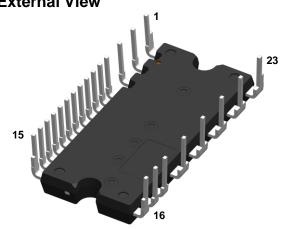


## **External View**



Size: 33.4 x 15 x 3.6 mm



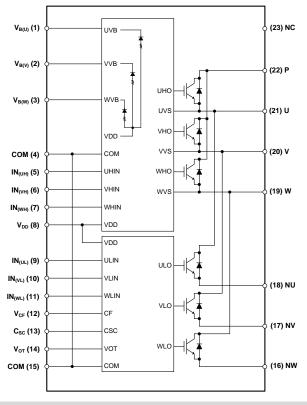
# Features

- UL Recognized:
- 600V-5A (Trench Shielded Planar Gate IGBT)
- 3 phase Inverter module including HVIC drivers
- Built-in bootstrap diodes with integrated current-limiting resistor
- Control supply under-voltage lockout protection (UVLO)
- Over-temperature (OT) protection and temperature monitoring  $(V_{\text{OT}})$  pin open
- Temperature monitoring only (V\_{OT})  $10k\Omega$  resistor connection
- Short-circuit current protection (C<sub>SC</sub>)
- Controllable fault out signal (V $_{\mbox{CF}}$ ) corresponding to SC, UV and OT fault
- Wide input interface (3-18V), Schmitt trigger receiver circuit (Active High)
- Very good EMI behavior
- Isolation ratings of 2000Vrms/min

# Applications

- AC 100-240Vrms class low power motor drives
- Washing Machines, Compressors, Fan Motors, Refrigerators and Dishwashers

# Internal Equivalent Circuit / Pin Configuration





## **Ordering Information**

Part Number	Temperature Range	Package	Pin Length Description		
AIP5D05E060Q4	-40°C to 150°C	IPM-5	Normal		
AIP5D05E060Q4S	-40°C to 150°C	IPM-5A	Short		



AOS Green Products use reduced levels of Halogens, and are also RoHS compliant. Please visit www.aosmd.com/media/AOSGreenPolicy.pdf for additional information.

## **Pin Description**

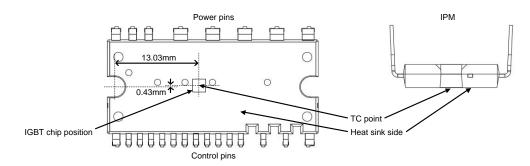
Pin Number	Pin Name	Pin Function
1	V <sub>B(U)</sub>	High-Side Bias Voltage for U-Phase IGBT Driving
2	V <sub>B(V)</sub>	High-Side Bias Voltage for V-Phase IGBT Driving
3	V <sub>B(W)</sub>	High-Side Bias Voltage for W-Phase IGBT Driving
4	COM	Common Supply Ground
5	IN <sub>(UH)</sub>	Signal Input for High-Side U-Phase
6	IN <sub>(VH)</sub>	Signal Input for High-Side V-Phase
7	IN <sub>(WH)</sub>	Signal Input for High-Side W-Phase
8	V <sub>DD</sub>	Common Bias Voltage for IC and IGBTs Driving
9	IN <sub>(UL)</sub>	Signal Input for Low-Side U-Phase
10	IN <sub>(VL)</sub>	Signal Input for Low-Side V-Phase
11	IN <sub>(WL)</sub>	Signal Input for Low-Side W-Phase
12	V <sub>CF</sub>	Controllable Fault Output
13	C <sub>SC</sub>	Capacitor (Low-Pass Filter) for Short-circuit Current Detection Input
14	V <sub>OT</sub>	Voltage Output of LVIC Temperature
15	COM	Common Supply Ground
16	NW	Negative DC-Link Input for W-Phase
17	NV	Negative DC-Link Input for V-Phase
18	NU	Negative DC-Link Input for U-Phase
19	W	Output for W-Phase
20	V	Output for V-Phase
21	U	Output for U-Phase
22	Р	Positive DC-Link Input
23	NC	No Connection



# **Absolute Maximum Ratings**

 $T_J = 25^{\circ}C$ , unless otherwise specified.

