
HM5116160A Series

HM5118160A Series

1048576-word × 16-bit Dynamic Random Access Memory

HITACHI

ADE-203-208C (Z)

Rev. 3.0

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Description

The Hitachi HM5116160A Series, HM5118160A Series are CMOS dynamic RAMs organized as 1,048,576-word × 16-bit. They employ the most advanced CMOS technology for high performance and low power. The HM5116160A Series, HM5118160A Series offer Fast Page Mode as a high speed access mode. They have package variations of 42-pin plastic SOJ and 50-pin plastic TSOP II.

Features

- Single 5 V ($\pm 10\%$)
- High speed
 - Access time: 60 ns/70 ns/80 ns (max)
- Low power dissipation
 - Active mode: 550 mW/495 mW/440 mW (max) (HM5116160A Series)
935 mW/825 mW/715 mW (max) (HM5118160A Series)
 - Standby mode : 11 mW (max)
: 0.83 mW (max) (L-version)
- Fast page mode capability
- Long refresh period
 - 4096 refresh cycles : 64 ms (HM5116160A Series)
: 128 ms (L-version)
 - 1024 refresh cycles : 16 ms (HM5118160A Series)
: 128 ms (L-version)
- 4 variations of refresh
 - RAS-only refresh
 - CAS-before-RAS refresh
 - Hidden refresh
 - Self refresh (L-version)
- 2CAS-byte control
- Battery backup operation (L-version)

This specification is fully compatible with the 16-Mbit DRAM specifications from TEXAS INSTRUMENTS.



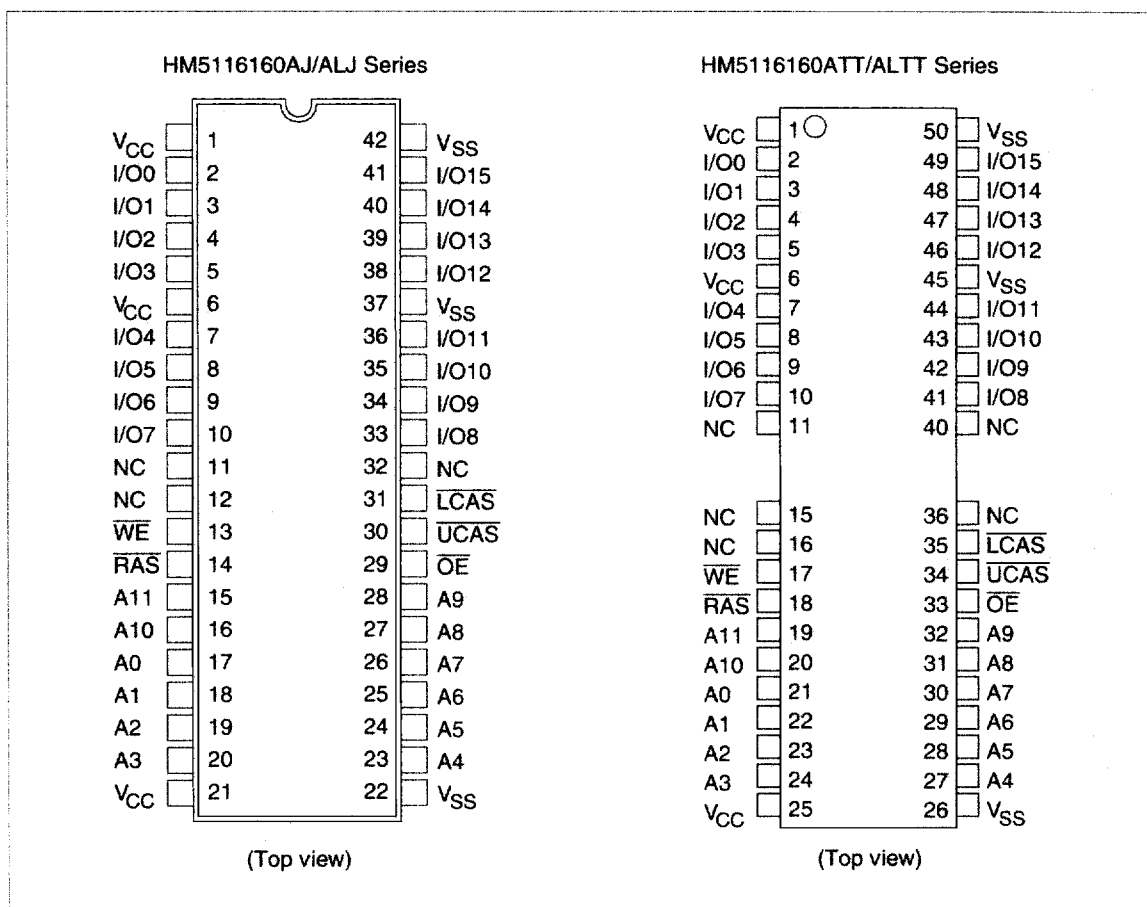
HM5116160A Series, HM5118160A Series

Ordering Information

Type No.	Access time	Package
HM5116160AJ-6	60 ns	400-mil 42-pin plastic SOJ (CP-42D)
HM5116160AJ-7	70 ns	
HM5116160AJ-8	80 ns	
HM5116160ALJ-6	60 ns	
HM5116160ALJ-7	70 ns	
HM5116160ALJ-8	80 ns	
HM5118160AJ-6	60 ns	
HM5118160AJ-7	70 ns	
HM5118160AJ-8	80 ns	
HM5118160ALJ-6	60 ns	
HM5118160ALJ-7	70 ns	
HM5118160ALJ-8	80 ns	
HM5116160ATT-6	60 ns	400-mil 50-pin plastic TSOP II (TTP-50/44DC)
HM5116160ATT-7	70 ns	
HM5116160ATT-8	80 ns	
HM5116160ALTT-6	60 ns	
HM5116160ALTT-7	70 ns	
HM5116160ALTT-8	80 ns	
HM5118160ATT-6	60 ns	
HM5118160ATT-7	70 ns	
HM5118160ATT-8	80 ns	
HM5118160ALTT-6	60 ns	
HM5118160ALTT-7	70 ns	
HM5118160ALTT-8	80 ns	

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Pin Arrangement

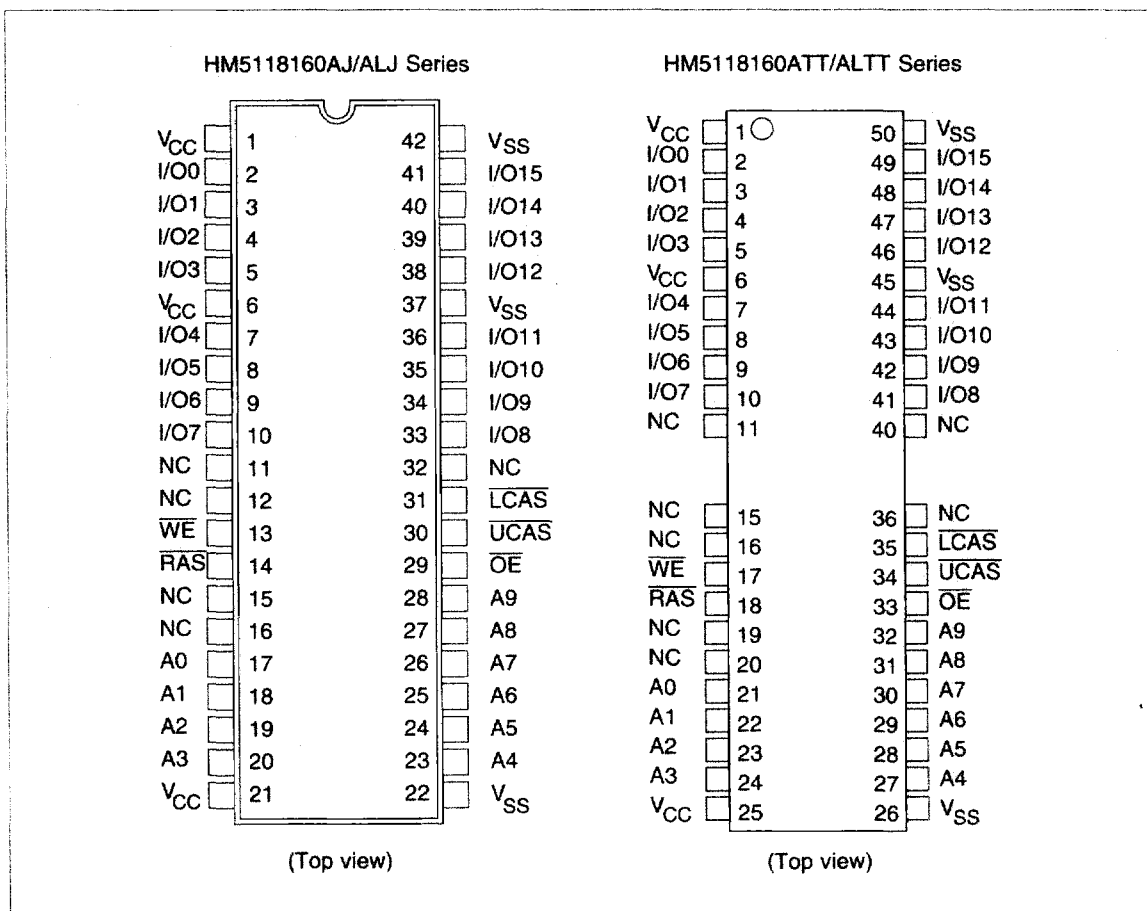


Pin Description

Pin name	Function
A0 to A11	Address input — Row/Refresh address A0 to A11 — Column address A0 to A7
I/O0 to I/O15	Data input/Data output
$\overline{\text{RAS}}$	Row address strobe
UCAS, LCAS	Column address strobe
WE	Read/Write enable
$\overline{\text{OE}}$	Output enable
V _{cc}	Power supply
V _{ss}	Ground
NC	No connection

