

# AL796

## MagnetoResistive FixPitch Sensor (2 mm)

The AL796 is an AnisotropicMagnetoResistive (AMR) position sensor. The sensor contains two Wheatstone bridges shifted against each other. The output signals are proportional to sine and cosine of the coordinate to be measured (see Fig. 2).

The MR strips of this FixPitch sensor geometrically match to a pole length of 2 mm (equal to a magnetic period of 4 mm). Additionally, the sensor layout incorporates PerfectWave technology, i. e. the position of each block of MR strips has a special arrangement to filter higher harmonics and to increase the signal quality. The resistors in this FixPitch sensor are distributed over several poles (2), thus the errors in the magnetic measurement scale are reduced without any signal delay. The amplitude is almost constant in a wide working range between sensor and magnetic scale.

The bond version of AL796 is available as bare die. For SMD processing, the sensor is available in a Si16, LGA or SIN8 package.

### Product Overview of AL796

Article description	Package	Delivery type
AL796ACA-AC	Bare Die	Wafer pack (192)
AL796ACA-AB	Die on Wafer <sup>1)</sup>	Waferbox
AL796AKA-AC	SIL6	Wafer pack (90)
AL796AMA-AE	LGA6L	Tape on reel (2500)
AL796AIA-AE	SIN8	Tape on reel (2500)
AL796AIA-AS	SIN8-D	Tape on reel (2500)

<sup>1)</sup> Minimum order quantities apply.

### Quick Reference Guide

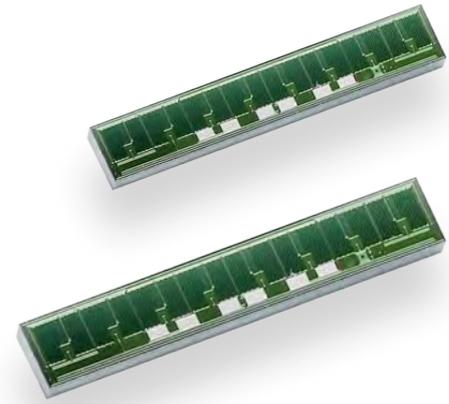
Symbol	Parameter	Min.	Typ.	Max.	Unit
P	Pitch (magnetic pole length)	-	2	-	mm
V <sub>CC</sub>	Supply voltage	-	5.0	-	V
V <sub>off</sub>	Offset voltage per V <sub>CC</sub>	-2.0	-	+2.0	mV/V
V <sub>peak</sub>	Signal amplitude per V <sub>CC</sub>	9.0	11.0	13.0	mV/V
R <sub>B</sub>	Bridge resistance	2.2	3.4	4.6	kΩ

### Absolute Maximum Ratings

In accordance with the absolute maximum rating system (IEC60134).

Symbol	Parameter	Min.	Max.	Unit
V <sub>CC</sub>	Supply voltage	-9.0	+9.0	V
T <sub>amb</sub>	Ambient temperature	-40	+125	°C
T <sub>stg(Die)</sub>	Storage temperature bare die version	-65	+150	°C
T <sub>stg(others)</sub>	Storage temperature others	-40	+125	°C

Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.



### Features

- Based on the AnisotropicMagnetoResistive (AMR) effect
- Contains two Wheatstone bridges on Chip
- Sine and Cosine output
- Adapted to 2 mm poles
- PurePitch design (2 poles)
- PerfectWave technology
- Ambient temperature range from -40 °C to +125 °C

### Advantages

- Contactless angle and position measurement
- Large air gap
- Excellent accuracy
- Minimized offset voltage
- Negligible hysteresis

### Applications

Incremental or absolute encoder for linear or rotary movements in various industrial applications, for example:

- Motor integrated encoder
- Motorfeedback system



## Magnetic Data

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$H_{ext}$	Magnetic field strength <sup>1)</sup>		5.0	25.0	-	kA/m

<sup>1)</sup> The stimulating magnetic field in the sensor plane to ensure minimum error specified in note 8.

## Electrical Data

$T_{amb} = 25\text{ °C}$ ;  $H_{ext} = 25\text{ kA/m}$ ;  $V_{CC} = 5\text{ V}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$V_{CC}$	Supply voltage		-	5.0	-	V
$V_{off}$	Offset voltage per $V_{CC}$	See Fig.2	-2.0	-	+2.0	mV/V
$TC_{V_{off}}$	Temperature coefficient of $V_{off}$ <sup>2)</sup>	$T_{amb} = (-40...+125)\text{ °C}$	-4.0	-	+4.0	( $\mu\text{V/V}$ )/K
$V_{peak}$	Signal amplitude per $V_{CC}$ <sup>3)</sup>	See Fig.2	9.0	11.0	13.0	mV/V
$TC_{V_{peak}}$	Temperature coefficient of $V_{peak}$ <sup>4)</sup>	$T_{amb} = (-40...+125)\text{ °C}$	-0.48	-0.42	-0.36	%/K
$R_B$	Bridge resistance <sup>5)</sup>		2.2	3.4	4.6	k $\Omega$
$R_S$	Sensor resistance <sup>6)</sup>		1.1	1.7	2.3	k $\Omega$
$TC_{R_B}$	Temperature coefficient of $R_B$ <sup>7)</sup>	$T_{amb} = (-40...+125)\text{ °C}$	0.24	0.28	0.32	%/K

$$^2) TC_{V_{off}} = \frac{V_{off(T_2)} - V_{off(T_1)}}{T_2 - T_1} \text{ with } T_1 = +25\text{ °C}; T_2 = +125\text{ °C}.$$

