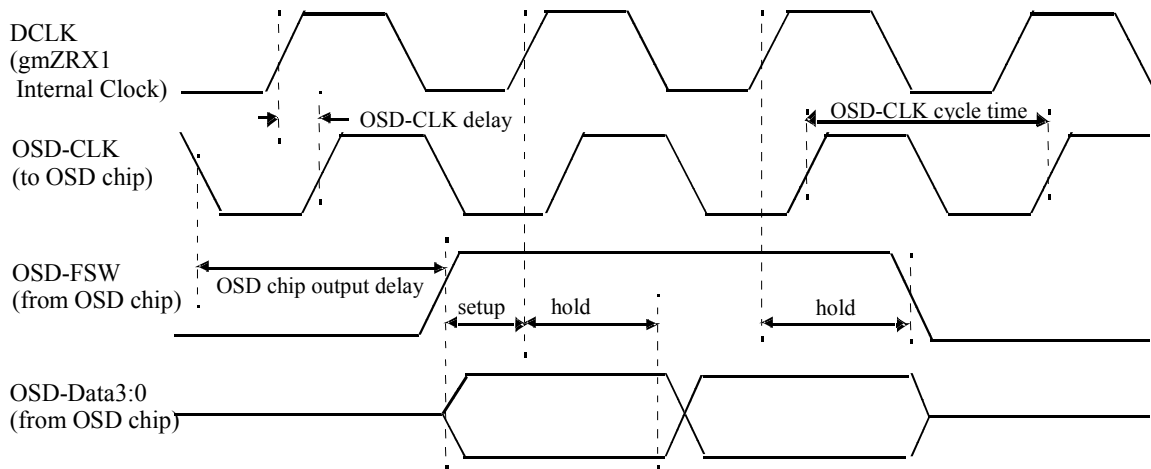
The gmZAN1 supports an external OSD controller for monitor vendors who wish to maintain a specific user interface, or the look and feel consistent with some previous device. Only those OSD controllers that are developed for a flat-panel monitor application and have a pixel-clock input pin are supported. As is the case with an on-chip OSD, the OSD window size is not affected by scaling.

An external OSD controller is connected to the gmZAN1 chip as shown in Table 17.

**Table 17. Pin Connection Between the gmZAN1 and an External OSD controller**

gmZAN1 Pin Name (Pin#, in/out)	External OSD Controller Pin (in/out)	Polarity	Position
OSD-HREF (#115, output)	HSync (input)	Programmable	Active during horizontal blanking period.
OSD-VREF (#116, output)	VSyn (input)	Programmable	Active during vertical blanking period.
OSD-CLK (#117, output)	Pixel Clock (input)		
OSD-FSW (#122, input)	OSD Window Indicator (output)	Programmable	Horizontal: M OSD-CLK cycles after the HREF for N pixels. Vertical: M' HREF pulses after the VREF for N' lines (M, N, M',N' programmed to external OSD chip)
OSD-DATA[3:0] (#118~#121, inputs)	Intensity, R, G, and B (outputs)		

The four-bit data from an external OSD controller becomes one of the 16 entries to the OSD look-up table (LUT), which is 12 bits wide (4 bits/color).

**Figure 14. External OSD Interface Data Latch Timing**


OSD-CLK delay = 3 ns default. Additional 0 ~ 12 ns delay can be added.

OSD-FSW/OSD-DATA setup/hold time = 1.5 ns min.

OSD-CLK cycle time = 95 MHz max.

When the external OSD controller interface enabled, data from the OSD LUT is displayed on a TFT panel instead of the ADC output whenever the OSD-FSW signal is active.

The OSD-CLK output to an external OSD controller chip is derived from the DCLK (destination clock) whose clock frequency is the same as the panel clock in frequency (or twice the panel clock frequency on a two-pixels-per-clock panel). The maximum frequency is 120 MHz.

Both the OSD Data and OSD-FSW signals are latched by gmZAN1 on the rising edge of the DCLK. To maximize the setup/ hold time for the OSD-Data and OSD-FSW signal, a delay of up to 6 ns can be added to the OSD-CLK.