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Pin Arrangement

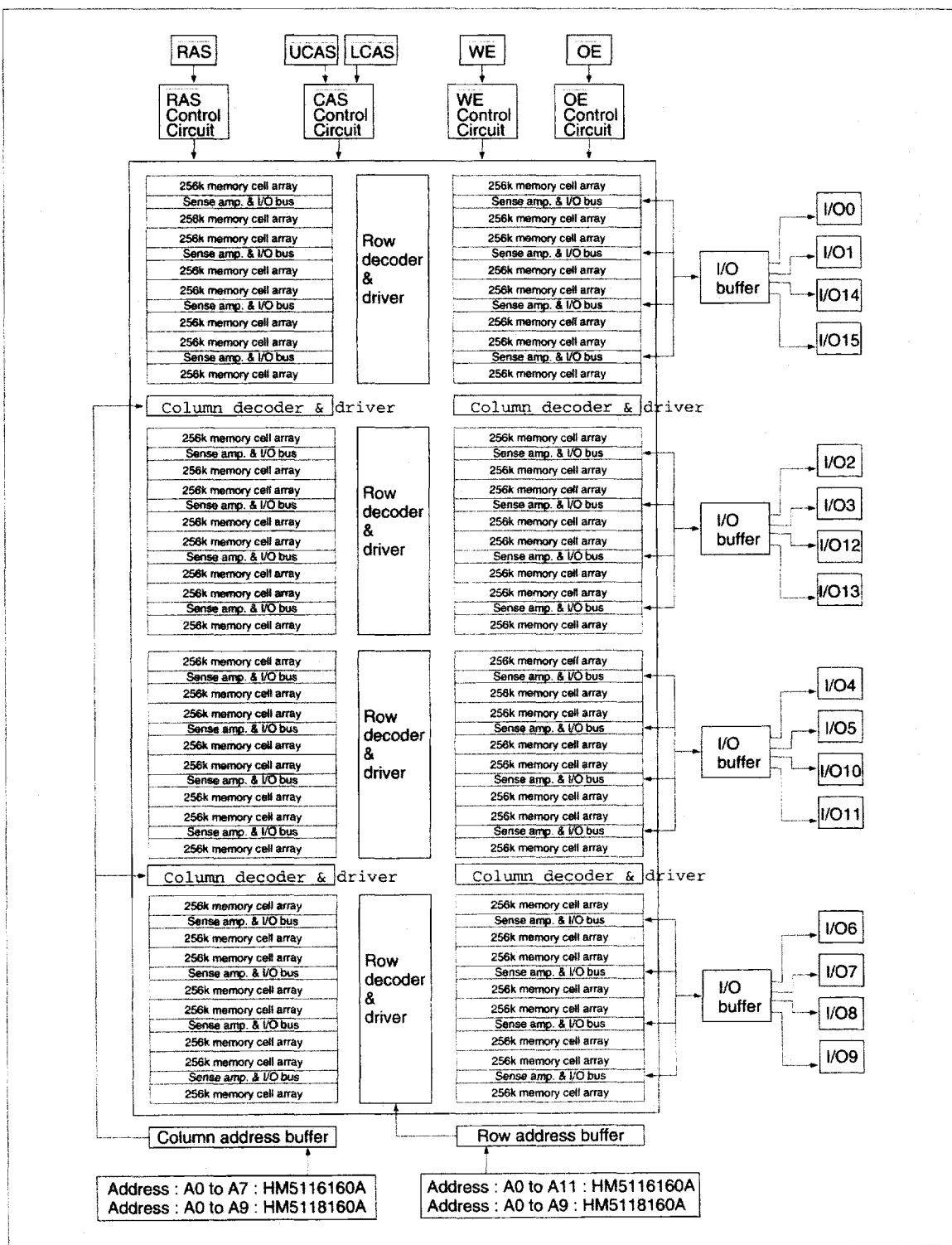


Pin Description

Pin name	Function
A0 to A9	Address input — Row/Refresh address A0 to A9 — Column address A0 to A9
I/O0 to I/O15	Data input/Data output
RAS	Row address strobe
UCAS, LCAS	Column address strobe
WE	Read/Write enable
OE	Output enable
V _{CC}	Power supply
V _{SS}	Ground
NC	No connection

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Block Diagram



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Truth Table

RAS	LCAS	UCAS	WE	OE	Output		Operation
H	D	D	D	D	Open		Standby
L	L	H	H	L	Valid	Lower byte	Read cycle
L	H	L	H	L	Valid	Upper byte	
L	L	L	H	L	Valid	Word	
L	L	H	L* ²	D	Open	Lower byte	Early write cycle
L	H	L	L* ²	D	Open	Upper byte	
L	L	L	L* ²	D	Open	Word	
L	L	H	L* ²	H	Undefined	Lower byte	Delayed write cycle
L	H	L	L* ²	H	Undefined	Upper byte	
L	L	L	L* ²	H	Undefined	Word	
L	L	H	H to L	L to H	Valid	Lower byte	Read-modify-write cycle
L	H	L	H to L	L to H	Valid	Upper byte	
L	L	L	H to L	L to H	Valid	Word	
L	H	H	D	D	Open	Word	RAS-only refresh cycle
H to L	H	L	D	D	Open	Word	CAS-before-RAS refresh cycle or
H to L	L	H	D	D	Open	Word	Self refresh cycle (L-version)
H to L	L	L	D	D	Open	Word	
L	L	L	H	H	Open		Read cycle (Output disabled)

Notes: 1. H: High (inactive) L: Low (active) D: H or L

2. $t_{wcs} \geq 0$ ns Early write cycle

$t_{wcs} < 0$ ns Delayed write cycle

3. Mode is determined by the OR function of the \overline{UCAS} and \overline{LCAS} . (Mode is set by the earliest of \overline{UCAS} and \overline{LCAS} active edge and reset by the latest of \overline{UCAS} and \overline{LCAS} inactive edge.) However write OPERATION and output HIZ control are done independently by each \overline{UCAS} , \overline{LCAS} .

ex. if $\overline{RAS} = H$ to L , $\overline{UCAS} = H$, $\overline{LCAS} = L$, then \overline{CAS} -before- \overline{RAS} refresh cycle is selected.

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Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Voltage on any pin relative to V_{SS}	V_T	-1.0 to +7.0	V
Supply voltage relative to V_{SS}	V_{CC}	-1.0 to +7.0	V
Short circuit output current	I_{out}	50	mA
Power dissipation	P_T	1.0	W
Operating temperature	T_{opr}	0 to +70	°C
Storage temperature	T_{stg}	-55 to +125	°C

Recommended DC Operating Conditions ($T_a = 0$ to $+70^\circ\text{C}$)

Parameter	Symbol	Min	Typ	Max	Unit	Notes
Supply voltage	V_{CC}	4.5	5.0	5.5	V	1, 2
Input high voltage	V_{IH}	2.4	—	6.5	V	1
Input low voltage	V_{IL}	-1.0	—	0.8	V	1

Notes: 1. All voltage referred to V_{SS}

2. The supply voltage with all V_{CC} pins must be on the same level. The supply voltage with all V_{SS} pins must be on the same level.

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DC Characteristics

($T_a = 0$ to $+70^\circ\text{C}$, $V_{CC} = 5\text{ V} \pm 10\%$, $V_{SS} = 0\text{ V}$) (HM5116160A Series)

Parameter	Symbol	HM5116160A						Unit	Test conditions
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
Operating current**1, *2	I_{CC1}	—	100	—	90	—	80	mA	$t_{RC} = \text{min}$
Standby current	I_{CC2}	—	2	—	2	—	2	mA	TTL interface $\overline{\text{RAS}}, \overline{\text{UCAS}}, \overline{\text{LCAS}} = V_{IH}$ Dout = High-Z
		—	1	—	1	—	1	mA	CMOS interface $\overline{\text{RAS}}, \overline{\text{UCAS}},$ $\overline{\text{LCAS}} \geq V_{CC} - 0.2\text{ V}$ Dout = High-Z
Standby current (L-version)	I_{CC2}	—	150	—	150	—	150	μA	CMOS interface $\overline{\text{RAS}}, \overline{\text{UCAS}},$ $\overline{\text{LCAS}} \geq V_{CC} - 0.2\text{ V}$ Dout = High-Z
$\overline{\text{RAS}}$ -only refresh current**2	I_{CC3}	—	100	—	90	—	80	mA	$t_{RC} = \text{min}$
Standby current*1	I_{CC5}	—	5	—	5	—	5	mA	$\overline{\text{RAS}} = V_{IH}$ $\overline{\text{UCAS}}, \overline{\text{LCAS}} = V_{IL}$ Dout = enable
$\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh current	I_{CC6}	—	100	—	90	—	80	mA	$t_{RC} = \text{min}$
Fast page mode current*1, *3	I_{CC7}	—	105	—	95	—	85	mA	$t_{PC} = \text{min}$
Battery backup current*4 (Standby with CBR refresh) (L-version)	I_{CC10}	—	500	—	500	—	500	μA	CMOS interface Dout = High-Z CBR refresh: $t_{RC} = 31.3\ \mu\text{s}$ $t_{RAS} \leq 0.3\ \mu\text{s}$
Self refresh mode current (L-version)	I_{CC11}	—	300	—	300	—	300	μA	CMOS interface $\overline{\text{RAS}}, \overline{\text{UCAS}}, \overline{\text{LCAS}} \leq 0.2\text{ V}$ Dout = High-Z
Input leakage current	I_{LI}	-10	10	-10	10	-10	10	μA	$0\text{ V} \leq V_{in} \leq 7\text{ V}$
Output leakage current	I_{LO}	-10	10	-10	10	-10	10	μA	$0\text{ V} \leq V_{out} \leq 7\text{ V}$ Dout = disable
Output high voltage	V_{OH}	2.4	V_{CC}	2.4	V_{CC}	2.4	V_{CC}	V	High Iout = -7 mA
Output low voltage	V_{OL}	0	0.4	0	0.4	0	0.4	V	Low Iout = 4.2 mA

Notes: 1. I_{CC} depends on output load condition when the device is selected. I_{CC} max is specified at the output open condition.

2. Address can be changed once or less while $\overline{\text{RAS}} = V_{IL}$.

3. Address can be changed once or less while $\overline{\text{UCAS}}$ and $\overline{\text{LCAS}} = V_{IH}$.

4. $V_{IH} \geq V_{CC} - 0.2\text{ V}$, $0\text{ V} \leq V_{IL} \leq 0.2\text{ V}$.

HM5116160A Series, HM5118160A Series

DC Characteristics

($T_a = 0$ to $+70^\circ\text{C}$, $V_{CC} = 5\text{ V} \pm 10\%$, $V_{SS} = 0\text{ V}$) (HM5118160A Series)

		HM5118160A							
		-6		-7		-8			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Test conditions
Operating current* ^{1, *2}	I_{CC1}	—	170	—	150	—	130	mA	$t_{RC} = \text{min}$
Standby current	I_{CC2}	—	2	—	2	—	2	mA	TTL interface $\overline{\text{RAS}}, \overline{\text{UCAS}}, \overline{\text{LCAS}} = V_{IH}$ Dout = High-Z
		—	1	—	1	—	1	mA	CMOS interface $\overline{\text{RAS}}, \overline{\text{UCAS}},$ $\overline{\text{LCAS}} \geq V_{CC} - 0.2\text{ V}$ Dout = High-Z
Standby current (L-version)	I_{CC2}	—	150	—	150	—	150	μA	CMOS interface $\overline{\text{RAS}}, \overline{\text{UCAS}},$ $\overline{\text{LCAS}} \geq V_{CC} - 0.2\text{ V}$ Dout = High-Z
RAS-only refresh current* ²	I_{CC3}	—	170	—	150	—	130	mA	$t_{RC} = \text{min}$
Standby current* ¹	I_{CC5}	—	5	—	5	—	5	mA	$\overline{\text{RAS}} = V_{IH}$ $\overline{\text{UCAS}}, \overline{\text{LCAS}} = V_{IL}$ Dout = enable
CAS-before-RAS refresh current	I_{CC6}	—	170	—	150	—	130	mA	$t_{RC} = \text{min}$
Fast page mode current* ^{1, *3}	I_{CC7}	—	170	—	150	—	130	mA	$t_{PC} = \text{min}$
Battery backup current* ⁴ (Standby with CBR refresh) (L-version)	I_{CC10}	—	500	—	500	—	500	μA	CMOS interface Dout = High-Z CBR refresh: $t_{RC} = 125\ \mu\text{s}$ $t_{RAS} \leq 0.3\ \mu\text{s}$
Self refresh mode current (L-version)	I_{CC11}	—	300	—	300	—	300	μA	CMOS interface $\overline{\text{RAS}}, \overline{\text{UCAS}}, \overline{\text{LCAS}} \leq 0.2\text{ V}$ Dout = High-Z
Input leakage current	I_{LI}	-10	10	-10	10	-10	10	μA	$0\text{ V} \leq V_{in} \leq 7\text{ V}$
Output leakage current	I_{LO}	-10	10	-10	10	-10	10	μA	$0\text{ V} \leq V_{out} \leq 7\text{ V}$ Dout = disable
Output high voltage	V_{OH}	2.4	V_{CC}	2.4	V_{CC}	2.4	V_{CC}	V	High Iout = -7 mA
Output low voltage	V_{OL}	0	0.4	0	0.4	0	0.4	V	Low Iout = 4.2 mA

Notes: 1. I_{CC} depends on output load condition when the device is selected. I_{CC} max is specified at the output open condition.