<sup>3)</sup> Maximal output voltage without offset influences. Periodicity of  $V_{peak}$  is  $\sin(P)$  and  $\cos(P)$ .

$$^4) TC_{V_{peak}} = 100 \cdot \frac{V_{peak(T_2)} - V_{peak(T_1)}}{V_{peak(T_{amb})} \cdot (T_2 - T_1)} \text{ with } T_1 = +25\text{ °C}; T_2 = +125\text{ °C}.$$

<sup>5)</sup> Bridge resistance between  $+V_{O1}$  and  $-V_{O1}$ ,  $+V_{O2}$  and  $-V_{O2}$ .

<sup>6)</sup> Sensor resistance between  $V_{CC}$  and GND.

$$^7) TC_{R_B} = 100 \cdot \frac{R_{B(T_2)} - R_{B(T_1)}}{R_{B(T_{amb})} \cdot (T_2 - T_1)} \text{ with } T_1 = +25\text{ °C}; T_2 = +125\text{ °C}.$$

## Accuracy

$T_{amb} = 25\text{ °C}$ ;  $H_{ext} = 25\text{ kA/m}$ ;  $V_{CC} = 5\text{ V}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
$\Delta X$	Measurement error <sup>8)</sup>		-	5.0	7.0	$\mu\text{m}$
k	Amplitude synchronism <sup>9)</sup>		-	0.1	1	% of $V_{peak}$

<sup>8)</sup>  $\Delta X = |X_{real} - X_{measured}|$  without offset influences due to deviations from ideal sinusoidal characteristics (ascertained at an ideal magnetic scale).

$$^9) k = 100 - 100 \cdot \frac{V_{peak1}}{V_{peak2}}$$

## Dynamic Data

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
f	Frequency range		1 <sup>10)</sup>	-	-	MHz

<sup>10)</sup> No significant amplitude loss in this frequency range.

## General Data

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
P	Pitch (magnetic pole length)	See Fig. 1	-	2	-	mm
d	Distance <sup>11)</sup>	See Fig. 1	-	0.7	-	mm
$T_{amb}$	Ambient temperature		-40	-	+125	°C

<sup>11)</sup> See Fig. 3 for detailed information.