**Table 18. External OSD Interface Timing Parameters**

Parameter	minimum	typical	maximum
OSD-CLK Frequency			95 MHz
OSD-FSW/OSD-DATA setup time	1.5 ns		
OSD-FSW/OSD-DATA hold time	1.5 ns		
OSD-CLK delay from DCLK		0 ~ 5.6 ns, programmable in 800-ps increment	
OSD-HREF delay from DCLK		0 ~ 12 ns, programmable in 800-ps increment	
OSD-CLK/DCLK ratio		1/4x, 1/2x, 1x, programmable	

The external-OSD window position is referenced to the edge of the OSD-HREF and OSD-VREF. The horizontal start position is defined in terms of OSD-CLK pulse counts. The vertical position is defined in terms of OSD-HREF pulse counts. These values must be programmed into an external OSD controller chip.

The trailing edge of OSD-HREF and OSD-VREF are always positioned at the beginning of a display period. Thus, the external OSD window position will stay at the same place regardless of input resolution and refresh rate.

Enabling and configuring the external OSD interface and writing to the OSD LUT is achieved using API calls.

## 2.9 On-chip TCLK Oscillator

The gmZAN1 on-chip TCLK oscillator circuitry is a custom designed circuit that supports the use of an external oscillator or an external crystal resonator to generate a reference frequency source for the gmZAN1 device. When used with an external crystal resonator, the oscillator circuit provides a very low jitter and very low harmonic clock to the internal circuitry of the gmZAN1. The on-chip oscillator circuit also minimizes the overdrive of the crystal, which reduces the aging of the crystal.

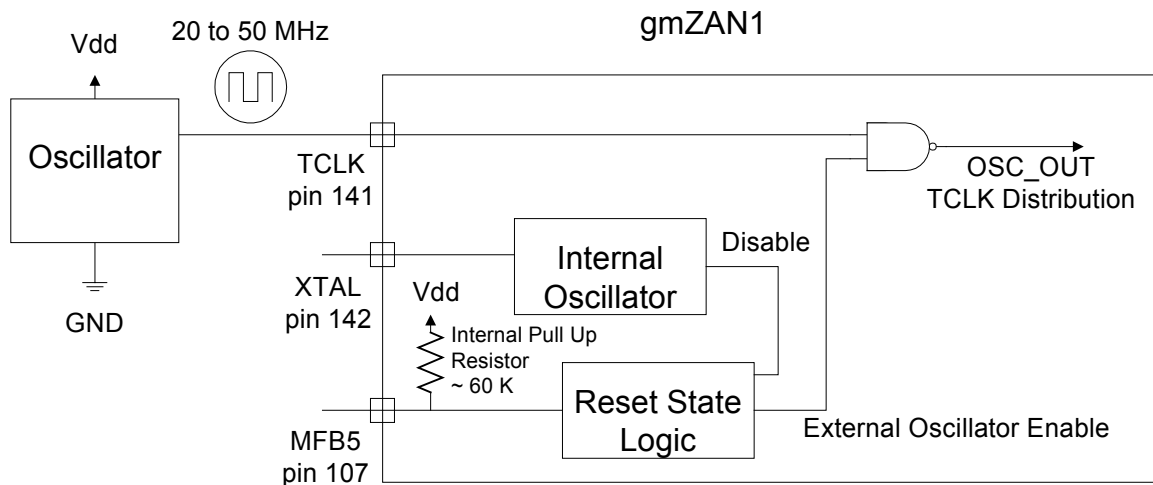
The requirements for the TCLK signal are shown below.

**Table 19. TCLK Specification**

Frequency	20 MHz to 50 MHz
Jitter	250 ps maximum
Rise Time (10% to 90%)	5 ns
Duty Cycle	40-60

### 2.9.1 External Oscillator mode

The first mode of operation of the TCLK circuitry is the external oscillator mode. When the gmZAN1 is in reset, the state of the MFB5 (pin 107) is sampled. If the pin is pulled high to Vdd (there is an internal 60K Ohm pull up resistor on this pin) the external oscillator mode is enabled. In this mode the internal oscillator circuit is disabled and the external oscillator signal that is connected to the TCLK (pin 141) is routed to an internal clock buffer as shown in figure 15.