2. Address can be changed once or less while $\overline{\text{RAS}} = V_{IL}$.

3. Address can be changed once or less while $\overline{\text{UCAS}}$ and $\overline{\text{LCAS}} = V_{IH}$.

4. $V_{IH} \geq V_{CC} - 0.2\text{ V}$, $0\text{ V} \leq V_{IL} \leq 0.2\text{ V}$.

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Capacitance (Ta = 25°C, VCC = 5 V ± 10 %)

Parameter	Symbol	Typ	Max	Unit	Notes
Input capacitance (Address)	C _{I1}	—	5	pF	1
Input capacitance (Clocks)	C _{I2}	—	7	pF	1
Output capacitance (Data-in, Data-out)	C _{VO}	—	7	pF	1, 2

Notes : 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.
2. \overline{UCAS} and $\overline{LCAS} = V_{IH}$ to disable Dout.

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AC Characteristics ($T_a = 0$ to $+70^\circ\text{C}$, $V_{CC} = 5\text{ V} \pm 10\%$, $V_{SS} = 0\text{ V}$) *1. *2. *18. *19. *20

Test Conditions

- Input rise and fall time: 5 ns
- Input timing reference levels: 0.8 V, 2.4 V
- Output timing reference levels: 0.4 V, 2.4 V
- Output load: 2 TTL gate + C_L (100 pF) (Including scope and jig)

Read, Write, Read-Modify-Write and Refresh Cycles (Common parameters)

Parameter	Symbol	HM5116160A/HM5118160A						Unit	Notes
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
Random read or write cycle time	t_{RC}	110	—	130	—	150	—	ns	
$\overline{\text{RAS}}$ precharge time	t_{RP}	40	—	50	—	60	—	ns	
$\overline{\text{CAS}}$ precharge time	t_{CP}	10	—	10	—	10	—	ns	
$\overline{\text{RAS}}$ pulse width	t_{RAS}	60	10000	70	10000	80	10000	ns	
$\overline{\text{CAS}}$ pulse width	t_{CAS}	15	10000	18	10000	20	10000	ns	
Row address setup time	t_{ASR}	0	—	0	—	0	—	ns	
Row address hold time	t_{RAH}	10	—	10	—	10	—	ns	
Column address setup time	t_{ASC}	0	—	0	—	0	—	ns	21
Column address hold time	t_{CAH}	10	—	15	—	15	—	ns	21
$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ delay time	t_{RCD}	20	45	20	52	20	60	ns	3
$\overline{\text{RAS}}$ to column address delay time	t_{RAD}	15	30	15	35	15	40	ns	4
$\overline{\text{RAS}}$ hold time	t_{RSH}	15	—	18	—	20	—	ns	
$\overline{\text{CAS}}$ hold time	t_{CSH}	60	—	70	—	80	—	ns	23
$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ precharge time	t_{CRP}	5	—	5	—	5	—	ns	22
$\overline{\text{OE}}$ to Din delay time	t_{OED}	15	—	18	—	20	—	ns	5
$\overline{\text{OE}}$ delay time from Din	t_{DZO}	0	—	0	—	0	—	ns	6
$\overline{\text{CAS}}$ delay time from Din	t_{DZC}	0	—	0	—	0	—	ns	6
Transition time (rise and fall)	t_T	3	50	3	50	3	50	ns	7

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Read Cycle

Parameter	Symbol	HM5116160A/HM5118160A						Unit	Notes
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
Access time from $\overline{\text{RAS}}$	t_{RAC}	—	60	—	70	—	80	ns	8, 9
Access time from $\overline{\text{CAS}}$	t_{CAC}	—	15	—	18	—	20	ns	9, 10, 17
Access time from address	t_{AA}	—	30	—	35	—	40	ns	9, 11, 17
Access time from $\overline{\text{OE}}$	t_{OEA}	—	15	—	18	—	20	ns	9, 25
Read command setup time	t_{RCS}	0	—	0	—	0	—	ns	
Read command hold time to $\overline{\text{CAS}}$	t_{RCH}	0	—	0	—	0	—	ns	12, 22
Read command hold time to $\overline{\text{RAS}}$	t_{RRH}	5	—	5	—	5	—	ns	12
Column address to $\overline{\text{RAS}}$ lead time	t_{RAL}	30	—	35	—	40	—	ns	
Column address to $\overline{\text{CAS}}$ lead time	t_{CAL}	30	—	35	—	40	—	ns	
$\overline{\text{CAS}}$ to output in low-Z	t_{CLZ}	0	—	0	—	0	—	ns	
Output data hold time	t_{OH}	3	—	3	—	3	—	ns	
Output data hold time from $\overline{\text{OE}}$	t_{OHO}	3	—	3	—	3	—	ns	
Output buffer turn-off time	t_{OFF}	—	15	—	15	—	15	ns	13
Output buffer turn-off to $\overline{\text{OE}}$	t_{OEZ}	—	15	—	15	—	15	ns	13
$\overline{\text{CAS}}$ to Din delay time	t_{CDD}	15	—	18	—	20	—	ns	5

Write Cycle

Parameter	Symbol	HM5116160A/HM5118160A						Unit	Notes
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
Write command setup time	t_{WCS}	0	—	0	—	0	—	ns	14, 21
Write command hold time	t_{WCH}	10	—	15	—	15	—	ns	21
Write command pulse width	t_{WCP}	10	—	10	—	10	—	ns	
Write command to $\overline{\text{RAS}}$ lead time	t_{RWL}	15	—	18	—	20	—	ns	
Write command to $\overline{\text{CAS}}$ lead time	t_{CWL}	15	—	18	—	20	—	ns	23
Data-in setup time	t_{DS}	0	—	0	—	0	—	ns	15, 23
Data-in hold time	t_{DH}	10	—	15	—	15	—	ns	15, 23

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Read-Modify-Write Cycle

Parameter	Symbol	HM5116160A/HM5118160A						Unit	Notes
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
Read-modify-write cycle time	t_{RWC}	155	—	181	—	205	—	ns	
RAS to \overline{WE} delay time	t_{RWD}	85	—	98	—	110	—	ns	14
CAS to \overline{WE} delay time	t_{CWD}	40	—	46	—	50	—	ns	14
Column address to \overline{WE} delay time	t_{AWD}	55	—	63	—	70	—	ns	14
OE hold time from \overline{WE}	t_{OEH}	15	—	18	—	20	—	ns	

Refresh Cycle

Parameter	Symbol	HM5116160A/HM5118160A						Unit	Notes
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
CAS setup time (CBR refresh cycle)	t_{CSR}	5	—	5	—	5	—	ns	21
CAS hold time (CBR refresh cycle)	t_{CHR}	10	—	10	—	10	—	ns	22
RAS precharge to CAS hold time	t_{RPC}	0	—	0	—	0	—	ns	21

Fast Page Mode Cycle

Parameter	Symbol	HM5116160A/HM5118160A						Unit	Notes
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
Fast page mode cycle time	t_{PC}	40	—	45	—	50	—	ns	
Fast page mode \overline{RAS} pulse width	t_{RASP}	—	100000	—	100000	—	100000	ns	16
Access time from CAS precharge	t_{CPA}	—	35	—	40	—	45	ns	9, 17, 22
RAS hold time from CAS precharge	t_{CPRH}	35	—	40	—	45	—	ns	

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Fast Page Mode Read-Modify-Write Cycle

Parameter	Symbol	HM5116160A/HM5118160A						Unit	Notes
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
Fast page mode read-modify-write cycle time	t_{PRWC}	85	—	96	—	105	—	ns	
WE delay time from CAS precharge	t_{CPW}	60	—	68	—	75	—	ns	14, 22

Refresh (HM5116160A Series)

Parameter	Symbol	Max	Unit	Note
Refresh period	t_{REF}	64	ms	4096 cycles
Refresh period (L-version)	t_{REF}	128	ms	4096 cycles

Refresh (HM5118160A Series)

Parameter	Symbol	Max	Unit	Note
Refresh period	t_{REF}	16	ms	1024 cycles
Refresh period (L-version)	t_{REF}	128	ms	1024 cycles

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Self Refresh Mode (L-version)

Parameter	Symbol	HM5116160AL/HM5118160AL						Unit	Notes
		-6		-7		-8			
		Min	Max	Min	Max	Min	Max		
$\overline{\text{RAS}}$ pulse width (Self refresh)	t_{RASS}	100	—	100	—	100	—	μs	26
$\overline{\text{RAS}}$ precharge time (Self refresh)	t_{RPS}	110	—	130	—	150	—	ns	
$\overline{\text{CAS}}$ hold time (Self refresh)	t_{CHS}	-50	—	-50	—	-50	—	ns	

- Notes:
- AC measurements assume $t_T = 5 \text{ ns}$.
 - An initial pause of $200 \mu\text{s}$ is required after power up followed by a minimum of eight initialization cycles (any combination of cycles containing $\overline{\text{RAS}}$ -only refresh or $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh). If the internal refresh counter is used, a minimum of eight $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh cycles are required.
 - Operation with the t_{RCD} (max) limit insures that t_{RAC} (max) can be met, t_{RCD} (max) is specified as a reference point only; if t_{RCD} is greater than the specified t_{RCD} (max) limit, then access time is controlled exclusively by t_{CAC} .
 - Operation with the t_{RAD} (max) limit insures that t_{RAC} (max) can be met, t_{RAD} (max) is specified as a reference point only; if t_{RAD} is greater than the specified t_{RAD} (max) limit, then access time is controlled exclusively by t_{AA} .
 - Either t_{OED} or t_{CDD} must be satisfied.
 - Either t_{DZO} or t_{DZC} must be satisfied.
 - V_{IH} (min) and V_{IL} (max) are reference levels for measuring timing of input signals. Also, transition times are measured between V_{IH} (min) and V_{IL} (max).
 - Assumes that $t_{\text{RCD}} \leq t_{\text{RCD}}$ (max) and $t_{\text{RAD}} \leq t_{\text{RAD}}$ (max). If t_{RCD} or t_{RAD} is greater than the maximum recommended value shown in this table, t_{RAC} exceeds the value shown.
 - Measured with a load circuit equivalent to 2 TTL loads and 100 pF. ($V_{\text{OH}} = 2.4 \text{ V}$, $V_{\text{OL}} = 0.4 \text{ V}$)
 - Assumes that $t_{\text{RCD}} \geq t_{\text{RCD}}$ (max) and $t_{\text{RCD}} + t_{\text{CAC}}$ (max) $\geq t_{\text{RAD}} + t_{\text{AA}}$ (max).
 - Assumes that $t_{\text{RAD}} \geq t_{\text{RAD}}$ (max) and $t_{\text{RCD}} + t_{\text{CAC}}$ (max) $\leq t_{\text{RAD}} + t_{\text{AA}}$ (max).
 - Either t_{RCH} or t_{RRH} must be satisfied for a read cycles.
 - t_{OFF} (max) and t_{OEZ} (max) define the time at which the outputs achieve the open circuit condition and are not referred to output voltage levels.
 - t_{WCS} , t_{RWD} , t_{CWD} , t_{AWD} and t_{CPW} are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only; if $t_{\text{WCS}} \geq t_{\text{WCS}}$ (min), the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout the entire cycle; if $t_{\text{RWD}} \geq t_{\text{RWD}}$ (min), $t_{\text{CWD}} \geq t_{\text{CWD}}$ (min), and $t_{\text{AWD}} \geq t_{\text{AWD}}$ (min), or $t_{\text{CWD}} \geq t_{\text{CWD}}$ (min), $t_{\text{AWD}} \geq t_{\text{AWD}}$ (min) and $t_{\text{CPW}} \geq t_{\text{CPW}}$ (min), the cycle is a read-modify-write and the data output will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.
 - These parameters are referred to $\overline{\text{UCAS}}$ and $\overline{\text{LCAS}}$ leading edge in early write cycles and to $\overline{\text{WE}}$ leading edge in delayed write or read-modify-write cycles.
 - t_{RASP} defines $\overline{\text{RAS}}$ pulse width in fast page mode cycles.
 - Access time is determined by the longest among t_{AA} , t_{CAC} and t_{CPA} .
 - In delayed write or read-modify-write cycles, $\overline{\text{OE}}$ must disable output buffer prior to applying data to the device. After $\overline{\text{RAS}}$ is reset, if $t_{\text{OEH}} \geq t_{\text{CWL}}$, the I/O pin will remain open circuit (high impedance); if $t_{\text{OEH}} < t_{\text{CWL}}$, invalid data will be out at each I/O.
 - When both $\overline{\text{UCAS}}$ and $\overline{\text{LCAS}}$ go low at the same time, all 16-bit data are written into the device. $\overline{\text{UCAS}}$ and $\overline{\text{LCAS}}$ cannot be staggered within the same write/read cycles.
 - All the V_{CC} and V_{SS} pins shall be supplied with the same voltages.
 - t_{ASC} , t_{CAH} , t_{RCS} , t_{WCS} , t_{WCH} , t_{CSR} and t_{RPC} are determined by the earlier falling edge of $\overline{\text{UCAS}}$ or $\overline{\text{LCAS}}$.
 - t_{CRP} , t_{CHR} , t_{RCH} , t_{CPA} and t_{CPW} are determined by the later rising edge of $\overline{\text{UCAS}}$ or $\overline{\text{LCAS}}$.
 - t_{CWL} , t_{DH} and t_{DS} should be satisfied by both $\overline{\text{UCAS}}$ and $\overline{\text{LCAS}}$.