**Output Signal Information**

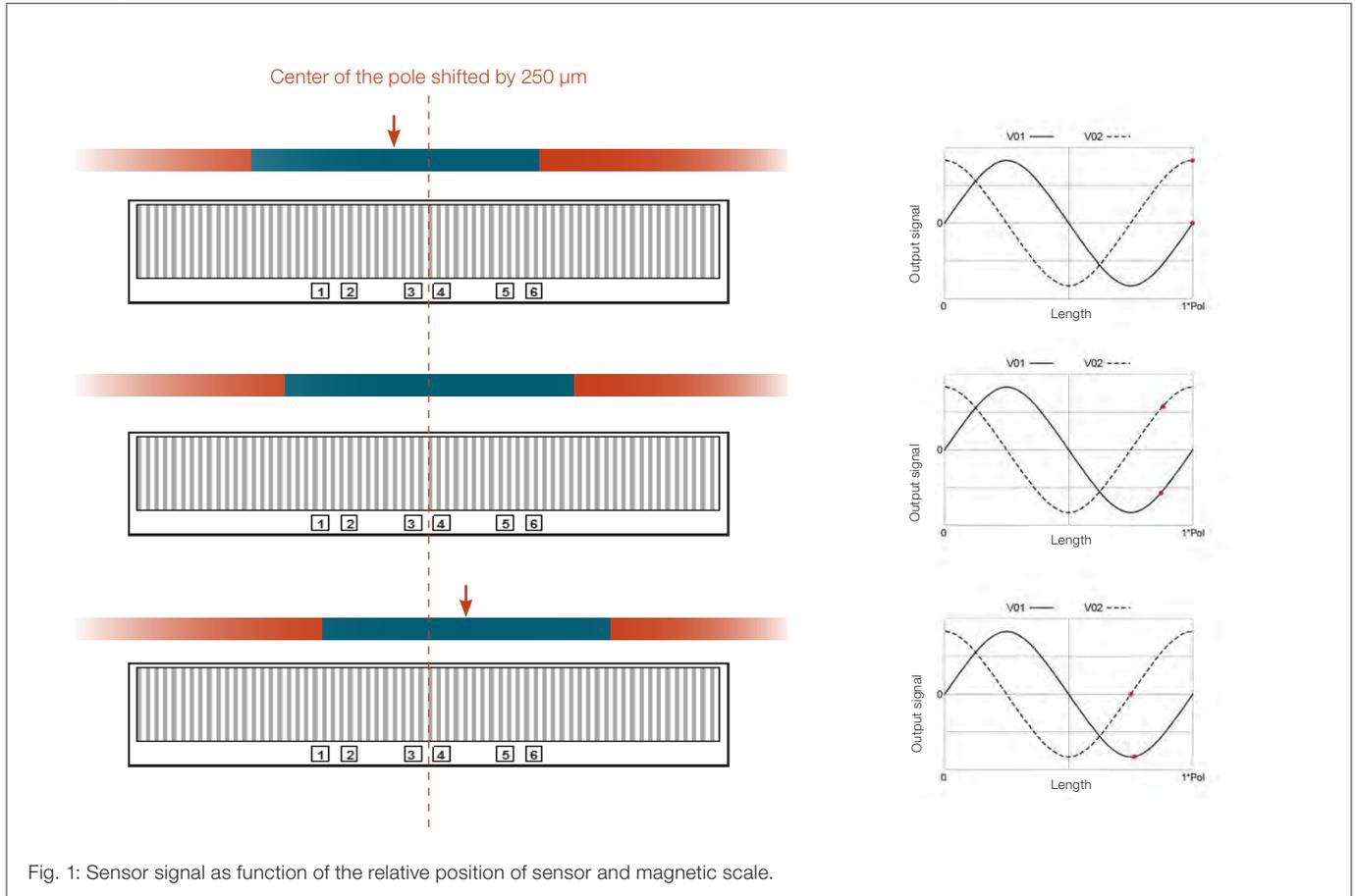


Fig. 1: Sensor signal as function of the relative position of sensor and magnetic scale.

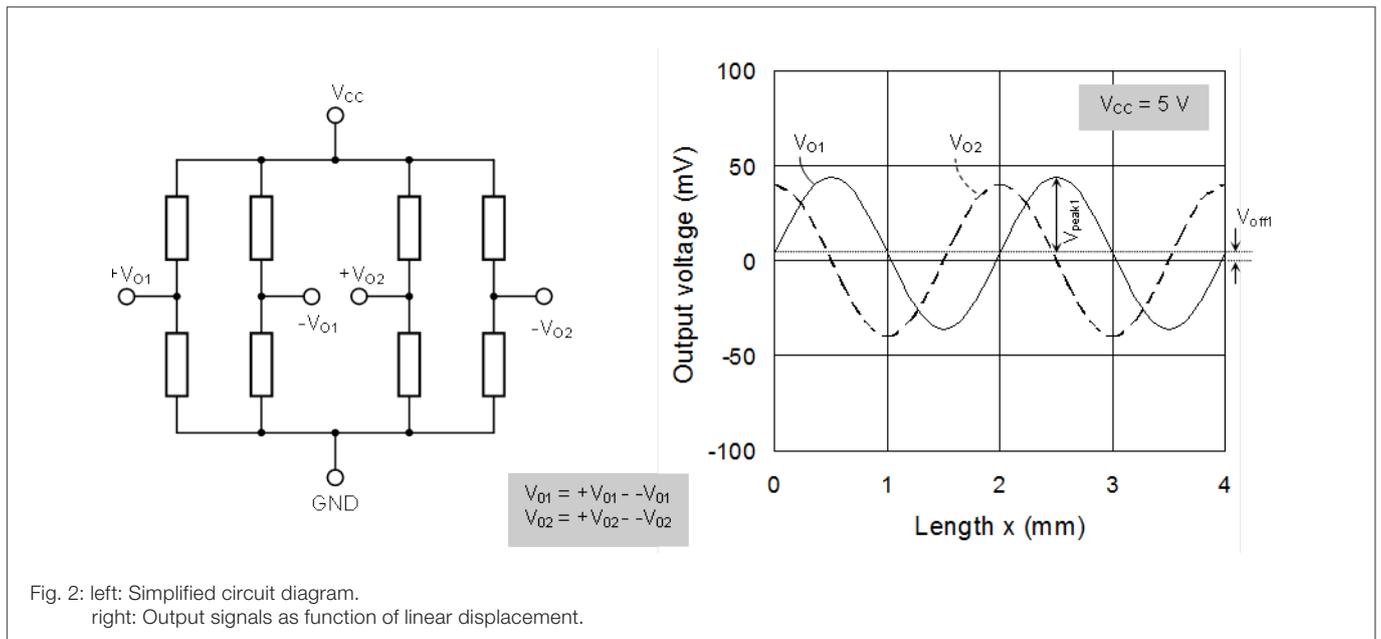


Fig. 2: left: Simplified circuit diagram.  
right: Output signals as function of linear displacement.