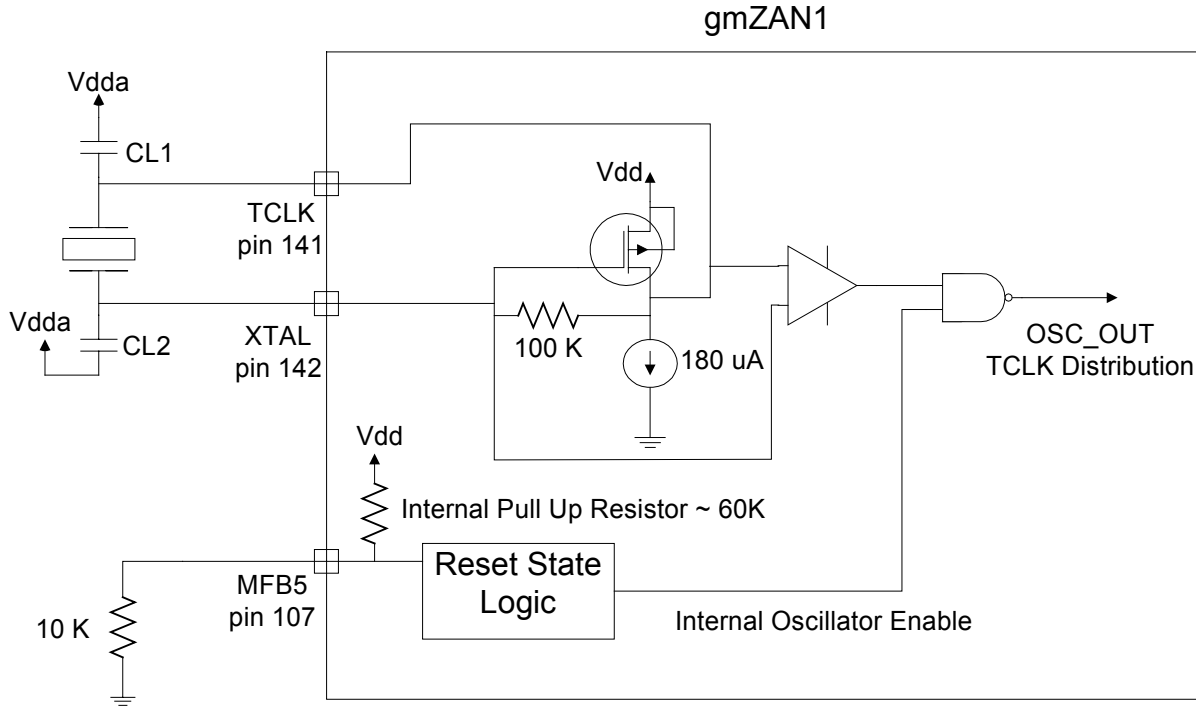


**Figure 15. Using an External Oscillator**

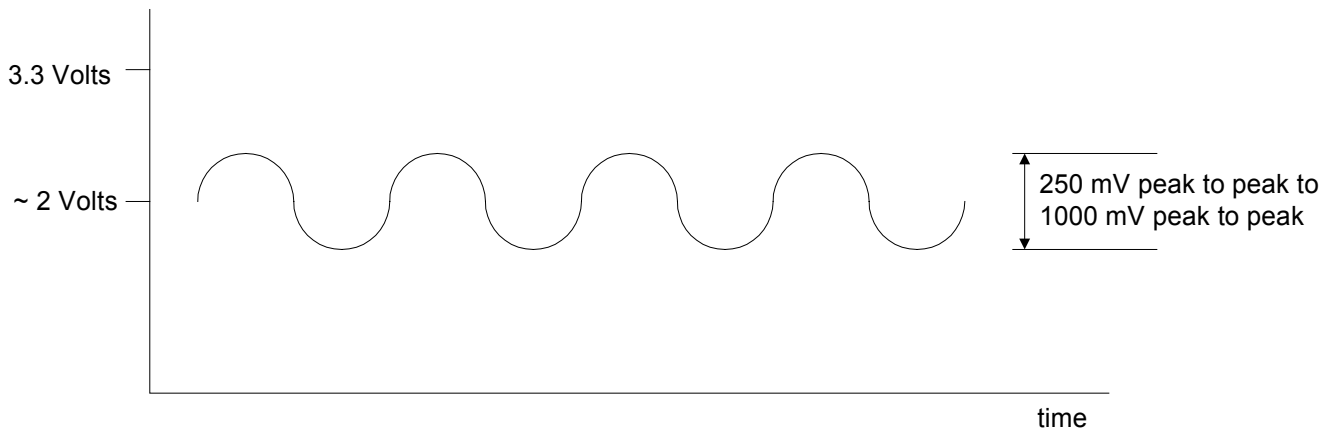
### 2.9.2 Internal Oscillator mode

The second mode of operation for the TCLK circuitry is the internal oscillator mode. When the gmZAN1 is in reset, the state of the pin MFB5 (pin 107) is sampled. If the pin is pulled low by connecting the pin directly to GND, or by connecting the pin to GND through a pull down resistor, the internal oscillator is enabled. The maximum value of the pull down resistor is 15K Ohm. In this mode, an external crystal resonator is connected between the XTAL (pin 142) and the TCLK (pin 141) with the appropriately sized loading capacitors  $C_{L1}$  and  $C_{L2}$ . The sizes of  $C_{L1}$  and  $C_{L2}$  are determined from the crystal manufacturer's specification and by compensating for the parasitic capacitance of the gmZAN1 device and the printed circuit board traces. The loading capacitors are terminated to the Vdda power supply. This connection increases the power supply rejection ratio when compared to terminating the loading capacitors to ground.

The oscillator circuit is a Pierce Oscillator circuit and a simplified schematic is shown in Figure 16. The output of the oscillator circuit, measured at the TCLK (pin 141), is an approximate sine wave with a bias of about 2 volts above ground (see Figure 17). The peak-to-peak voltage of the output can range from 250 mV to 1000 mV depending on the specific characteristics of the external crystal used and variation in the oscillator characteristics. The output of the oscillator is connected to a comparator that converts the sine wave to a square wave. The comparator requires a minimum signal level of about 50mV peak-to-peak to function correctly. The output of the comparator is buffered and is then distributed to the gmZAN1 circuits.