Symbol	Parameter	Conditions	Ratings	Units
Inverter	•	·		1
V <sub>PN</sub>	Supply Voltage	Applied between P - NU,NV,NW	450	V
VPN(surge)	Supply Voltage (surge)	Applied between P - NU,NV,NW	500	V
V <sub>CES</sub>	Collector-Emitter Voltage		600	V
1	Output Phase Current	T <sub>C</sub> =25°C, T <sub>J</sub> <150°C	5	А
l <sub>c</sub>	Output Phase Current	T <sub>C</sub> =100°C, T <sub>J</sub> <150°C	3	А
±I <sub>PK</sub>	Output Peak Phase Current	T <sub>C</sub> =25°C, less than 1ms pulse width	10	А
t <sub>sc</sub>	Short Circuit Withstand Time	V <sub>PN</sub> ≤400V, T <sub>J</sub> =150°C, V <sub>DD</sub> =15V	5	μs
Pc	Collector Dissipation	T <sub>C</sub> =25°C, per chip	18.9	W
TJ	Operating Junction Temperature		-40 to 150	°C
Control (P	rotection)			
V <sub>DD</sub>	Control Supply Voltage	Applied between V <sub>DD</sub> -COM	25	V
V <sub>DB</sub>	High-Side Control Bias Voltage	Applied between V <sub>B(U)</sub> -U, V <sub>B(V)</sub> -V, V <sub>B(W)</sub> -W	25	V
V <sub>IN</sub>	Input Voltage	Applied between IN_(UH), IN_(VH), IN_(WH), IN_(UL), IN_(VL), IN_(VL) - COM	$V_{DD} \pm 0.5$	V
V <sub>CF</sub>	Fault Output Supply Voltage	Applied between V <sub>CF</sub> -COM	5±0.5	V
I <sub>CF</sub>	Fault Output Current	Sink current at V <sub>CF</sub> terminal	1	mA
V <sub>SC</sub>	Current Sensing Input Voltage	Applied between C <sub>SC</sub> -COM	5±0.5	V
V <sub>OT</sub>	Temperature Output	Applied between Vor-COM	5±0.5	V
Total Syst	em			
V <sub>PN(PROT)</sub>	Self Protection Supply Voltage Limit (Short-Circuit Protection Capability)	V <sub>DD</sub> =13.5-16.5V, Inverter part T <sub>J</sub> =150°C, Non-repetitive, less than 2µs	400	V
T <sub>C</sub>	Module Case Operation Temperature	Measurement point of $T_C$ is provided in Figure 1	-30 to 125	°C
T <sub>STG</sub>	Storage Temperature		-40 to 150	°C
V <sub>ISO</sub>	Isolation Voltage	60Hz, sinusoidal, AC 1min, between connected all pins and heat sink plate	2000	V <sub>rms</sub>



## Figure 1. T<sub>c</sub> Measurement Point

# **Thermal Resistance**

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
R <sub>th(j-c)Q</sub>	Junction to Case Thermal Resistance <sup>(1)</sup>	Inverter IGBT (per 1/6 module)	-	-	6.6	K/W
R <sub>th(j-c)F</sub>		Inverter FWD (per 1/6 module)	-	-	8.5	K/W

Note:

1. For the measurement point of case temperature  $(T_c)$ , please refer to Figure 1.



# **Electrical Characteristics**

 $T_J = 25^{\circ}C$ , unless otherwise specified.