Typical Performance Graphs

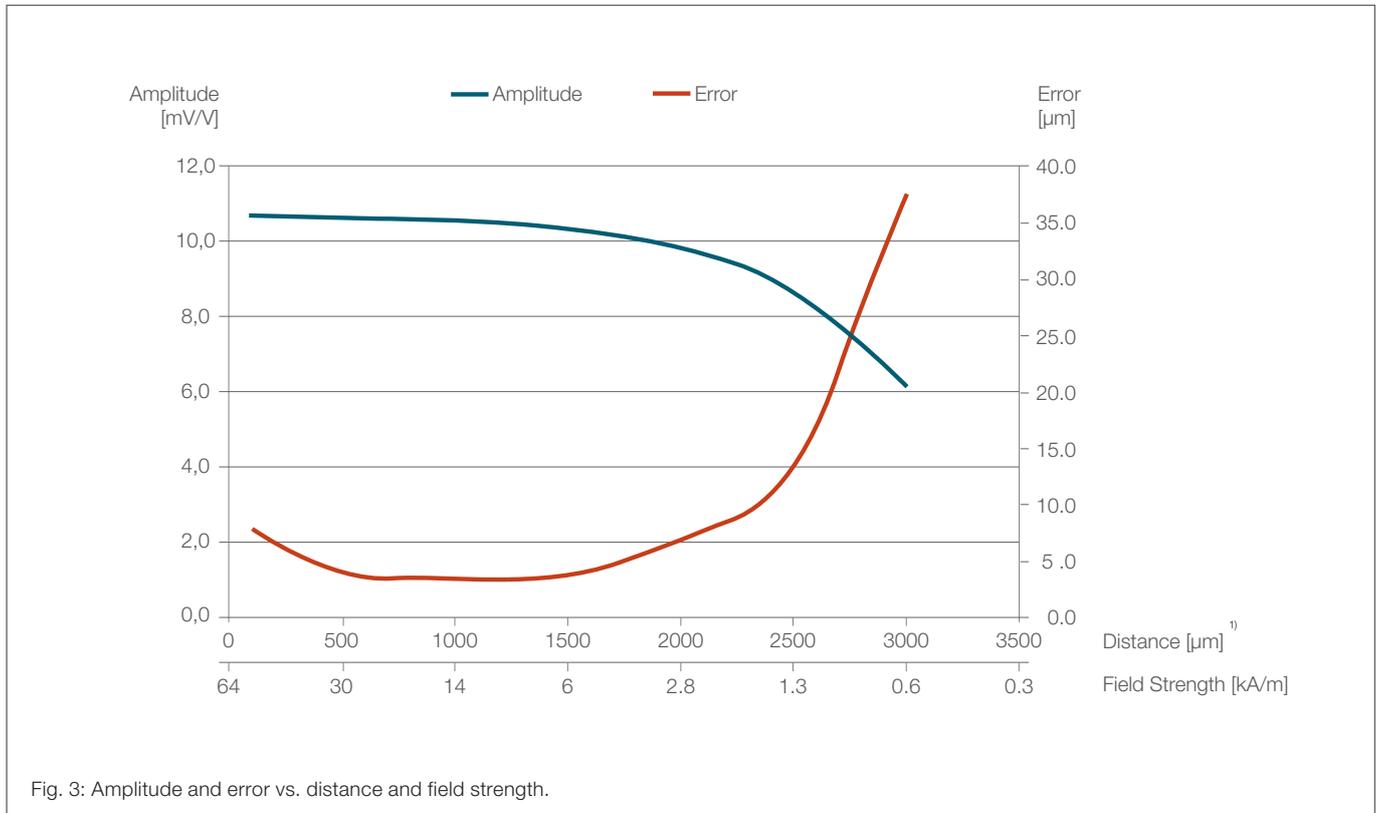


Fig. 3: Amplitude and error vs. distance and field strength.

<sup>1)</sup> In use with a plastic bound hard ferrite magnetic scale (Br = 220 mT, thickness 1 mm, mounted on stainless steel).

## AL796ACA Bare Die

### Pinning

Pad	Symbol	Parameter
1	+V <sub>O1</sub>	Positive output voltage bridge 1
2	+V <sub>O2</sub>	Positive output voltage bridge 2
3	V <sub>CC</sub>	Supply voltage
4	GND	Ground
5	-V <sub>O1</sub>	Negative output voltage bridge 1
6	-V <sub>O2</sub>	Negative output voltage bridge 2

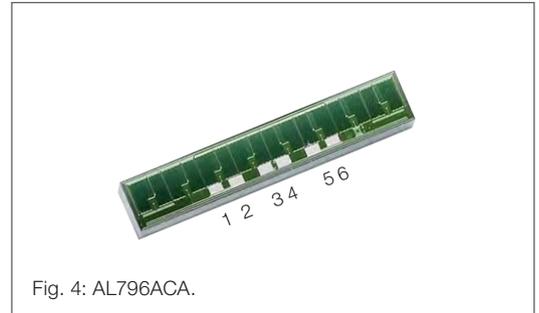


Fig. 4: AL796ACA.