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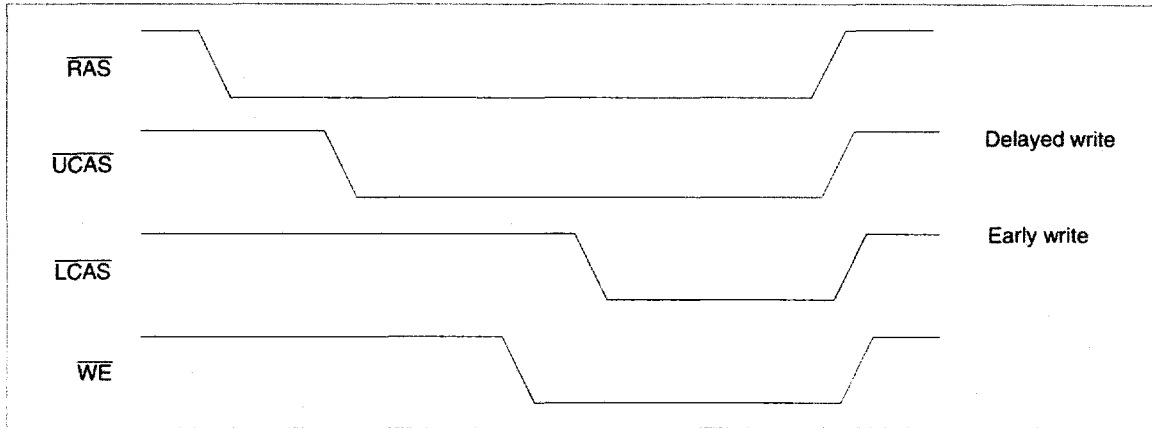
24. t_{CP} is determined by the time that both \overline{UCAS} and \overline{LCAS} are high.
25. When output buffers are enabled once, sustain the low impedance state until valid data is obtained. When output buffer is turned on and off within a very short time, generally it causes large V_{CC}/V_{SS} line noise, which causes to degrade V_{IH} min/ V_{IL} max level.
26. Please do not use t_{RASS} timing, $10 \mu s \leq t_{RASS} \leq 100 \mu s$. During this period, the device is in transition state from normal operation mode to self refresh mode. If $t_{RASS} \geq 100 \mu s$, then \overline{RAS} precharge time should use t_{RPS} instead of t_{RP} .
27. If you use distributed CBR refresh mode with $15.6 \mu s$ interval in normal read/write cycle, CBR refresh should be executed within $15.6 \mu s$ immediately after exiting from and before entering into self refresh mode.
28. If you use \overline{RAS} only refresh or CBR burst refresh mode in normal read/write cycle, 4096 or 1024 cycles (4096 cycles: HM5116160A Series, 1024 cycles: HM5118160A Series) of distributed CBR refresh with $15.6 \mu s$ interval should be executed within 64 or 16 ms (64 ms: HM5116160A, 16 ms: HM5118160A) immediately after exiting from and before entering into the self refresh mode.
29. Repetitive self refresh mode without refreshing all memory is not allowed. Once you exit from self refresh mode, all memory cells need to be refreshed before re-entering the self refresh mode again.
30. H or L (H: $V_{IH}(\min) \leq V_{IN} \leq V_{IH}(\max)$, L: $V_{IL}(\min) \leq V_{IN} \leq V_{IL}(\max)$)
 Invalid Dout

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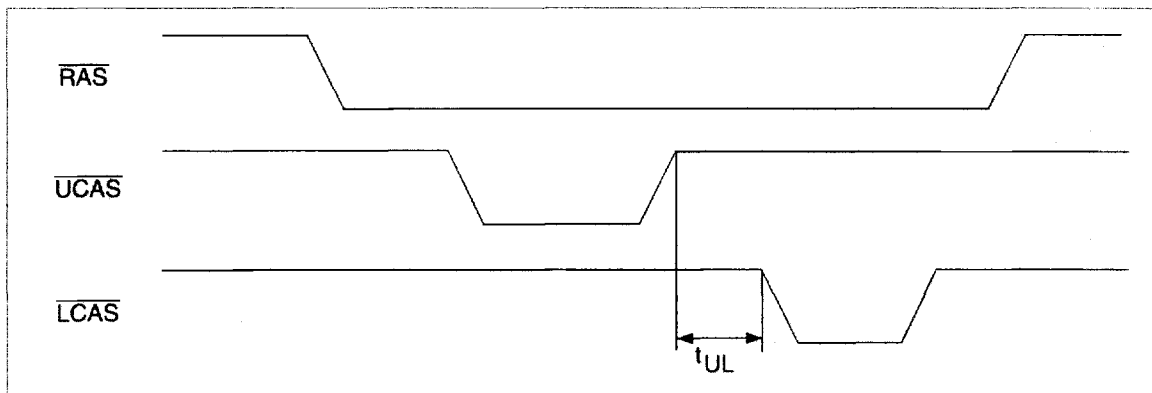
Notes concerning 2CAS control

Please do not separate the UCAS/LCAS operation timing intentionally. However skew between UCAS/LCAS are allowed under the following conditions.

1. Each of the UCAS/LCAS should satisfy the timing specifications individually.
2. Different operation mode for upper/lower byte is not allowed; such as following.



3. Closely separated upper/lower byte control is not allowed. However when the condition ($t_{CP} \leq t_{UL}$) is satisfied, fast page mode can be performed.