Symbol	Parameter	Conditions		Min.	Тур.	Max.	Units
Inverter	1			I			•
V	Collector-Emitter Saturation	V <sub>DD</sub> =V <sub>DB</sub> =15V,	I <sub>C</sub> =2.5A, T <sub>J</sub> =25°C	-	1.48	1.85	V
$V_{CE(SAT)}$	Voltage	V <sub>IN</sub> =5V I <sub>C</sub> =2.5A, T <sub>J</sub> =125°C		-	1.69	-	V
V <sub>F</sub>	FWD Forward Voltage	V <sub>IN</sub> =0	I <sub>F</sub> =2.5A, T <sub>J</sub> =25°C	-	1.75	2.15	V
t <sub>ON</sub>		$V_{PN}$ =300V, $V_{DD}$ = $V_{DB}$ =15V I <sub>C</sub> =2.5A, T <sub>J</sub> =25°C, $V_{IN}$ =0V ↔ 5V		0.40	0.80	1.40	μs
t <sub>C(ON)</sub>				-	0.25	0.50	μs
<b>t</b> off	Switching Times			-	1.00	1.60	μs
$t_{C(OFF)}$		Inductive load (high-	-side)	-	0.14	0.40	μs
trr				-	0.20	-	μs
	Collector-Emitter Leakage		TJ=25°C	-	-	1	mA
ICES	Current	V <sub>CE</sub> =V <sub>CES</sub>	T <sub>J</sub> =125°C	-	-	10	mA
Control (F	rotection)						
I <sub>QDD</sub>	Quiescent V <sub>DD</sub> Supply Current	VDD=15V, IN(UH,VH,WH,UL,VL,WL) =0V	V <sub>DD</sub> -COM	-	-	1.5	mA
I <sub>QDB</sub>	Quiescent V <sub>DB</sub> Supply Current	Vdb=15V, IN(UH, VH, WH)=0V	$V_{B(U)}\text{-}U, \ V_{B(V)}\text{-}V, \ V_{B(W)}\text{-}W$	-	-	0.3	mA
V <sub>SC(ref)</sub>	Short-Circuit Trip Level	$V_{DD}=15V^{(2)}$		0.45	0.48	0.51	V
$UV_{DT}$		Trip Level		10.3	11.4	12.5	V
$UV_{DR}$	Supply Circuit Under-Voltage	Reset Level		10.8	11.9	13.0	V
$UV_{DBT}$	Protection	Trip Level		9.0	10.0	11.0	V
$UV_{DBR}$		Reset Level		10.0	11.0	12.0	V
V <sub>OT</sub>	Temperature Output	Pull-down	LVIC Temperature=80°C	2.36	2.45	2.55	V
VOI		R=10kΩ <sup>(3)</sup>	LVIC Temperature=25°C	0.77	1.00	1.25	V
OTT	Over-Temperature	V <sub>DD</sub> =15V, Detect	Trip Level	110	130	150	°C
OT <sub>HYS</sub>	Protection <sup>(4)</sup>	LVIC Temperature	Hysteresis of Trip Reset	-	30	-	°C
V <sub>CFH</sub>	Fault Output Voltage	V <sub>SC</sub> =0V, V <sub>CF</sub> Circuit:	$10k\Omega$ to 5V pull-up	4.9	-	-	V
$V_{CFL}$	1 aut Ouput Voltage	V <sub>SC</sub> =1V, V <sub>CF</sub> Circuit:	$10k\Omega$ to 5V pull-up	-	-	0.5	V
$V_{CF+}$	CF positive going threshold			-	1.9	2.2	V
V <sub>CF-</sub>	CF negative going threshold			0.8	1.1	-	V
t <sub>FO</sub>	Fault Output Pulse Width (5)			20	-	-	μs
I <sub>IN</sub>	Input Current	V <sub>IN</sub> =5V		-	1.0	-	mA
V <sub>th(on)</sub>	ON Threshold Voltage				2.3	2.6	V
$V_{\text{th(off)}}$	OFF Threshold Voltage	Applied between IN <sub>(UH),</sub> IN <sub>(VH),</sub> IN <sub>(WH),</sub> IN <sub>(UL),</sub> IN <sub>(VL)</sub> , IN <sub>(WL)</sub> -COM		0.8	1.2		V
$V_{\text{th(hys)}}$	ON/OFF Threshold Hysteresis Voltage			-	1.1	-	V
$V_{\text{F(BSD)}}$	Bootstrap Diode Forward Voltage	Resistor <sup>(6)</sup>	oltage Drop by Limiting	-	5.0	-	V
R <sub>BSD</sub>	Built-in Limiting Resistance	Included in Bootstra	p Diode	-	500	-	Ω

#### Notes:

2. Short-circuit protection works only for low sides.

The IPM does not shutdown IGBTs and output fault signal automatically when temperature rises excessively. When temperature exceeds the
protective level that the user defined, the controller (MCU) should stop the IPM. Temperature of LVIC vs. V<sub>oT</sub> output characteristics is described
in Figure 3.