### Mechanical Data

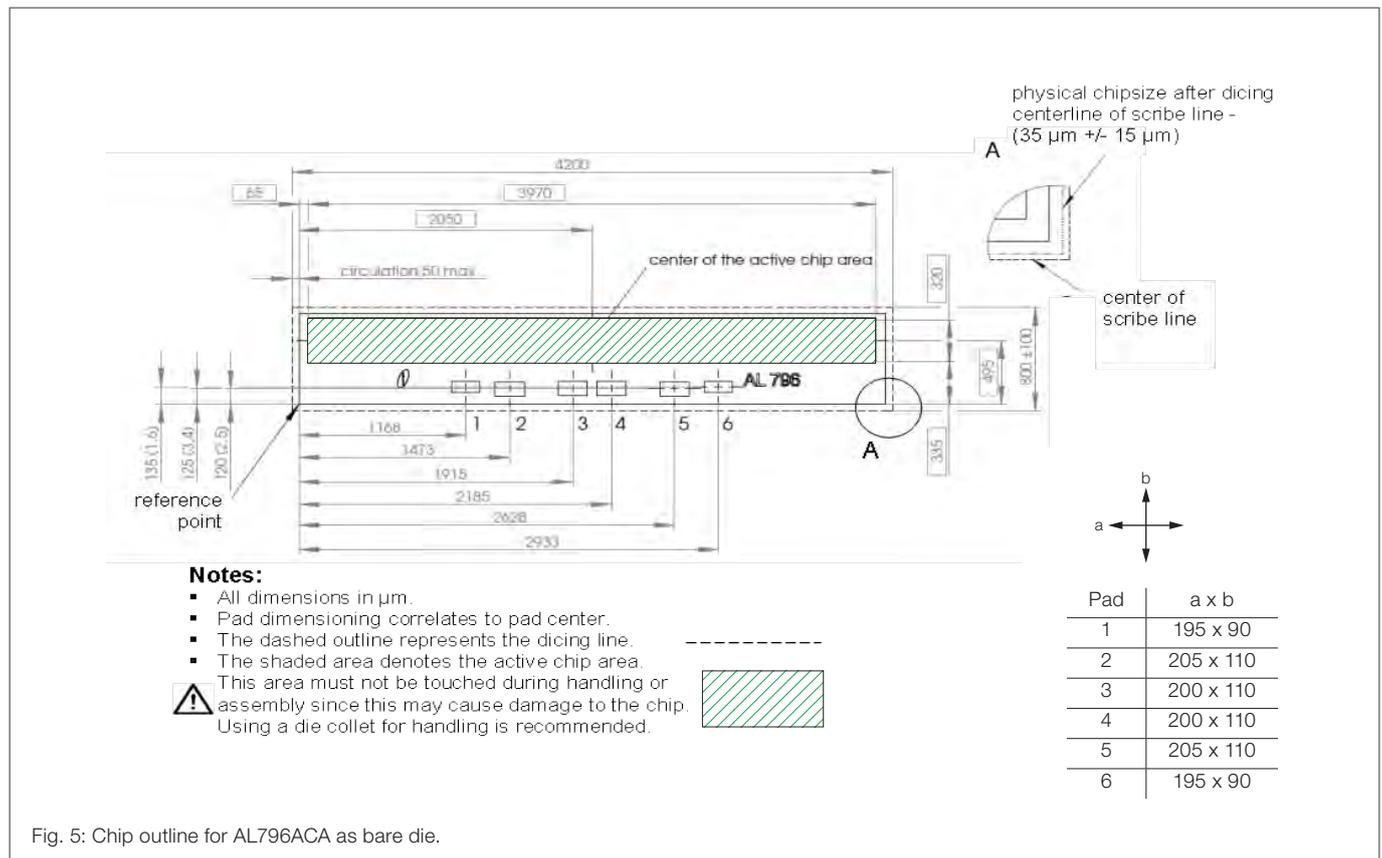


Fig. 5: Chip outline for AL796ACA as bare die.

### Data for Packaging and Interconnection Technologies

Parameter	Value	Unit
Chip area <sup>1)</sup>	4.2 x 0.8	mm <sup>2</sup>
Chip thickness	525 ± 10	μm
Pad size	See Fig. 5	-
Pad thickness	0.8	μm
Pad material	AICu	-

<sup>1)</sup> Tolerances of chip see Fig.5.

## AL796AKA SIL6 Package

### Pinning

Pad	Symbol	Parameter
1	+V <sub>O1</sub>	Positive output voltage bridge 1
2	+V <sub>O2</sub>	Positive output voltage bridge 2
3	V <sub>CC</sub>	Supply voltage
4	GND	Ground
5	-V <sub>O1</sub>	Negative output voltage bridge 1
6	-V <sub>O2</sub>	Negative output voltage bridge 2

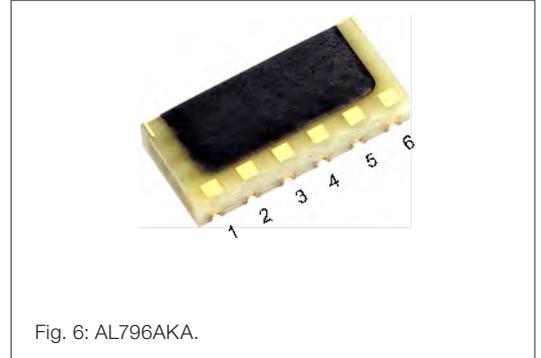


Fig. 6: AL796AKA.