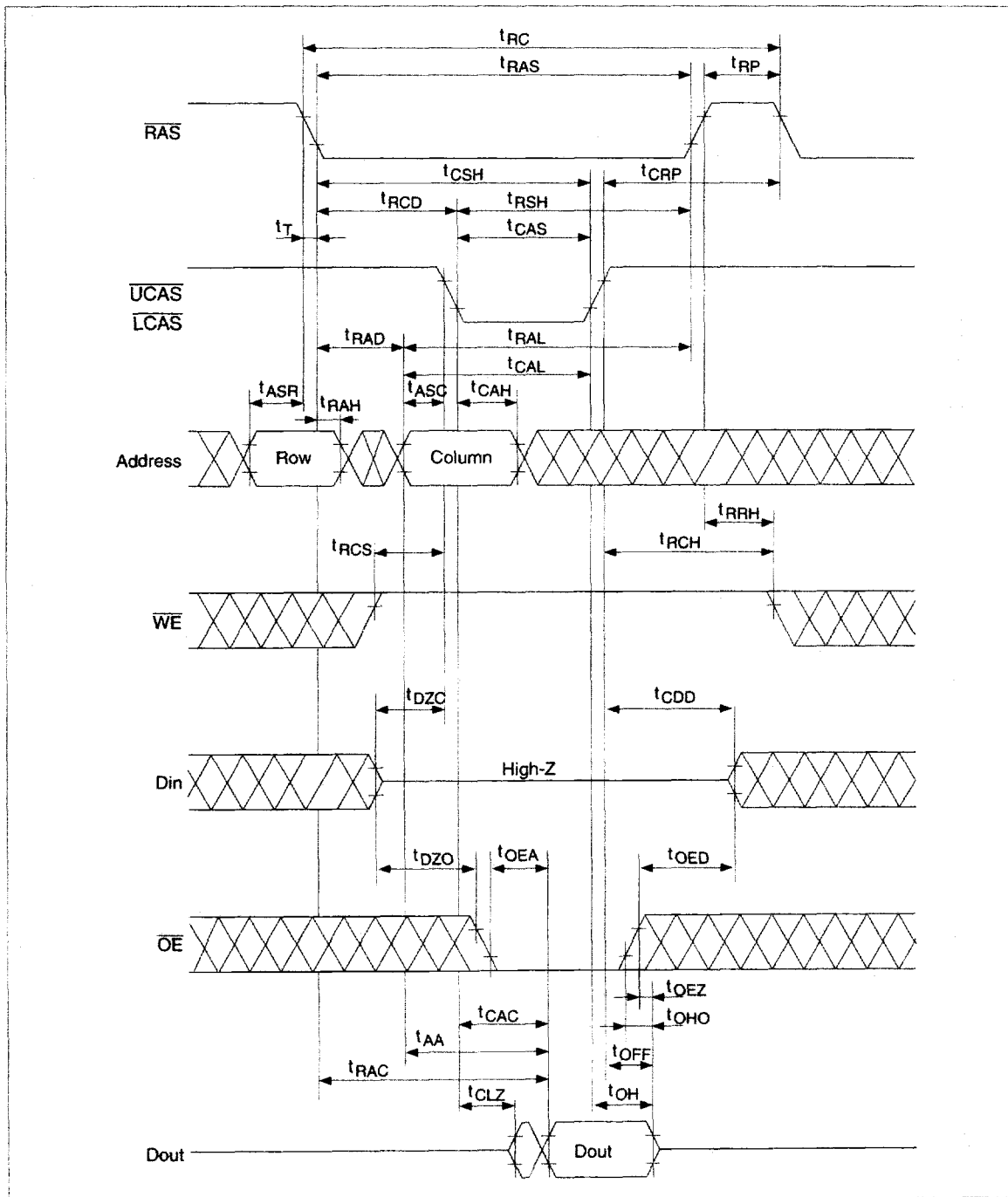


4. Byte control operation by remaining UCAS or LCAS high is guaranteed.

HM5116160A Series, HM5118160A Series

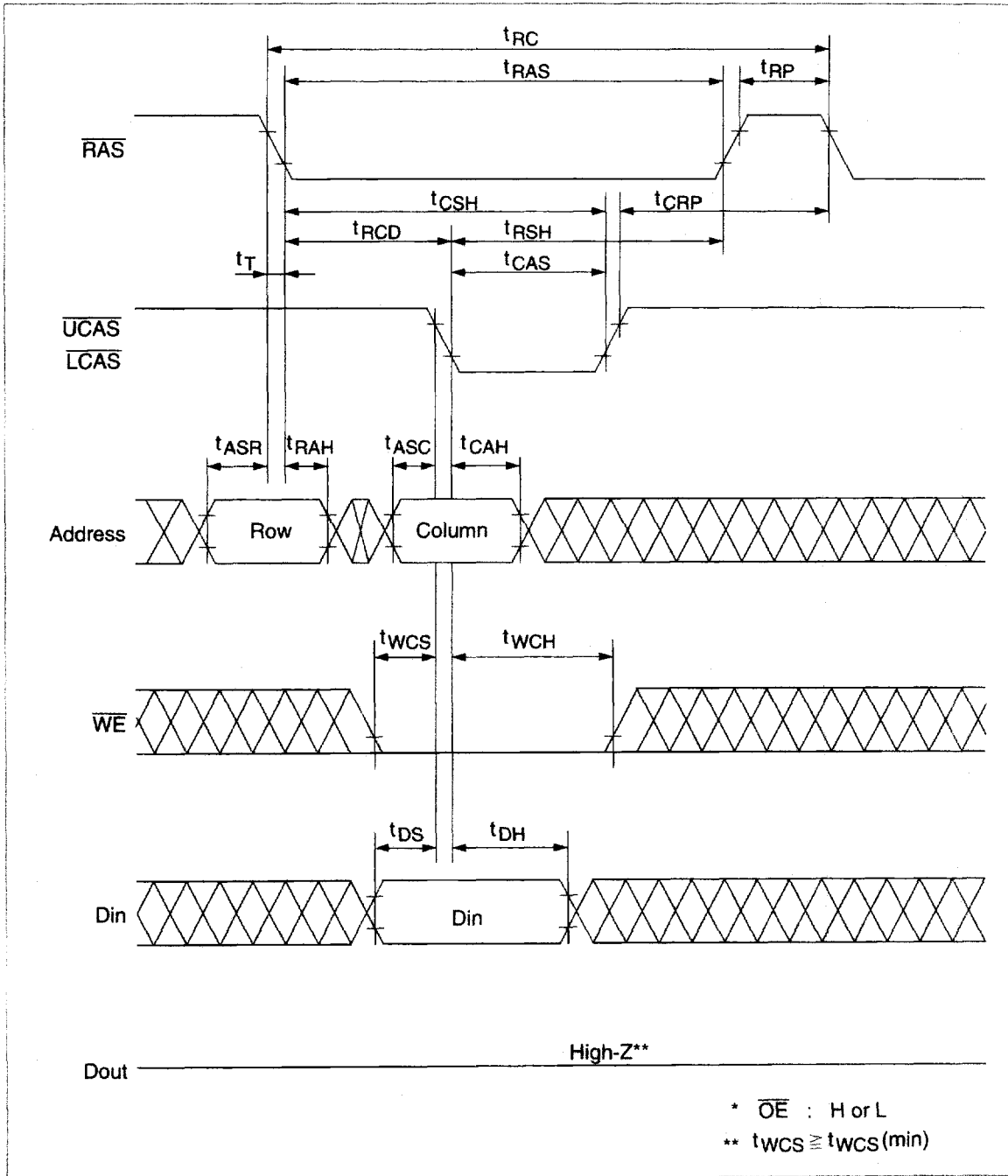
Timing Waveforms*30

Read Cycle



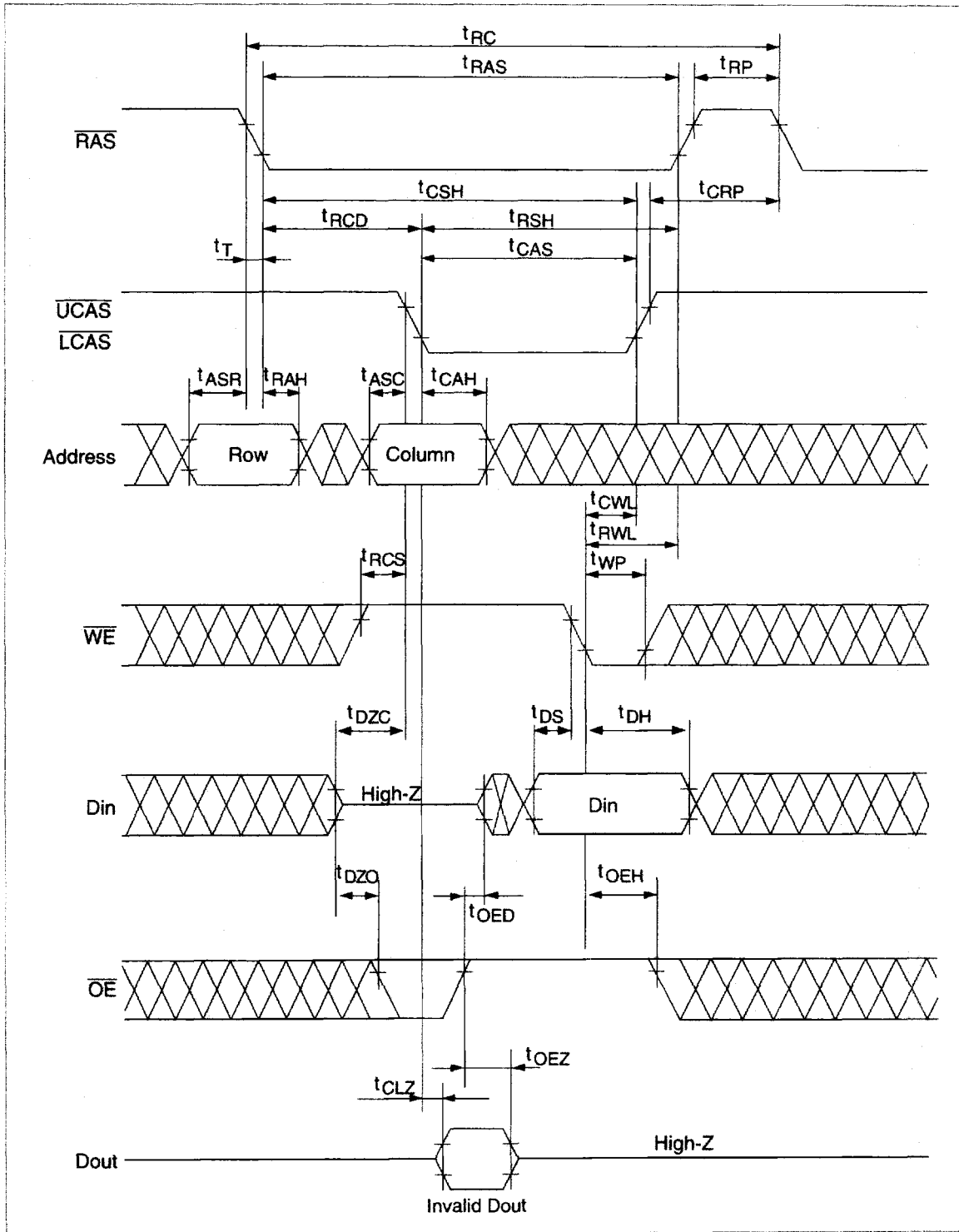