4. When the LVIC temperature exceeds OT Trip temperature level (OT<sub>T</sub>), OT protection is triggered and fault outputs.

Fault signal (F<sub>o</sub>) outputs when SC, UV or OT protection is triggered. F<sub>o</sub> pulse width is different for each protection mode. At SC failure, F<sub>o</sub> pulse width is a fixed width (minimum 20µs), but at UV or OT failure, F<sub>o</sub> outputs continuously until recovering from UV or OT state. (But minimum F<sub>o</sub> pulse width is 20µs).

6. The characteristics of bootstrap diodes are described in Figure 2.

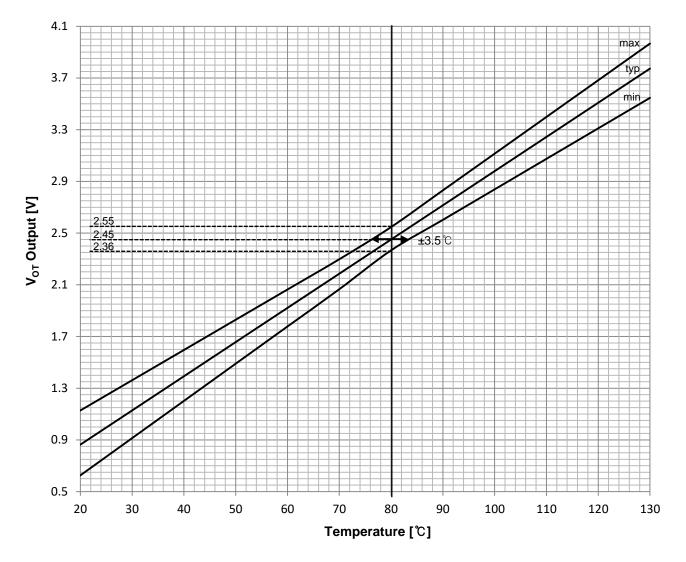


Figure 3. Temperature of LVIC vs. Vot Output Characteristics

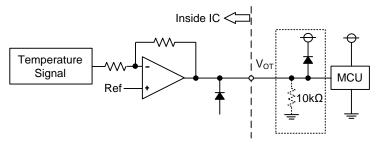


Figure 4. Vot Output Circuit

- (1) If the V<sub>OT</sub> pin is left unconnected, the internal over-temperature protection function and temperature monitoring function are used simultaneously.
- (2) If pull-down resistor of  $10k\Omega$  connected to V<sub>OT</sub> pin, the temperature monitoring function is only used.
- (3) In the case of using V<sub>OT</sub> with low voltage controller like 3.3V MCU, V<sub>OT</sub> output might exceed control supply voltage 3.3V when temperature rises excessively. If system uses low voltage controller, it is recommended to insert a clamp diode between control supply of the controller and V<sub>OT</sub> output for preventing over voltage destruction.

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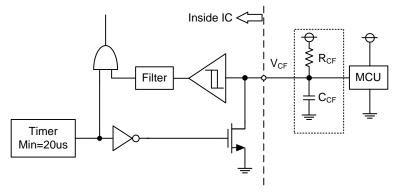


Figure 5. V<sub>CF</sub> Output Circuit

- (1) The  $V_{CF}$  pin provides an enable functionality that allows it to shut down the all low-side IGBTs. When the  $V_{CF}$  pin is in the high state the IPM is able to operate normally. If the  $V_{CF}$  pin is in a low state, the low-side IGBTs are turned off until the enable condition is restored. In addition, the  $V_{CF}$  pin can provide the fault output signal with the fixed or controlled fault out pulse width.
- (2) If only a pull-up resistor of  $10k\Omega$  connected to the V<sub>CF</sub> pin, the fault output pulse width is fixed at minimum 20us.
- (3) If a capacitor is connected with a pull-up resistor together, the fault output pulse width can be controlled according to the resistor and the capacitor values. The length of fault output pulse width is determined by the following formula ;
  - $t_{FO} = -(R_{CF}*C_{CF})*ln(1-V_{CF}+/V_{DD}) + 20us(min.)$
  - ex)  $V_{DD}=5V$ ,  $R_{CF}=2.2M\Omega$ ,  $C_{CF}=1nF$ ,  $t_{FO}\approx1.07ms$ . Recommended parameters in the design are  $C_{CF}$  of  $\leq 1nF$  and  $R_{CF}$  of 0.1M to 2.2M $\Omega$ .