### Dimensions

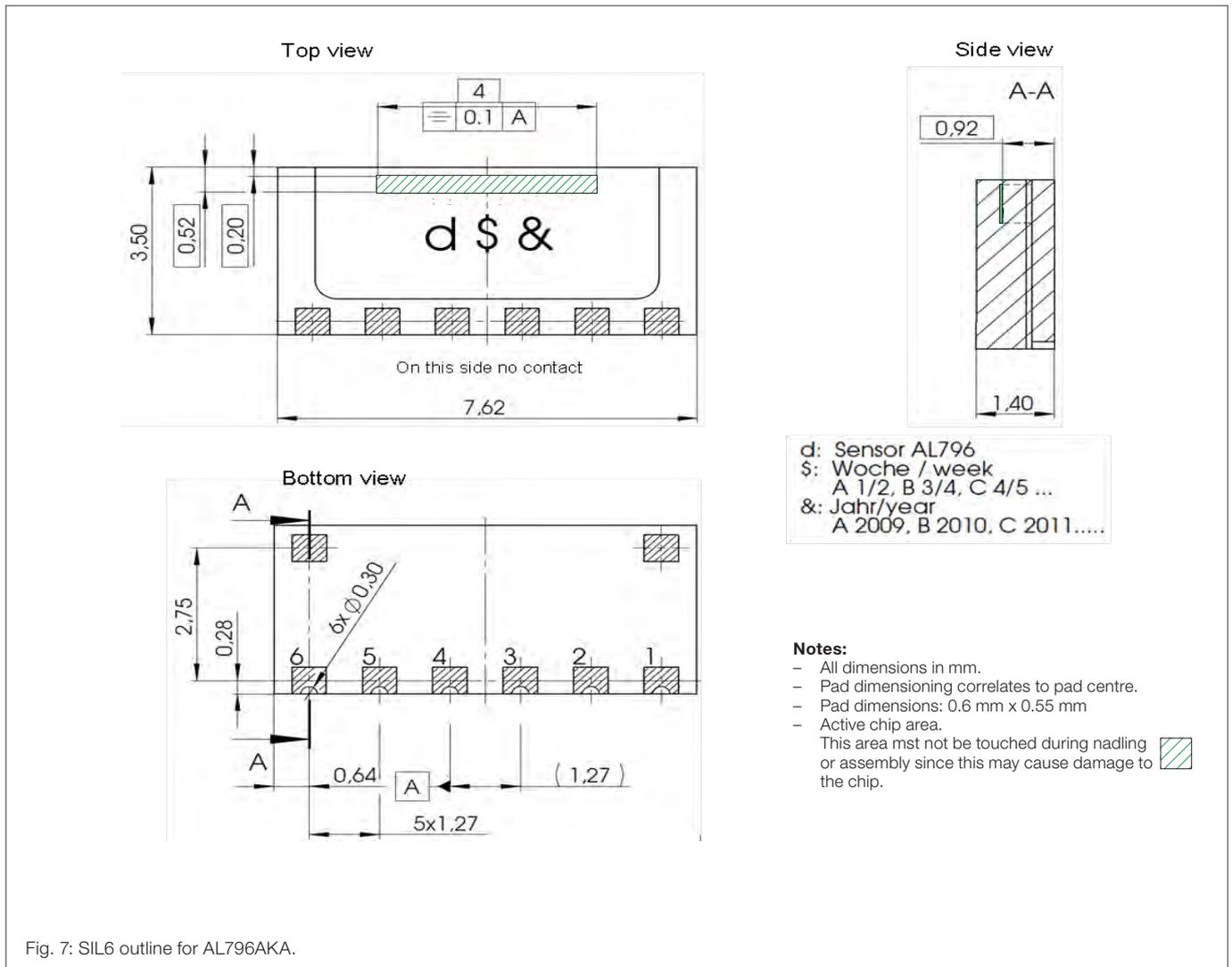


Fig. 7: SIL6 outline for AL796AKA.

## AL796AMA LGA6L Package

### Pinning

Pad	Symbol	Parameter
1	+V <sub>O1</sub>	Positive output voltage bridge 1
2	+V <sub>O2</sub>	Positive output voltage bridge 2
3	GND	Ground
4	V <sub>CC</sub>	Supply voltage
5	-V <sub>O1</sub>	Negative output voltage bridge 1
6	-V <sub>O2</sub>	Negative output voltage bridge 2
7-10	NC	Not connected

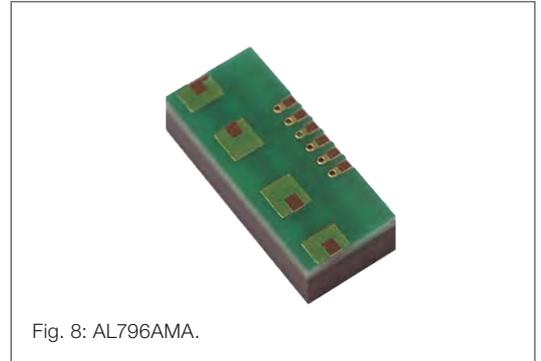


Fig. 8: AL796AMA.