HM5116160A Series, HM5118160A Series

Early Write Cycle



HM5116160A Series, HM5118160A Series

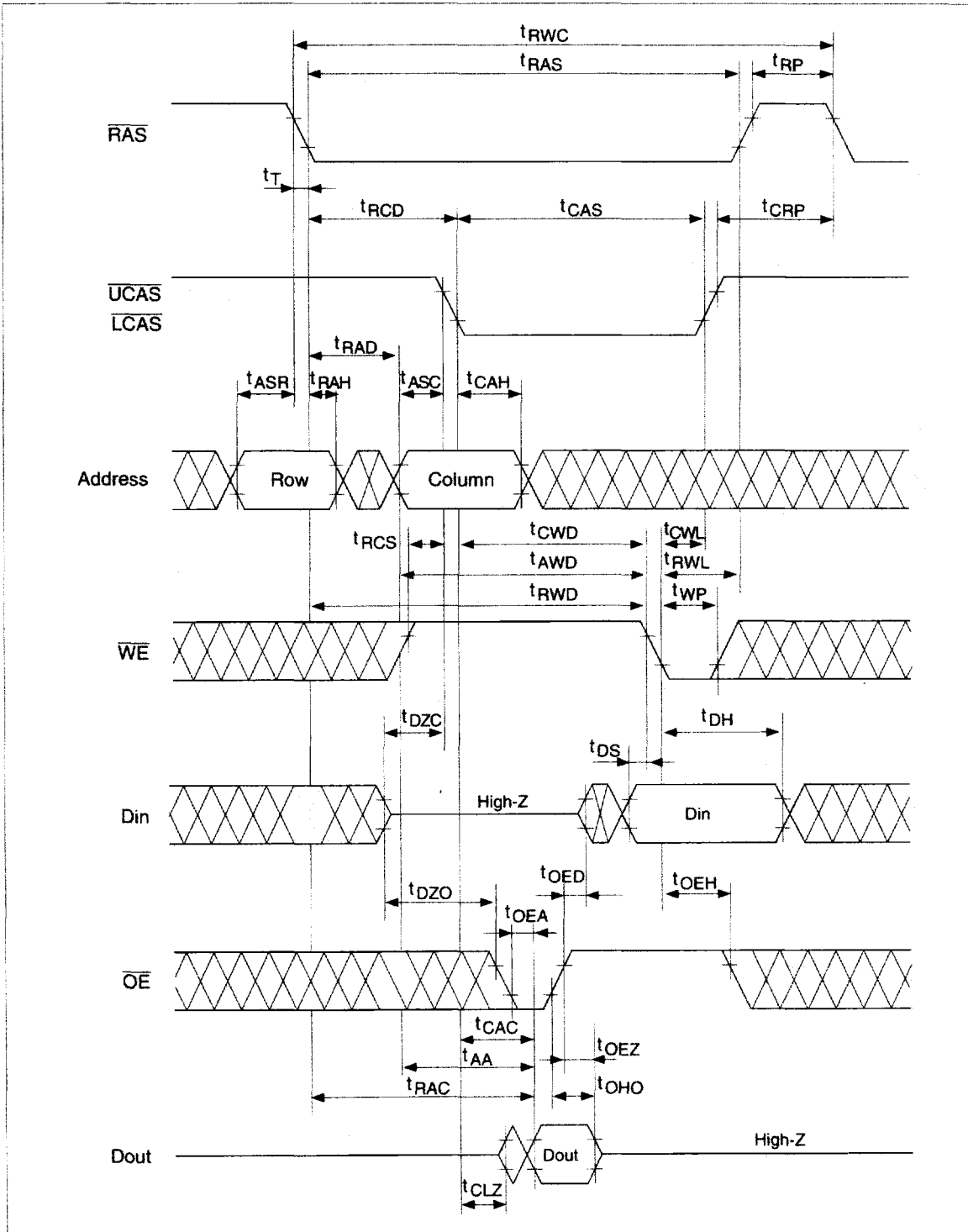
Delayed Write Cycle*18



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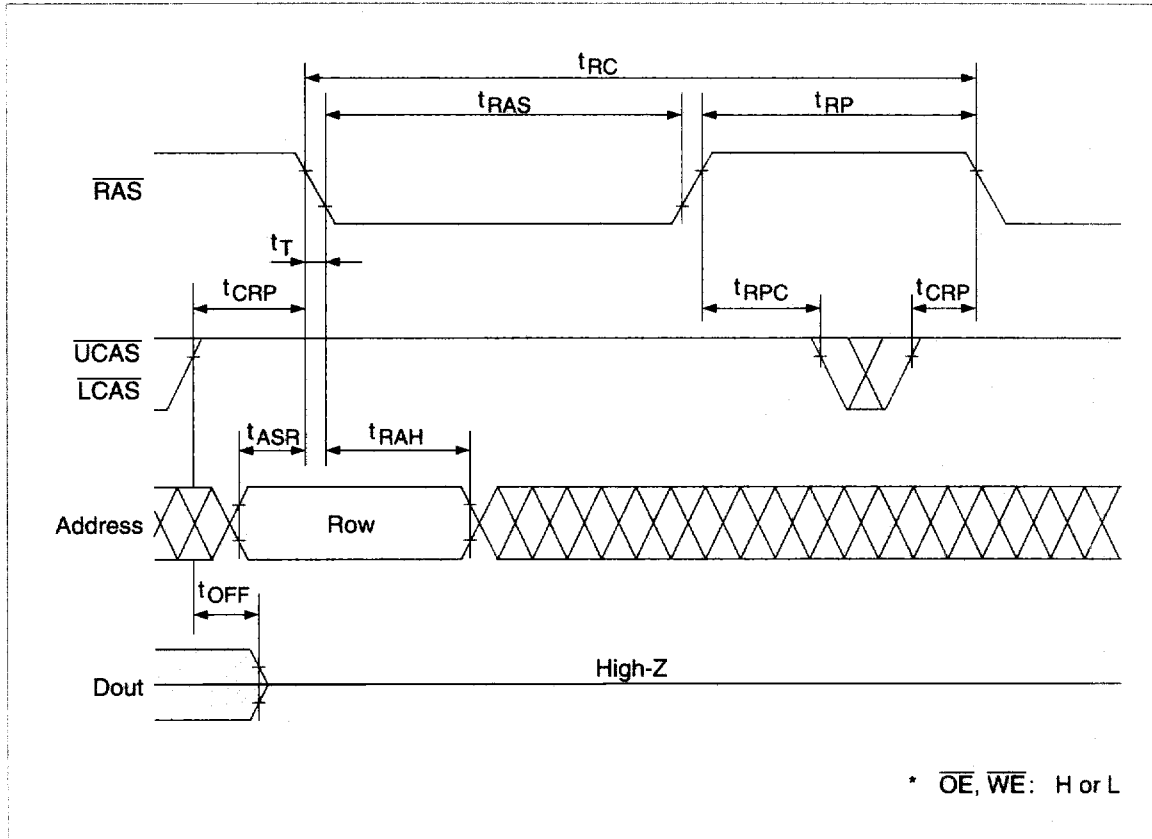
HM5116160A Series, HM5118160A Series