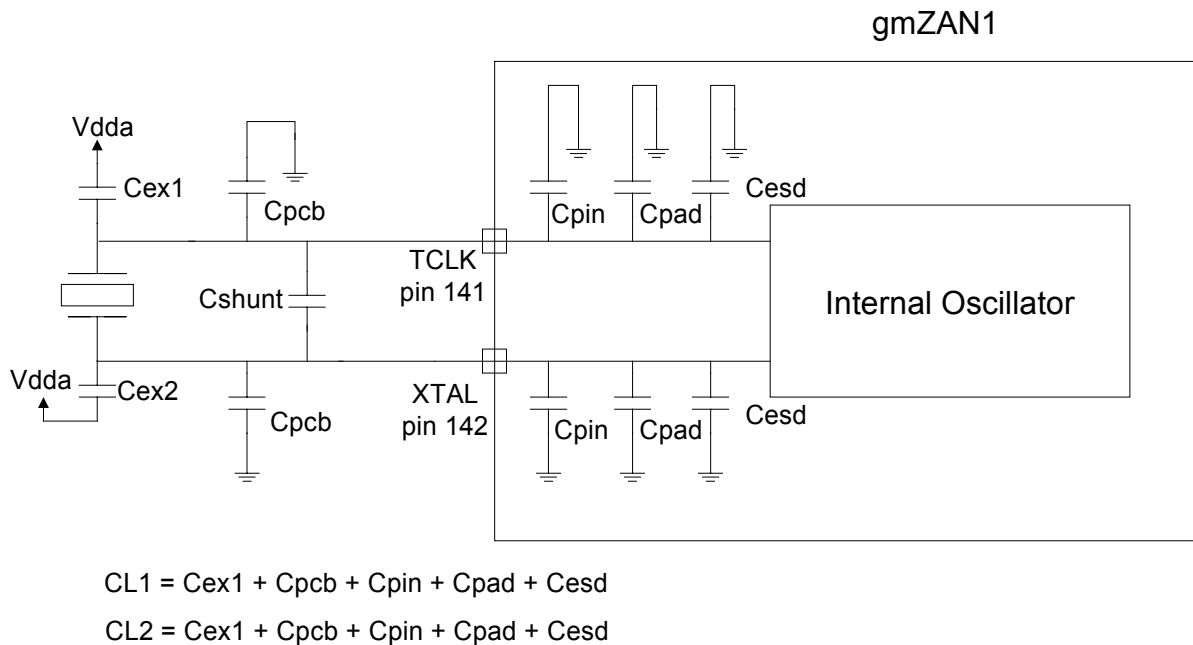


**Figure 16. Using an Internal Oscillator**



**Figure 17. Internal Oscillator output at TCLK**

One of the design parameters that must be given some consideration is the value of the loading capacitors used with the crystal.



**Figure 18. Parasitic Capacitance Sources**

The loading capacitance ( $C_{load}$ ) on the external crystal is the combination of  $C_{L1}$  and  $C_{L2}$  and is calculated by:  $C_{load} = ((C_{L1} * C_{L2}) / (C_{L1} + C_{L2})) + C_{shunt}$ .

The shunt capacitance  $C_{shunt}$  is the effective capacitance between the XTAL and TCLK pins. For the gmZAN1 this is approximately 9 pF.

$C_{L1}$  and  $C_{L2}$  are a parallel combination of the external loading capacitors ( $C_{ex}$ ), the PCB board capacitance ( $C_{PCB}$ ), the pin capacitance ( $C_{pin}$ ), the pad capacitance ( $C_{pad}$ ), and the ESD protection capacitance ( $C_{ESD}$ ). The capacitances are symmetrical so that  $C_{L1} = C_{L2} = C_{ex} + C_{PCB} + C_{pin} + C_{pad} + C_{ESD}$ . The correct value of  $C_{ex}$  must be calculated given the value of the parasitics.

$C_{PCB} \sim$  Layout dependent. Approximately 2 pF to 10 pF

$C_{pin} \sim 1.1$  pF

$C_{pad} \sim 1$  pF

$C_{ESD} \sim 5.3$  pF

$C_{shunt} \sim 9$  pF



Some attention must be given to the details of the oscillator circuit when used with an external crystal resonator. The value of  $C_{load}$  that is specified by the manufacturer should not be exceeded because of potential start up problems with the oscillator. Additionally, the external crystal used should be a parallel resonate cut and the value of the equivalent series resistance must be less than 90 Ohms.

### 3. ELECTRICAL CHARACTERISTICS

**Table 20. Absolute Ratings**

Parameter	Min.	Typ.	Max.	Note
PVDD			5.6 volts	
CVDD			5.6 volts	
Vin	Vss - 0.5volt		Vcc + 0.5V	
Operating temperature	0 degreeC		70 degreeC	
Storage temperature	-65 degreeC		150 degreeC	
Maximum power consumption at XGA resolution output			1.8 Watts	

**Table 21. DC Electrical Characteristic**

Parameter	Min.	Typ.	Max.	Note
PVDD	3.15 volts	3.3 volts	3.47 volts	
CVDD	3.15 volts	3.3 volts	3.47 volts	
Vil (CMOS inputs)			0.3 * CVDD	
Vil (TTL inputs)			0.8 volts	
Vih (CMOS inputs)	0.7 * CVDD		1.1 * CVDD	
Vih (TTL inputs)	2.0 volts		5.0+ 0.5 volts	(1)
Voh	2.4 volts		CVDD	
Vol		0.2 volts	0.4 volts	
Input Current	-10 uA		10 uA	
PVDD operating supply current	0 mA		20 mA/pad @ 10pF	(2)
CVDD operating supply current	0 mA		500 mA	(3)