### Dimensions

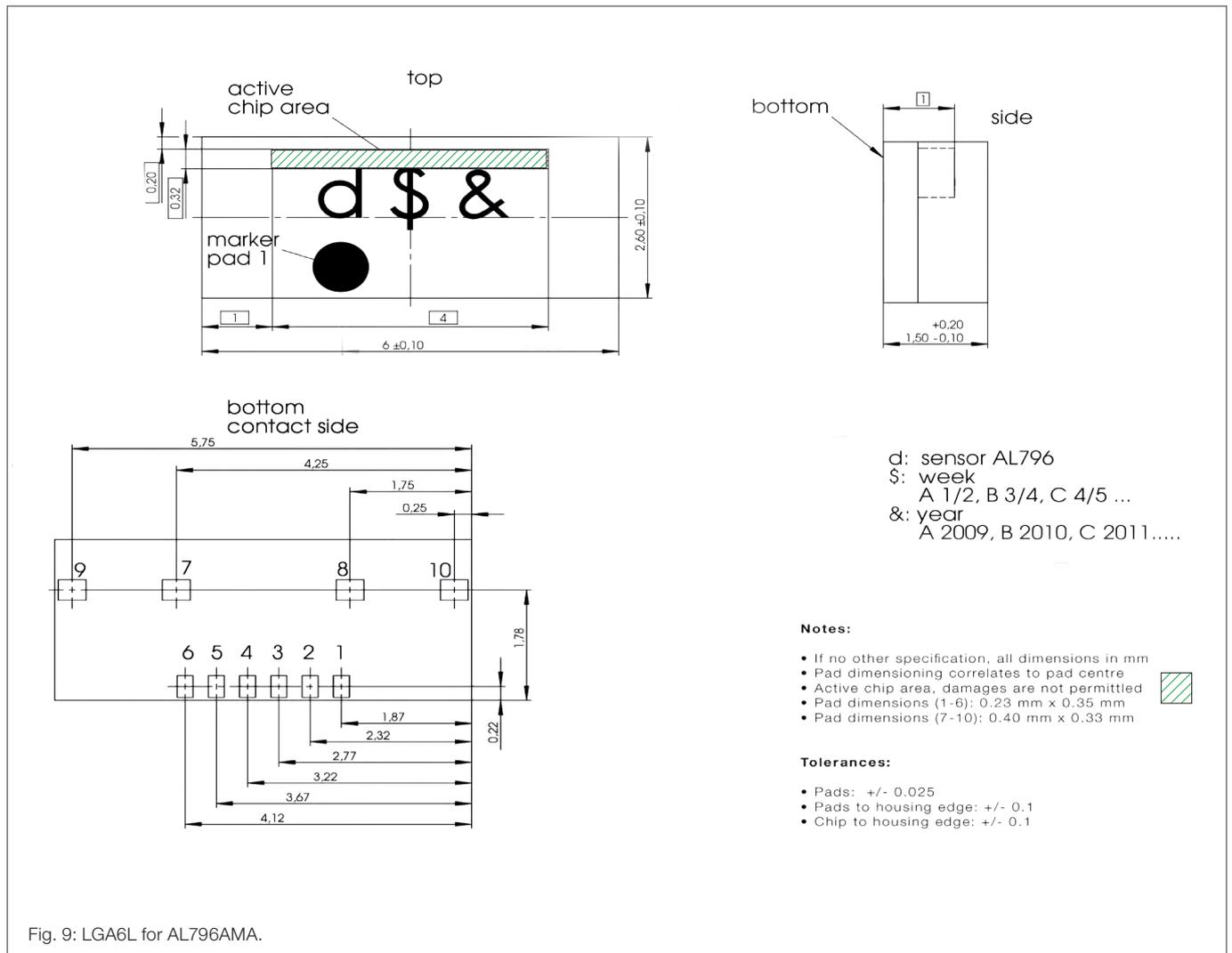


Fig. 9: LGA6L for AL796AMA.

## AL796AIA SIN8 Package

### Pinning

Pad	Symbol
1	n.c.
2	+V <sub>O1</sub>
3	+V <sub>O2</sub>
4	V <sub>CC</sub>
5	GND
6	-V <sub>O1</sub>
7	-V <sub>O2</sub>
8	n.c.