Read-Modify-Write Cycle*18



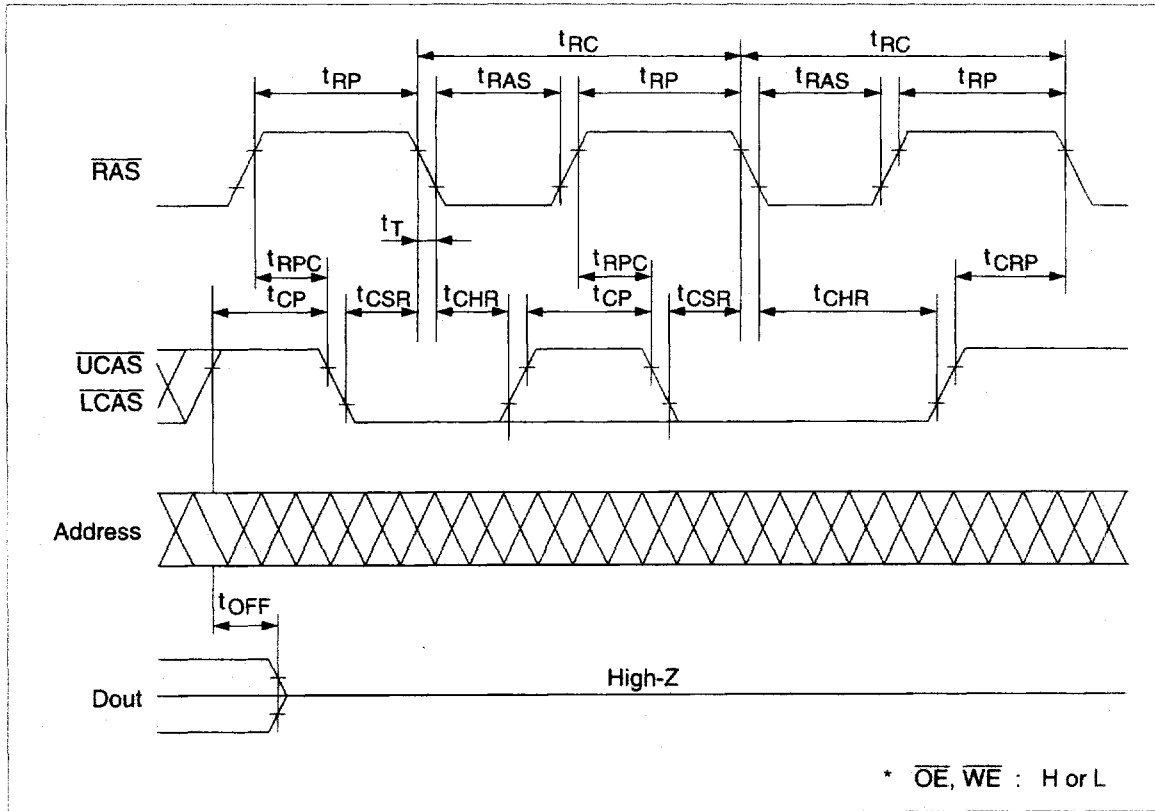
HM5116160A Series, HM5118160A Series

RAS-Only Refresh Cycle



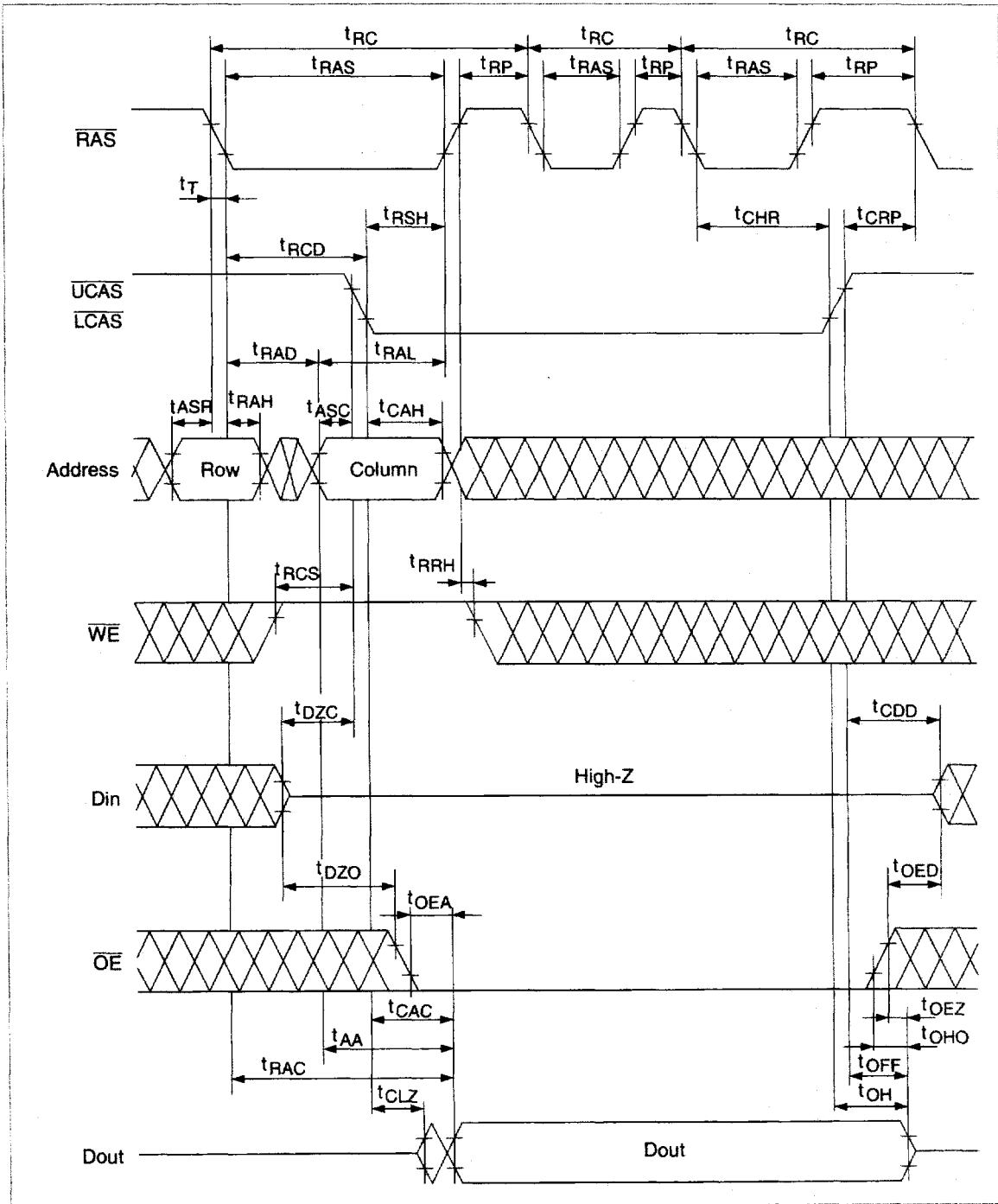
HM5116160A Series, HM5118160A Series

CAS-Before-RAS Refresh Cycle



HM5116160A Series, HM5118160A Series

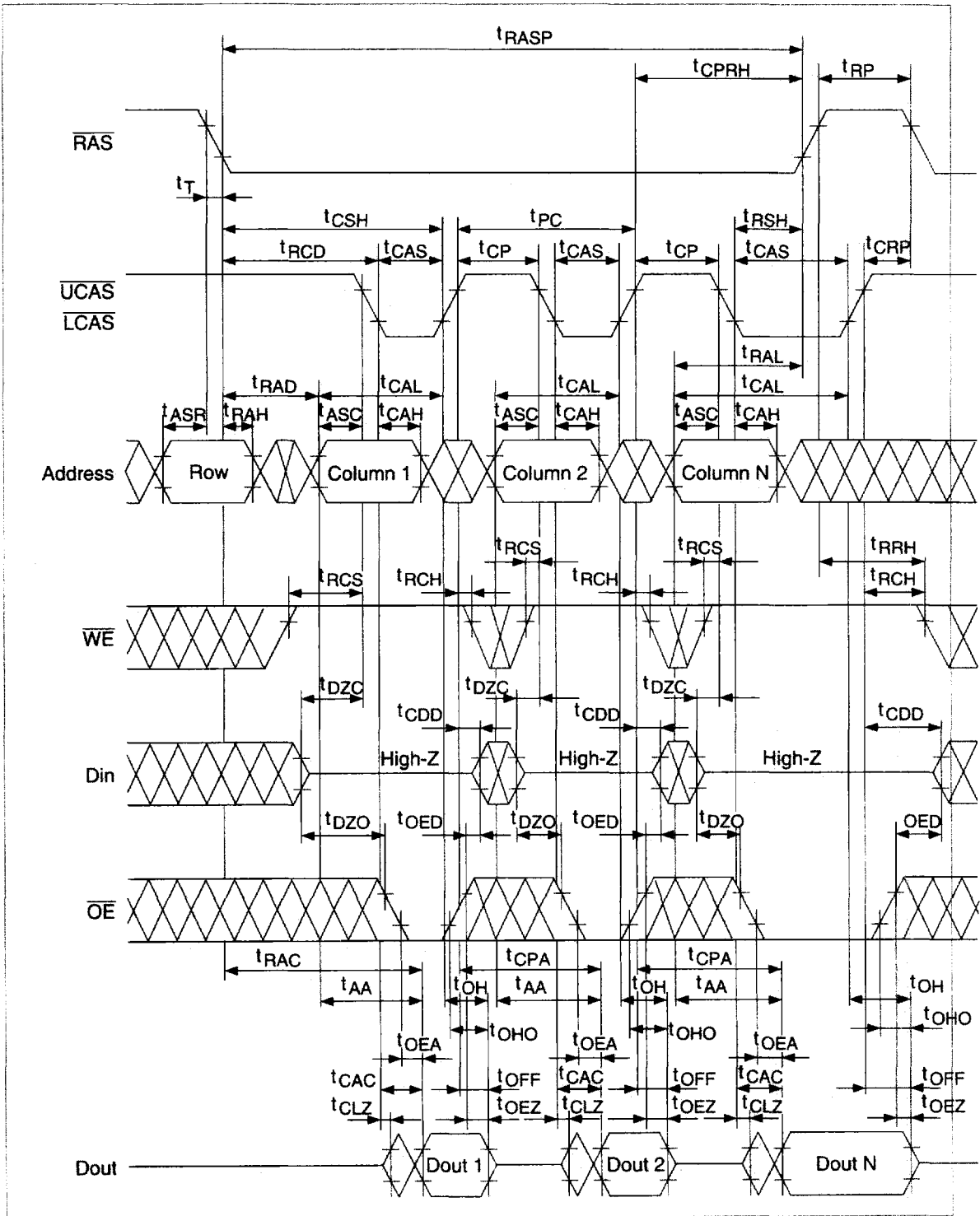
Hidden Refresh Cycle



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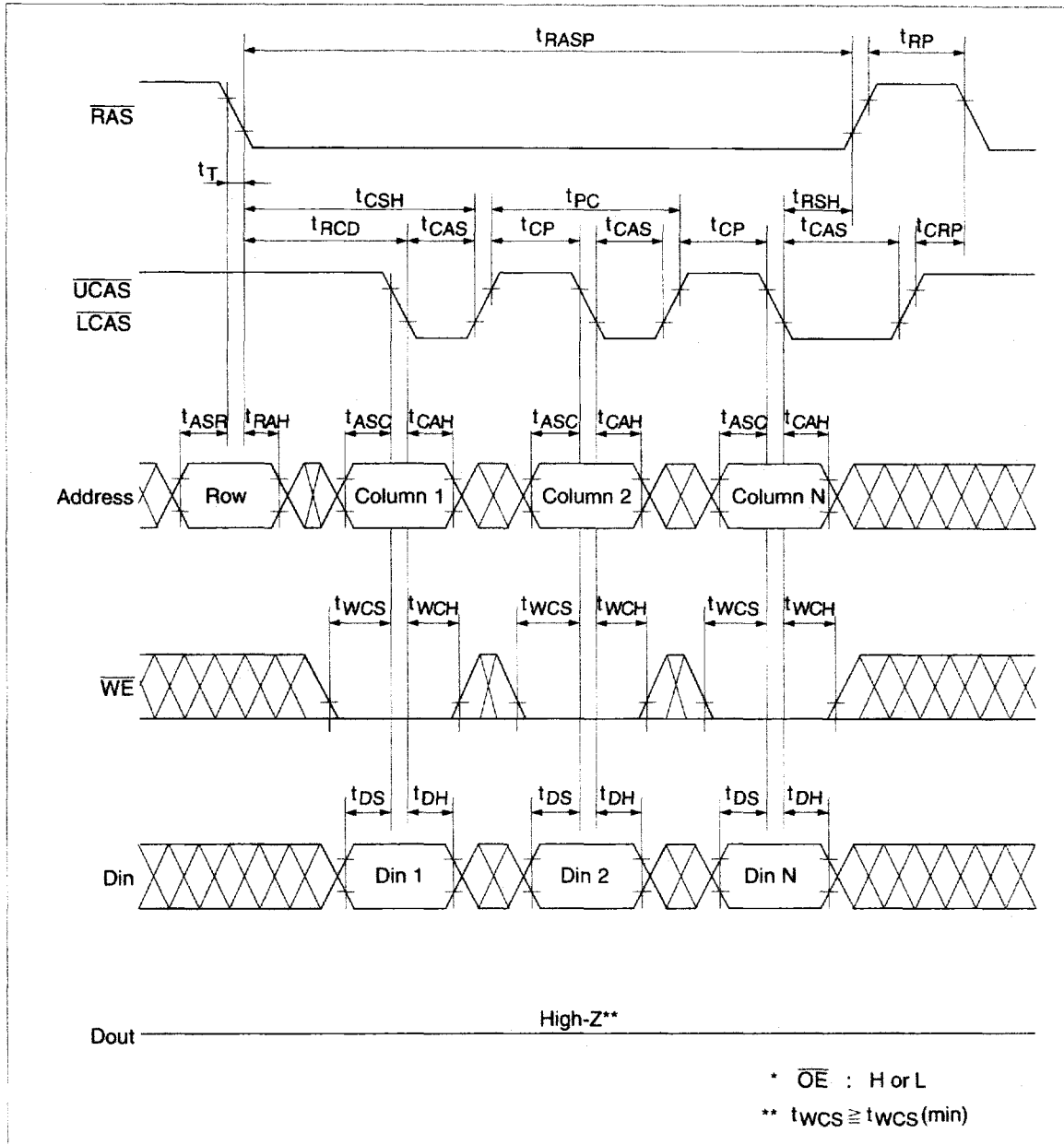
HM5116160A Series, HM5118160A Series