NOTE 1: 5V-Tolerant TTL Input pads are as follows:

- **CRT Interface:** HSYNC (pin #150), VSYNC (#148)
- **Host Interface:** HFS (#98), HCLK (#103), HDATA (#99), RESETN (#100), MFB[11:0]: MFB11 (#123), MFB10 (#124), MFB9 (#102), MFB8 (#104), MFB7 (#105), MFB6 (#106), MFB5(#107),MFB4 (#109), MFB3 (#110), MFB2 (#111), MFB1 (#112), MFB0 (#113)
- **OSD Interface:** OSD\_DATA3 (#121), OSD\_DATA2 (#120), OSD\_DATA1 (#119), OSD\_DATA0 (#118), OSD\_FSW (#122)
- **Non-5V-Tolerant TTL Input Pad is:** TCLK (#141)

NOTE 2: When the panel interface is disabled, the supply current is 0 mA. The drive current of each pad can be programmed in the range of 2 mA to 20 mA (@capacitive loading = 10 pF).

NOTE 3: When all circuits are powered down and TCLK is stopped, the CVDD supply current becomes 0mA.

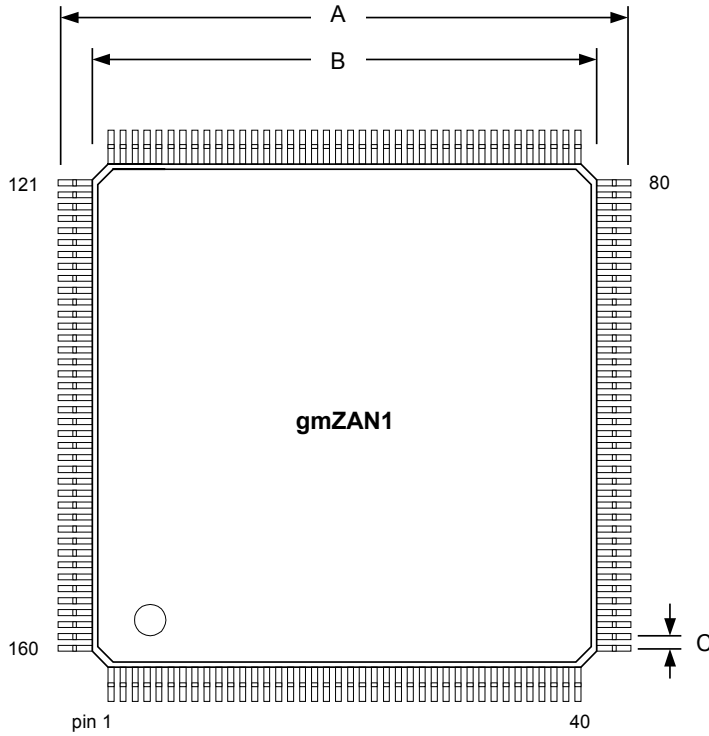


## 4. ORDERING INFORMATION

Order Code	Package	Temperature Rating
gmZAN1	160-pin PQFP	Commercial 0°C to 70°C

## 5. MECHANICAL DIMENSIONS

**Figure 19. 160 pin PQFP Package Dimensions**



Symbol	Millimeter			Inch		
	Min	Nom	Max	Min	Nom	Max
A	30.95	31.20	31.45	1.218	1.228	1.238
B	27.90	28.00	28.10	1.098	1.102	1.106
C		0.65			0.026	
D			4.25			0.167
E		1.60			0.063	
G	3.17	3.32	3.47	0.125	0.131	0.137
H	0.65	0.80	0.95	0.025	0.031	0.037
I	0.05	0.25	0.50	0.002	0.010	0.020
J	0		7	0		7
L	0.20	0.30	0.40	0.008	0.012	0.016
M	0.10	0.15	0.20	0.004	0.006	0.008

Depressed dot on package indicates pin 1 (lower left corner)