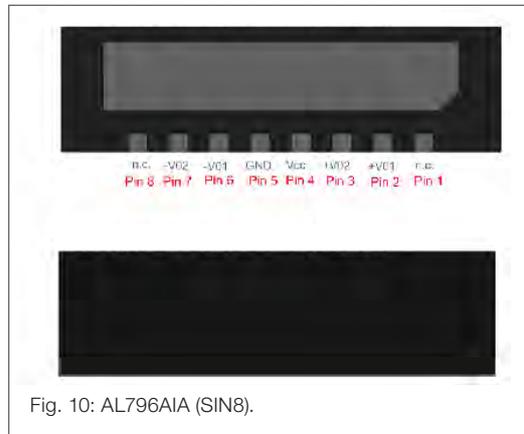
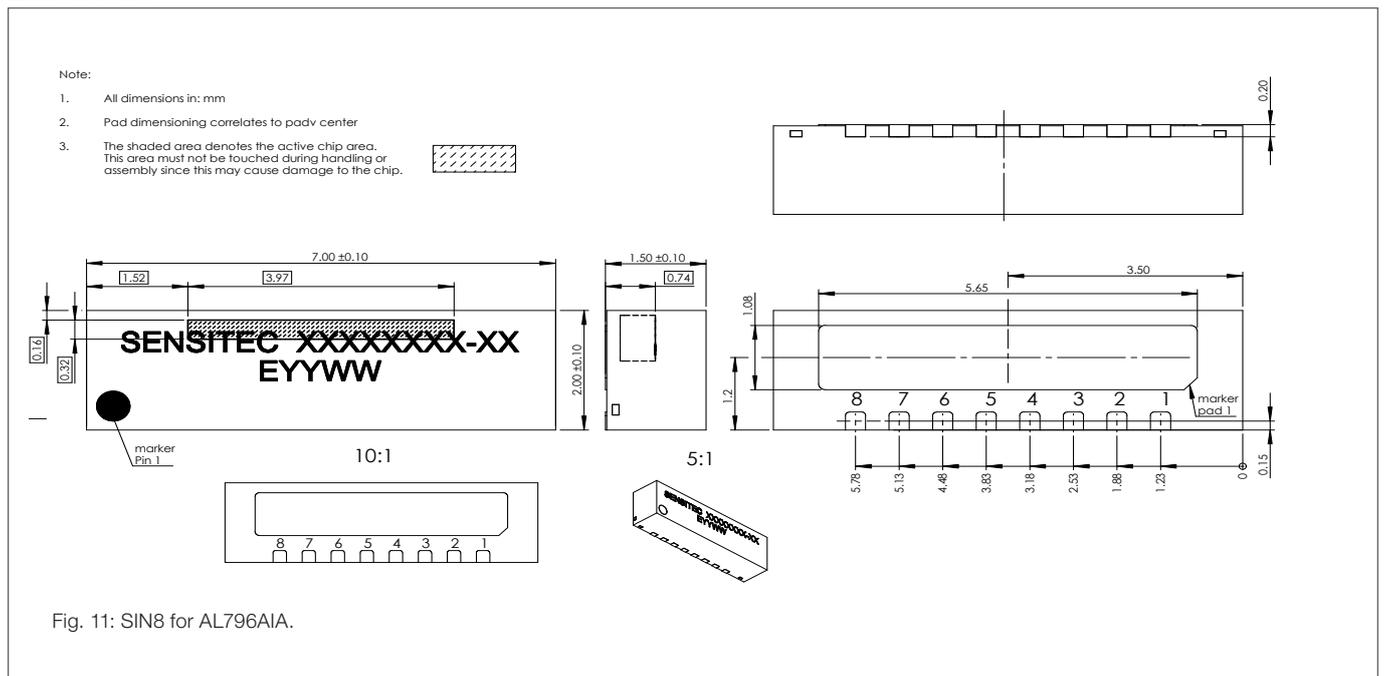


Fig. 10: AL796AIA (SIN8).

### Dimensions





### Special Design Features



**PerfectWave**

Sensors with PerfectWave design provide the best signal quality, highest accuracy and optimal sensor linearity by filtering out higher harmonics in the signal. The linearity of the sensor is assured, even for weak magnetic field measurement.



**PurePitch**

In PurePitch sensors the FixPitch principle is extended over several poles in order to increase accuracy still further. This arrangement reduces the influence of errors in the measurement scale and improves the immunity to interference fields.



**FixPitch**

FixPitch sensors are adapted to the pole length (pitch) of the measurement scale. The linearity of the sensor is optimized and the influence of interference fields is minimized.

## General Information

### Product Status

Article	Status
AL796ACA-AC	The product is in series production.
AL796ACA-AB	The product is in series production.
AL796AKA-AC	The product is in series production.
AL796AMA-AE	The product is in series production.
AL796AIA-AE	The product is under development, qualification is on going. Deliverables have a sample status. The datasheet is preliminary.
AL796AIA-AS	The product is under development , qualification is on going. Deliverables have a sample status. The datasheet is preliminary.
<b>Note</b>	The status of the product may have changed since this data sheet was published. The latest information is available on the internet at <a href="http://www.sensitec.com">www.sensitec.com</a> .

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## Changelist

Version	Description of the Change	Date
AL796.DSE.13	New product variant/Technical changes (p. 1, p. 8. p. 11) / New page (p. 9)	03/2022
AL796.DSE.12	New page (p. 8) / various textual changes	12/2021
AL796.DSE.11	Various textual changes	01/2020
AL796.DSE.00	Original (pp. 1-7)	04/2012

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