Fast Page Mode Read Cycle



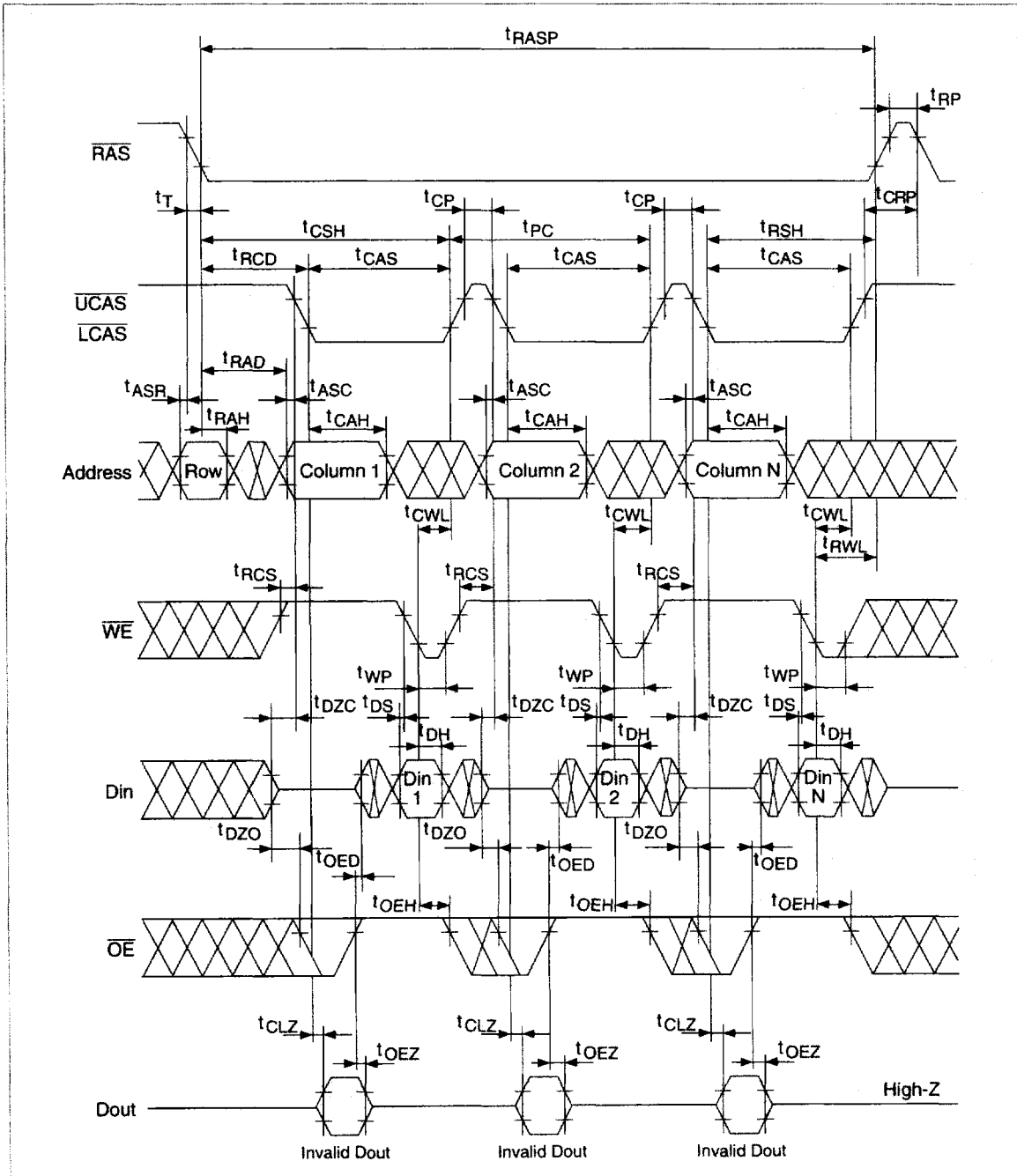
HM5116160A Series, HM5118160A Series

Fast Page Mode Early Write Cycle



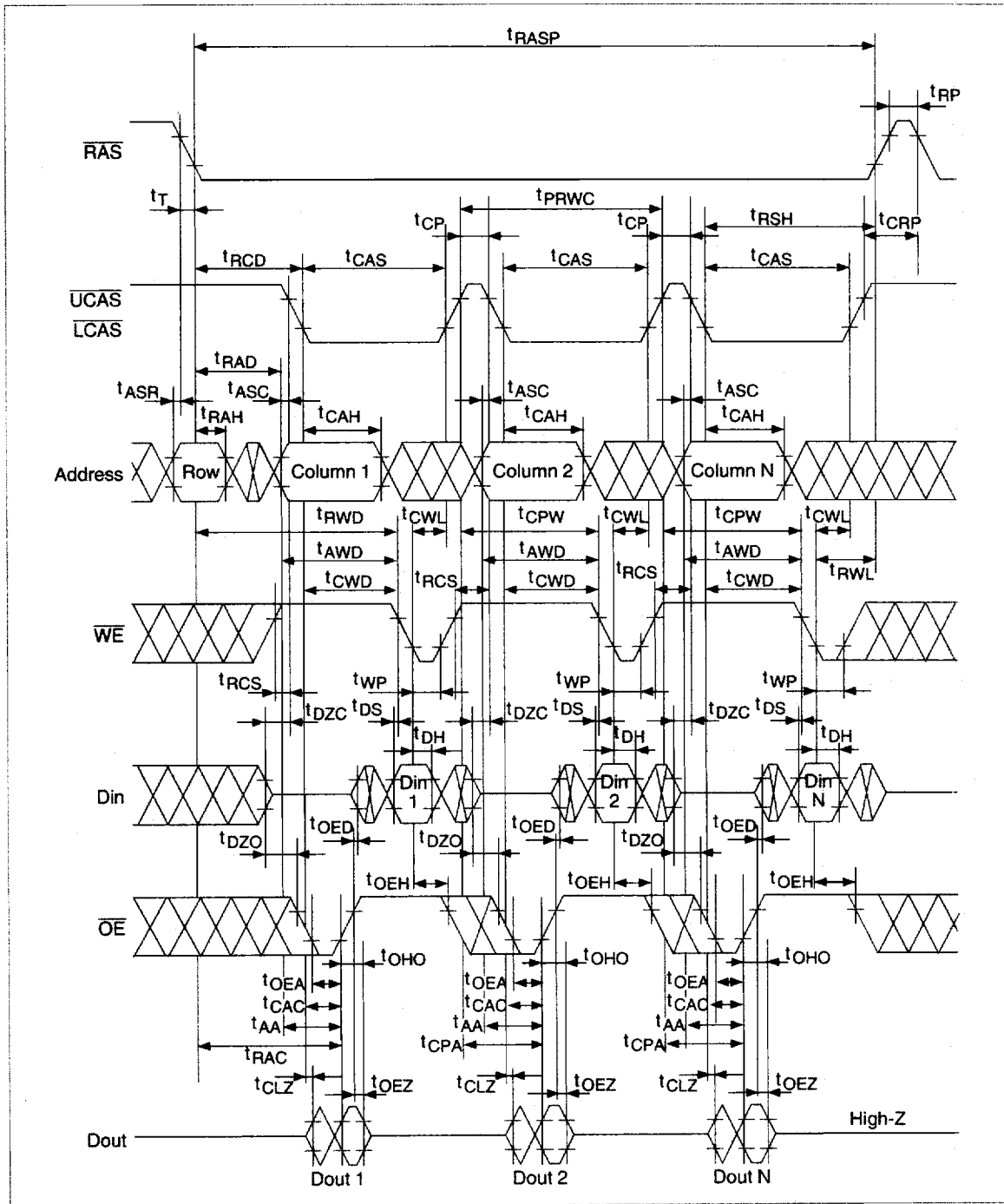
HM5116160A Series, HM5118160A Series

Fast Page Mode Delayed Write Cycle*18



HM5116160A Series, HM5118160A Series

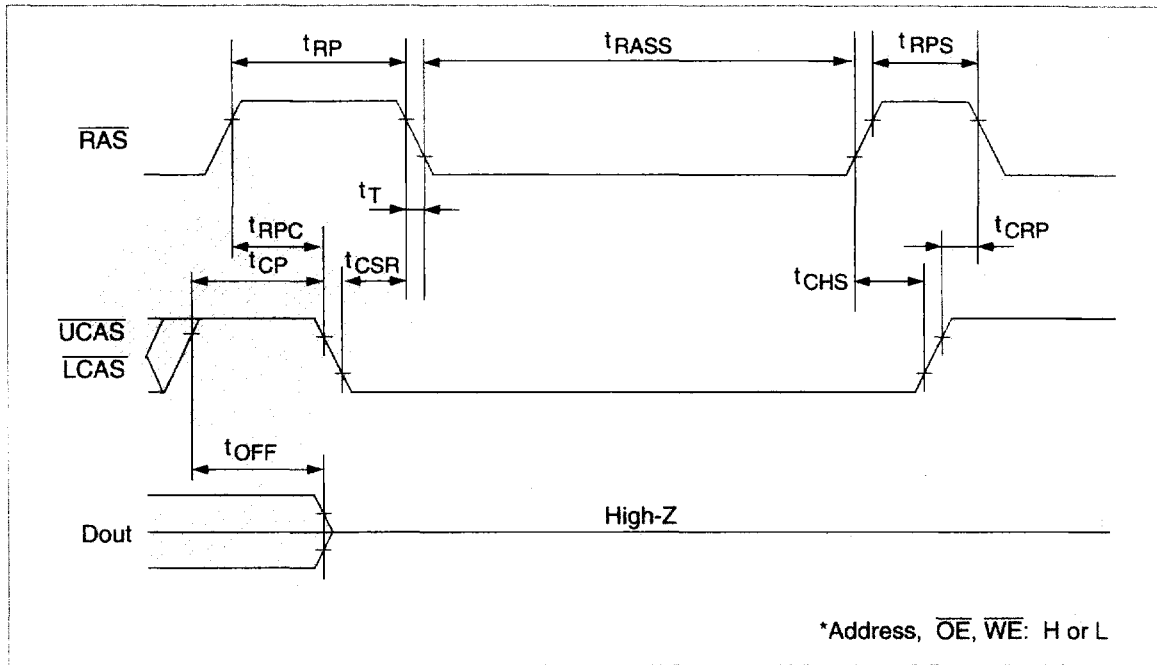
Fast Page Mode Read-Modify-Write Cycle*18



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HM5116160A Series, HM5118160A Series

Self Refresh Cycle (L-version)*26, 27, 28, 29



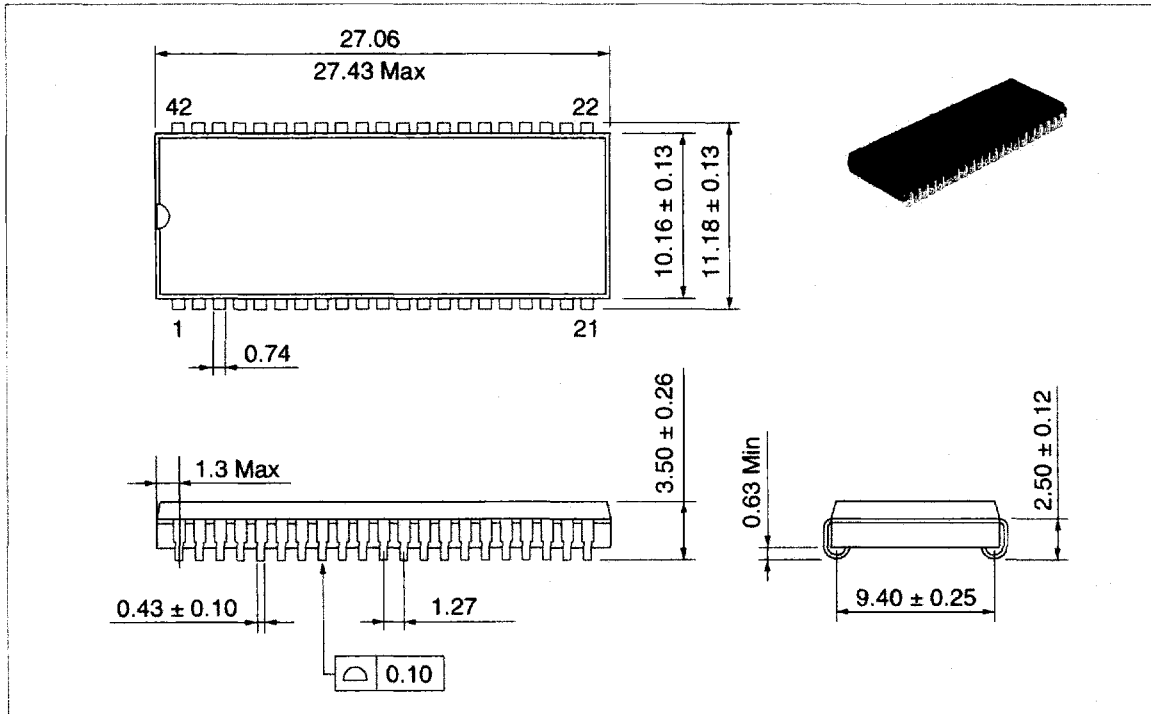
HM5116160A Series, HM5118160A Series

Package Dimensions

HM5116160AJ/ALJ Series

HM5118160AJ/ALJ Series (CP-42D)

Unit: mm

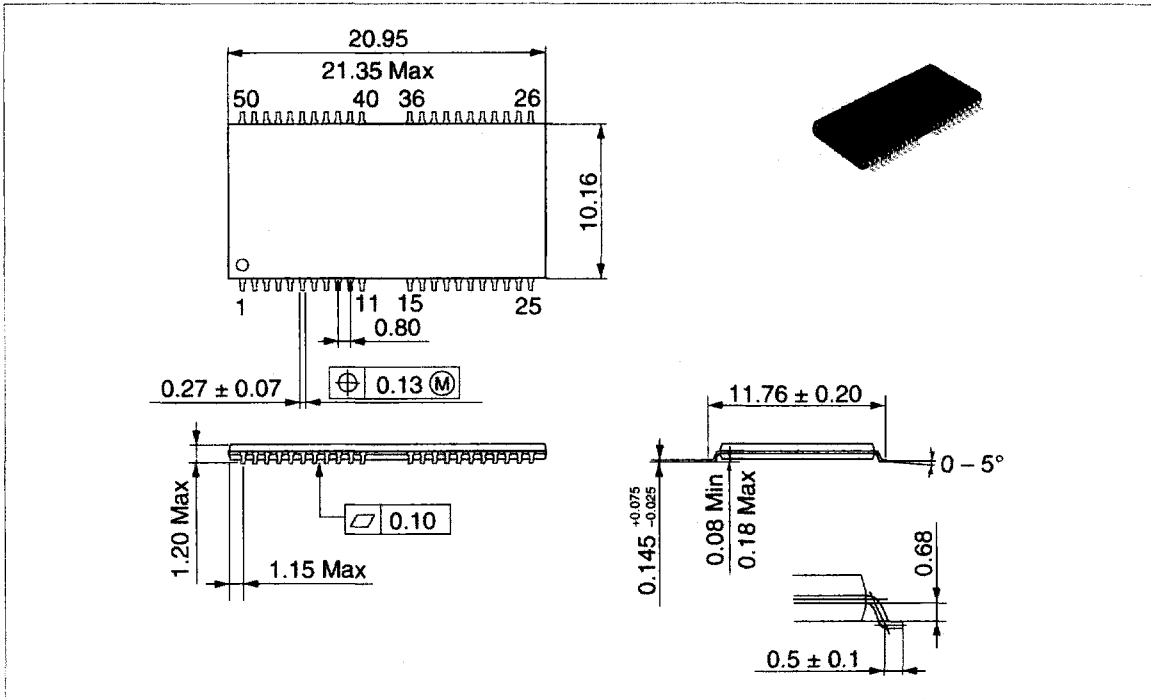


HM5116160A Series, HM5118160A Series

HM5116160ATT/ALTT Series

HM5118160ATT/ALTT Series (TTP-50/44DC)

Unit: mm



HM5116160A Series, HM5118160A Series

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HM5116160A Series, HM5118160A Series

Revision Record

Rev.	Date	Contents of Modification	Drawn by	Approved by
0.0	Dec. 27, 1993	Initial issue	H. Yoshioka	M. Yamamura
0.1	Jun. 1, 1994	Addition of HM5116160AL Series Addition of Standby (L-version) max: 0.83 mW Pin Arrangement Addition of Description for JEDEC pin number DC Characteristics Addition of I_{CC2} (L-version) max: 0.15/0.15/0.15 mA Addition of I_{CC10} (L-version) max: 0.5/0.5/0.5 mA I_{CC11} max: 200/200/200 μ A to 300/300/300 μ A AC Characteristics Deletion of t_{CPT} min: 20/20/20 ns Deletion of note 25 Change of note 2 Timing waveforms Deletion of \overline{CAS} -before- \overline{RAS} Refresh Counter Check Cycle Addition of Self Refresh Cycle	M. Mishima	H. Iijima
1.0	Feb. 2, 1995	Change of Package type name: TTP-44DC to TTP-50/44DC DC Characteristics I_{CC7} max: 100/90/80 mA to 105/95/85 mA Change of Package Dimensions: TTP-50/44DC	M. Mishima	H. Iijima
2.0	Aug. 30, 1995	Change format Change format of truth table Recommended DC Operating condition Addition of note 2 DC Characteristics Addition of note 4 AC Characteristics t_{RRH} min: 0/0/0 ns to 5/5/5 ns Change of notes 11, 12 Addition of note 25: t_{CP} is determined by the time that both \overline{UCAS} and \overline{LCAS} are high Package dimensions: CP-42D Package overhang: 1.265 mm to 1.3 mm Max	M. Mishima	K. Hayakawa

HM5116160A Series, HM5118160A Series

Revision Record (cont)

Rev.	Date	Contents of Modification	Drawn by	Approved by
3.0	Jul. 2, 1996	Unification of HM5116160A/HM5118160A Series Change format Addition of HM5118160A-6 Series Pin Description Addition of Row/Refresh address and Column address to address input AC Characteristics Deletion of note 3: Only row address is indispensable on address A8, A9, A10, A11 Notes concerning $2\overline{CAS}$ control Addition of note 4 Timing waveforms Deletion of note: $t_{OEH} \geq t_{CWE}$ Deletion of notes for RAS-only refresh cycle		