

## 3V High Speed Single LVDS Driver

### DESCRIPTION

The DG90LV011 High Speed driver is optimized for data rate in excess of 400 Mbps (200 MHz). Device works under current mode. It conforms to TIA/EIA standard. It is designed and manufactured for industrial temperature (- 40 °C ~ 85 °C) applications.

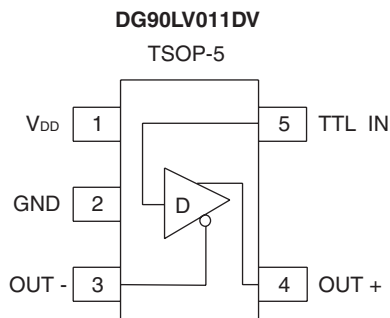
### FEATURES

- 3.3 V Power Supply
- +/- 350 mV Differential Signal
- > 400 Mbps (200 MHz)
- Low Power
- Differential Skew - 100 ps
- Propagation Delay - 1.2 ns
- TIA/EIA-644-A conformant
- Small TSOP-5 Package
- ESD > 8 KV (HBM)
- Latch-Up Current > 300 mA (JESD78)

### APPLICATIONS

- Routers/Hubs
- Switches
- Set Top boxes
- Game Controllers

### FUNCTIONAL BLOCK DIAGRAM AND PIN CONFIGURATION



### ORDERING INFORMATION

Temp Range	Package	Part Number
- 40 to 85 °C	TSOP-5	DG90LV011DV-T1-E3

### ABSOLUTE MAXIMUM RATINGS $T_A = 25\text{ }^\circ\text{C}$ , unless otherwise noted

Parameter	Limit	Unit
Reference to GND	V <sub>DD</sub>	- 0.3 to + 4
	V <sub>IN</sub>	- 0.3 to + 3.6
	V <sub>OUT</sub>	- 0.3 to + 3.9
Output short circuit current	24	mA
Storage Temperature (D Suffix)	- 65 to 150	°C
Power Dissipation (Packages) <sup>a</sup>	6-Pin TSOP-5 <sup>b</sup>	570
		mW

#### Notes

- All leads welded or soldered to PC Board.
- Derate 7.1 mW/°C above 70 °C.

SPECIFICATIONS							
Parameter	Symbol	Test Condition Otherwise Unless Specified $V_{DD} = 3.0\text{ V to }3.6\text{ V}$	Temp <sup>a</sup>	Limits - 40 °C to 85 °C			Unit
				Min <sup>b</sup>	Typ <sup>c</sup>	Max <sup>b</sup>	
<b>DC Characteristics</b>							
Output Differential Voltage	$ V_{OD} $	$R_L = 100\ \Omega$	Full	250		450	mV
VOD Magnitude Delta	$\Delta V_{OD}$				1	35	
Offset Voltage	$V_{OS}$	$R_L = 100\ \Omega$	Full	1.125	1.200	1.375	V
Offset Magnitude Delta	$\Delta V_{OS}$			0	1.4	25	mV
Power-Off Leakage	$I_{OFF}$	$V_{OUT} = \text{GND or } 3.6\text{ V}, V_{DD} = 0\text{ V}$	Full		$\pm 1$	$\pm 10$	$\mu\text{A}$
Output Short Circuit Current	$I_{OS}$	$V_{OUT+} \text{ and } V_{OUT-} = 0\text{ V}$		- 24	- 7		mA
Differential Output Short Circuit Current	$I_{OSD}$	$V_{OUT(DIFF)} = 0\text{ V}$		- 12	- 6.5		mA
Input High Voltage	$V_{IH}$		Full	2.0		$V_{DD}$	V
Input Low Voltage	$V_{IL}$			GND	0.8		
Input High Current	$I_{IH}$			$V_{IN} = 2.4\text{ V}$		$\pm 1$	10
Input Low Current	$I_{IL}$	$V_{IN} = 0.5\text{ V}$		$\pm 1$	10		
Input Capacitance	$C_{IN}$		Room		8		pF
Input Clamp Voltage	$V_{CLAMP}$	$I_{CLAMP} = - 18\text{ mA}$	Full	- 1.5	- 0.9		V
<b>Dynamic Characteristics</b>							
Differential Propagation Delay (L to H) <sup>d</sup>	$t_{PLHD}$	$R_L = 100\ \Omega, C_L = 15\text{ pF}$	Full	0.3	1.3	1.7	ns
Differential Propagation Delay (H to L) <sup>d</sup>	$t_{PHLD}$			0.3	1.2	1.7	
Differential Pulse Skew $ t_{PHLD} - t_{PLHD} $ <sup>d</sup>	$t_{SKD1}$			0	0.1	0.7	
Differential Part to Part Skew <sup>d,e</sup>	$t_{SKD3}$			0		1.0	
Differential Part to Part Skew <sup>d,f</sup>	$t_{SKD4}$			0		1.2	
Transition Time - (L to H) <sup>d</sup>	$t_{TLH}$			0.2	0.7	1.0	
Transition Time - (H to L) <sup>d</sup>	$t_{THL}$			0.2	0.7	1.0	
Maximum Operating Frequency <sup>d</sup>	$f_{MAX}$			200			
<b>Power Supply</b>							
Power Supply Range	$V_{DD}$		Full	3.0	3.3	3.6	V
Power Supply Current	$I_{DD}$	$R_L = \text{open}, V_{IN} = 0\text{ V or } V_{DD}$		7.3	9	mA	
		$R_L = 100\ \Omega, V_{IN} = 0\text{ V or } V_{DD}$		7.4	10		