# **Mechanical Characteristics and Ratings**

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
Mounting Torque	Mounting Screw: M3 (7)		0.59	0.69	0.78	N m
Weight			-	5.25	-	g
Flatness	Refer to Figure 6		-50	-	100	μm

#### Note:

7. Plain washers (ISO 7089-7094) are recommended.

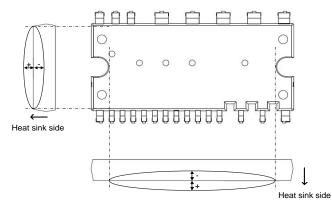


Figure 6. Flatness Measurement Positions

## **Recommended Operation Conditions**

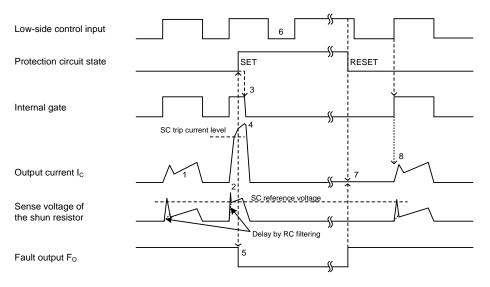
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
V <sub>PN</sub>	Supply Voltage	Applied between P-NU, NV, NW	0	300	400	V
V <sub>DD</sub>	Control Supply Voltage	Applied between V <sub>DD</sub> -COM	13.5	15.0	16.5	V
$V_{\text{DB}}$	High-Side Bias Voltage	Applied between $V_{B(U)}$ -U, $V_{B(V)}$ -V, $V_{B(W)}$ -W	13.5	15.0	18.5	V
dV <sub>DD</sub> /dt, dV <sub>DB</sub> /dt	Control Supply Variation		-1	-	1	V/µs
t <sub>dead</sub>	Arm Shoot-Through Blocking Time	For each input signal	1.0	-	-	μs
f <sub>PWM</sub>	PWM Input Frequency	-40°C < T <sub>J</sub> < 150°C	-	-	20	kHz
PW <sub>IN(ON)</sub>	Minimum Input Pulse Width <sup>(8)</sup>		0.5	-	-	μs
$PW_{IN(OFF)}$	winimum input Pulse width		0.5	-	-	μs
СОМ	COM Variation	Between COM-NU, NV, NW (including surge)	-5.0	-	5.0	V

#### Note:

8. IPM may not respond if the input pulse width is less than  $PW_{IN(ON)}$ ,  $PW_{IN(OFF)}$ .



## **Time Charts of the IPM Protective Function**



### Figure 7. Short-Circuit Protection (Low-side Operation Only with the External Shunt Resistor and RC Filter)

- (1) Normal operation: IGBT turns on and outputs current.
- (2) Short-circuit current detection (SC triggered).
- (3) All low-side IGBTs' gates are hard interrupted.
- (4) All low-side IGBTs turn OFF.
- (5)  $F_{O}$  output time (t<sub>FO</sub>)=minimum 20µs.
- (6) Input = "L" : IGBT OFF.
- (7) Fault output finishes, but output current will not turn on until next ON signal (L $\rightarrow$ H).
- (8) Normal operation: IGBT turns on and outputs current.

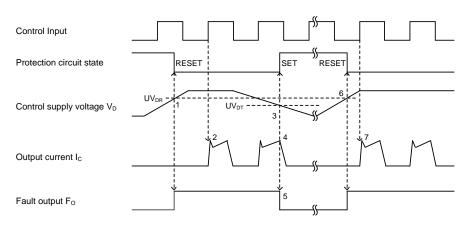
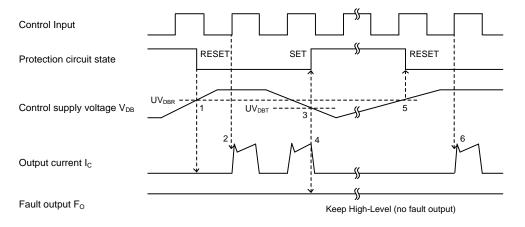


Figure 8. Under-Voltage Protection (Low-side, UV<sub>D</sub>)

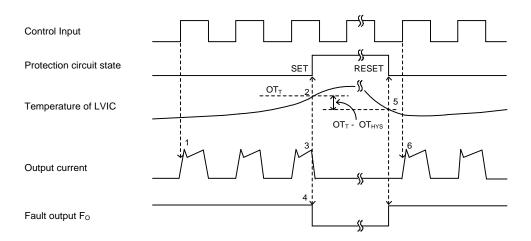
- (1) Control supply voltage  $V_{DD}$  exceeds under voltage reset level (UV<sub>DR</sub>), but IGBT turns on by next ON signal (L $\rightarrow$ H).
- (2) Normal operation: IGBT turns on and outputs current.
- (3)  $V_{DD}$  level drops to under voltage trip level (UV<sub>DT</sub>).
- (4) All low-side IGBTs turn OFF regardless of control input condition.
- (5)  $F_O$  output time ( $t_{FO}$ )=minimum 20µs, and  $F_O$  stays low as long as  $V_{DD}$  is below UV<sub>DR</sub>.
- (6)  $V_{DD}$  level reaches  $UV_{DR}$ .
- (7) Normal operation: IGBT turns on and outputs current.





#### Figure 9. Under-Voltage Protection (High-side, UV<sub>DB</sub>)

- (1) Control supply voltage  $V_{DB}$  rises. After the voltage reaches under voltage reset level  $UV_{DBR}$ , IGBT turns on by next ON signal (L $\rightarrow$ H).
- (2) Normal operation: IGBT turns on and outputs current.
- (3) V<sub>DB</sub> level drops to under voltage trip level (UV<sub>DBT</sub>).
- (4) All high-side IGBTs turn OFF regardless of control input condition, but there is no Fo signal output.
- (5)  $V_{DB}$  level reaches  $UV_{DBR}$ .
- (6) Normal operation: IGBT turns on and outputs current.

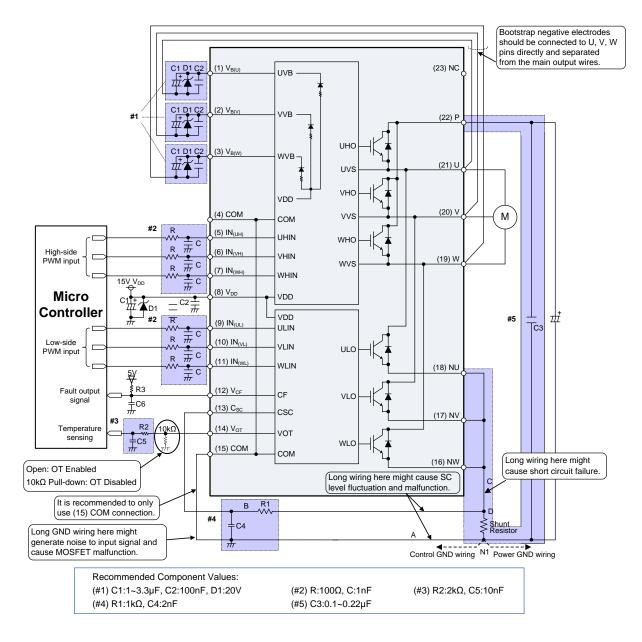


#### Figure 10. Over-Temperature Protection (Low-side, Detecting LVIC Temperature)

- (1) Normal operation: IGBT turns on and outputs current.
- (2) LVIC temperature exceeds over-temperature trip level (OT<sub>T</sub>).
- (3) All low-side IGBTs turn off regardless of control input condition.
- (4)  $F_0$  output time (t<sub>F0</sub>)=minimum 20µs, and  $F_0$  stays low as long as LVIC temperature is over OT<sub>T</sub>.
- (5) LVIC temperature drops to over-temperature reset level (OT<sub>T</sub>-OT<sub>HYS</sub>).
- (6) Normal operation: IGBT turns on by the next ON signal (L $\rightarrow$ H).