Notes

- a. Room = 25 °C, Full = as determined by the operating suffix.
- b. The algebraic convention whereby the most negative value is a minimum and most positive a maximum, is used in this data sheet.
- c. Typical values are based on  $V_{DD} = + 3.3\text{ V}$  and  $T_A = + 25\text{ °C}$ . Values are for design aid only and are not guaranteed nor subject to production testing.
- d. Guarantee by design or characterization, not subjected to production test.
- e.  $t_{SKD3}$ , Differential Part-to-Part Skew, is defined as the difference between the minimum and maximum specified differential propagation delays. This specification applies to devices at the same  $V_{DD}$  and with 5 °C of each other within the operatin temperature range.
- f.  $t_{SKD4}$ , Part-to-Part Skew, is the differential Channel-to-Channel skew of any event between devices. This specification applies to devices over recommended operating temperature and voltage ranges, and across process distribution.  $t_{SKD4}$  is defined as  $|\text{Max} - \text{Min}|$  differential propagation delay.

TEST CIRCUITS

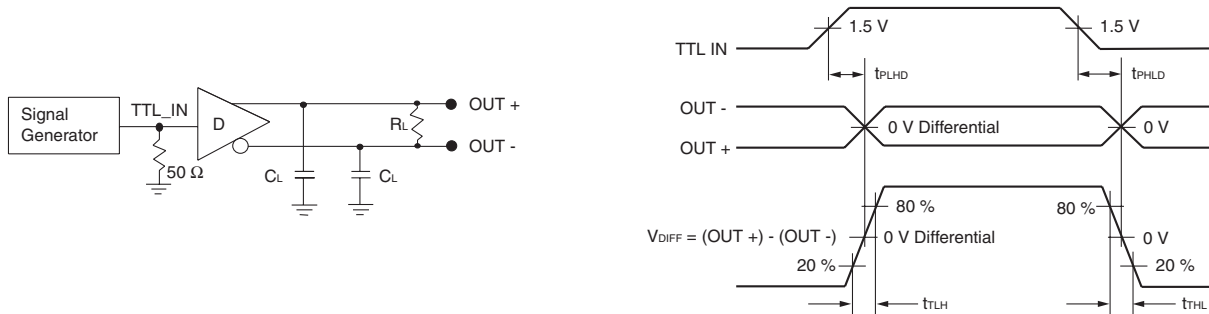


Figure 1. Driver Differential Propagation Delay / Transition Time



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