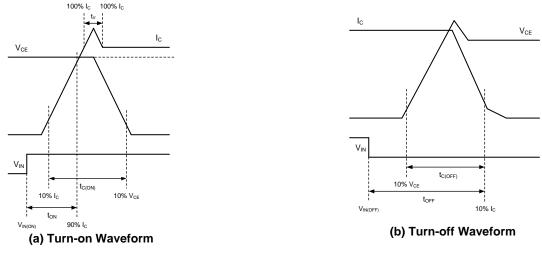
## **Example of Application Circuit**



- (1) If the control GND is connected with the power GND by common broad pattern, it may cause malfunction by power GND fluctuation. It is recommended to connect the control GND and power GND at a single point (N1), near the terminal of the shunt resistor.
- (2) There are two COM pins in the IPM but it is recommended to only use the (15) COM pin to minimize SC detection noise.
- (3) A zener diode D1 (24V/1W) is recommended between each pair of control supply pins to prevent surge destruction.
- (4) Prevention of surge destruction can further be improved by placing the bus capacitor as close to pin P and N1 as possible. Generally a 0.1-0.22µF snubber capacitor C3 between the P-N1 terminals is recommended.
- (5) Selection of the R1\*C4 filter components for short-circuit protection is recommended to have tight tolerance, and is temperaturecompensated type. The R1\*C4 time constant should be set such that SC current is shut down within 2µs; (typically 1.5-2µs). R1 and C4 should be placed as close as possible to the C<sub>SC</sub> pin. SC interrupting time may vary with layout patterns and components selection, therefore thorough evaluation in the system is necessary.
- (6) Tight tolerance and temperature-compensated components are also recommended when selecting the R2\*C5 filter for V<sub>oT</sub>. The R2\*C5 time constant should be set such that V<sub>oT</sub> is immune to noise. Recommended values of R2 and C5 are 2kΩ and 10nF.
- (7) To prevent malfunction, traces A, B, and C should be as short as possible.
- (8) It is recommended that all capacitors are mounted as close to the IPM as possible. (C1: electrolytic type with good temperature and frequency characteristics. C2: ceramic type with 0.1-2µF, good temperature, frequency and DC bias characteristics.)



- (9) Input drives are active-high. There is a minimum 3.5kΩ pull-down resistor in the input circuit of IC. To prevent malfunction, the layout to each input should be as short as possible. When using RC coupling circuit, make sure the input signal levels meet the required turn-on and turn-off threshold voltages.
- (10)  $V_{CF}$  output is open drain type. It should be pulled up to MCU or control power supply (max= 5±0.5V), limiting the current (I<sub>CF</sub>) to no more than 1mA. I<sub>CF</sub> is estimated roughly by the formula of control power supply voltage divided by the pull-up resistor R3. For example, if control supply is 5V, a 10k $\Omega$  (over 5k $\Omega$ ) pull-up resistor R3 is recommended.
- (11) If only a pull-up resistor R3 of  $10k\Omega$  connected to  $V_{CF}$  pin, the fault output pulse width is fixed at minimum 20us. If a capacitor C6 is connected with a pull-up resistor R3, the fault output pulse width can be controlled according to the resistor value and capacitor value. For the design guide, please refer to the Figure 5.
- (12) Direct drive of the IPM from the MCU is possible without having to use opto-coupler or isolation transformer.
- (13) The IPM may malfunction and erroneous operations may occur if high frequency noise is superimposed to the supply line. To avoid such problems, line ripple voltage is recommended to have dV/dt ≤ ±1V/µs, and Vripple ≤ 2Vp-p.
- (14) It is not recommended to use the IPM to drive the same load in parallel with another IPM or inverter types.



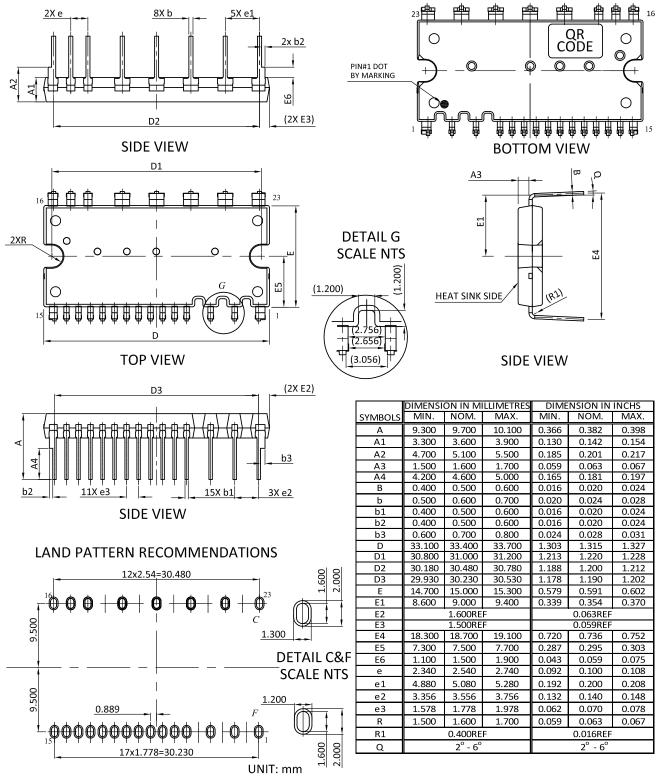


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# Package Dimensions, IPM-5



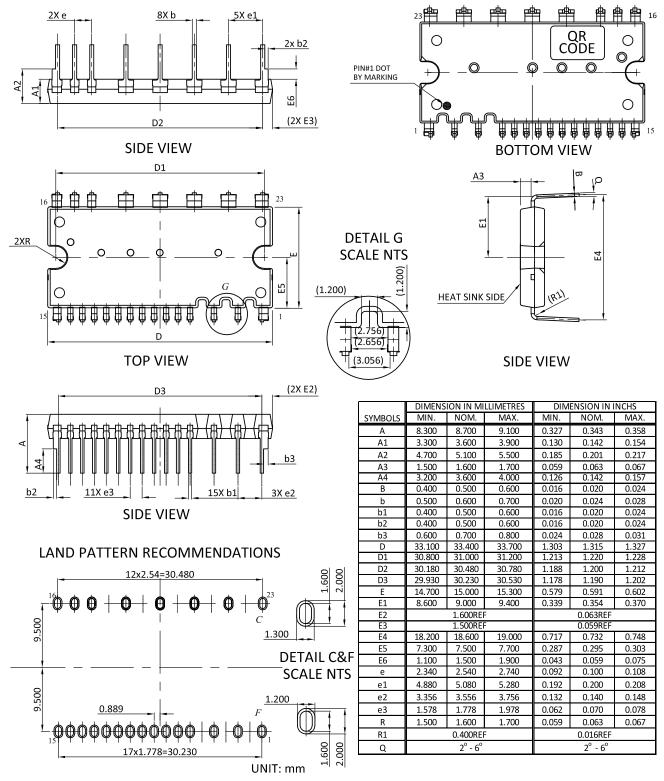
NOTES

- 1. PACKAGE BODY SIZES EXCLUDE MOLD FLASH AND GATE BURRS, MOLD FLASH SHOULD BE LESS THAN 6 MIL.
- 2. TOLERANCE 0.100 MILLIMETERS UNLESS OTHERWISE SPECIFIED.
- 3. CONTROLLING DIMENSION IS MILLIMETER, CONVERTED INCH DIMENSIONS ARE NOT NECESSARILY EXACT.

4. () IS REFERENCE.



# Package Dimensions, IPM-5A



NOTES

- 1. PACKAGE BODY SIZES EXCLUDE MOLD FLASH AND GATE BURRS, MOLD FLASH SHOULD BE LESS THAN 6 MIL.
- 2. TOLERANCE 0.100 MILLIMETERS UNLESS OTHERWISE SPECIFIED.
- 3. CONTROLLING DIMENSION IS MILLIMETER, CONVERTED INCH DIMENSIONS ARE NOT NECESSARILY EXACT.

4. () IS REFERENCE.



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2. A critical component in any component of a life support, device, or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.