NEC

MOS INTEGRATED CIRCUIT

μPD421165

1 M-BIT DYNAMIC RAM
64K-WORD BY 16-BIT, HYPER PAGE MODE (EDO), BYTE READ/WRITE MODE

Description

The μPD421165 is a 65,536 words by 16 bits CMOS dynamic RAM with optional hyper page mode (EDO).
Hyper page mode (EDO) is a kind of the page mode and is useful for the read operation.
The μPD421165 is packaged in 44-pin plastic TSOP (II) and 40-pin plastic SOJ.

Features

- Hyper page mode (EDO)
- 65,536 words by 16 bits organization
- Single +5.0 V ±10 % power supply
- $\overline{CAS}$ before $\overline{RAS}$ refresh, $\overline{RAS}$ only refresh, Hidden refresh
- 256 refresh cycles/4 ms

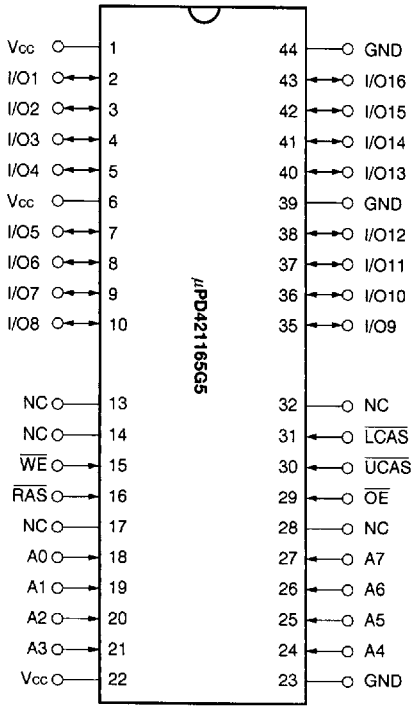
Part number	Power consumption		Access time (MAX.)	R/W cycle time (MIN.)	Hyper page mode (EDO) cycle time (MIN.)
	Active (MAX.)	Standby (MAX.)			
μPD421165-25-A	632.5 mW	5.5 mW (CMOS level input)	70 ns	124 ns	25 ns
μPD421165-30-A					30 ns
μPD421165-25					25 ns
μPD421165-30					30 ns
μPD421165-35					35 ns

Ordering Information

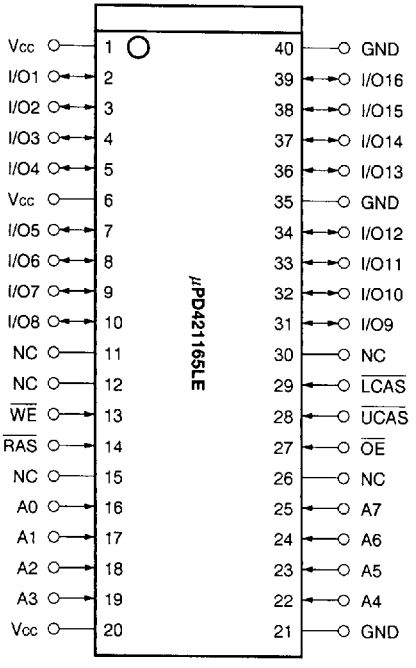
Part number	Access time (MAX.)	Hyper page mode (EDO) cycle time (MIN.)	Package	Refresh
μPD421165G5-25-A	70 ns	25 ns	44-pin plastic TSOP (II) (400 mil)	$\overline{CAS}$ before $\overline{RAS}$ refresh $\overline{RAS}$ only refresh Hidden refresh
μPD421165G5-30-A	70 ns	30 ns		
μPD421165G5-25	70 ns	25 ns		
μPD421165G5-30	70 ns	30 ns		
μPD421165G5-35	70 ns	35 ns		
μPD421165LE-25-A	70 ns	25 ns	40-pin plastic SOJ (400 mil)	
μPD421165LE-30-A	70 ns	30 ns		
μPD421165LE-25	70 ns	25 ns		
μPD421165LE-30	70 ns	30 ns		
μPD421165LE-35	70 ns	35 ns		

Pin Configurations (Marking Side)

44-pin Plastic TSOP (II) (400 mil)

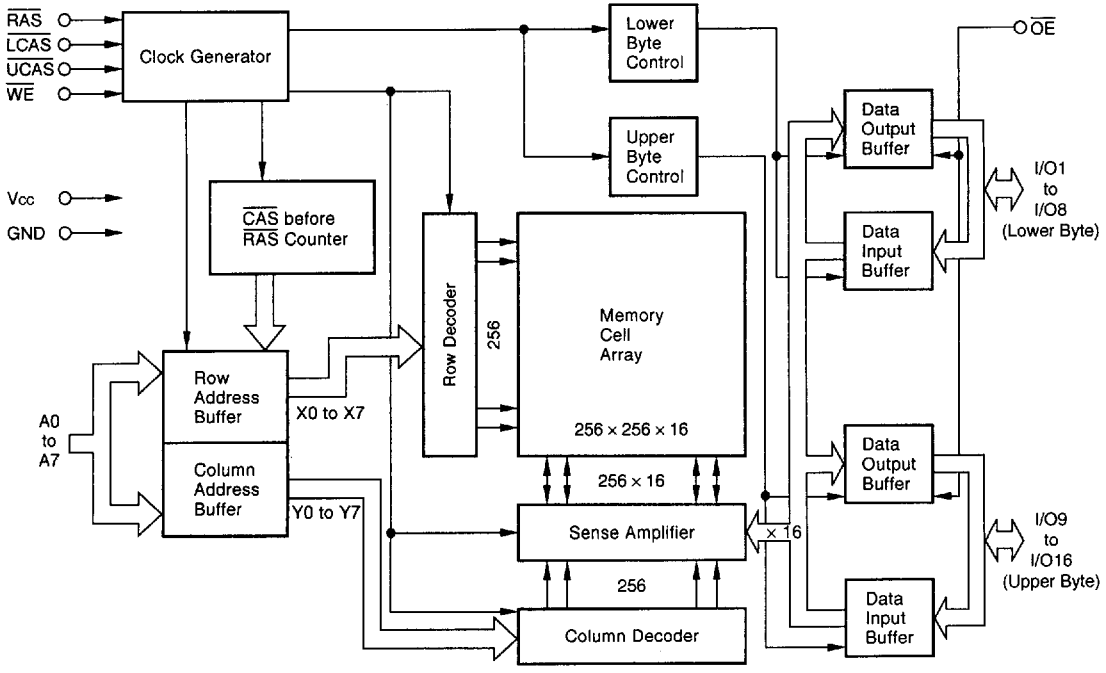


40-pin Plastic SOJ (400 mil)



A0 to A7	:	Address Inputs
I/O1 to I/O16	:	Data Inputs/Outputs
$\overline{RAS}$	:	Row Address Strobe
$\overline{UCAS}$	:	Column Address Strobe (upper)
$\overline{LCAS}$	:	Column Address Strobe (lower)
$\overline{WE}$	:	Write Enable
$\overline{OE}$	:	Output Enable
Vcc	:	Power Supply
GND	:	Ground
NC	:	No Connection

Block Diagram



Input/Output Pin Functions

The μPD421165 has input pins $\overline{RAS}$, $\overline{CAS}$[Note], $\overline{WE}$, $\overline{OE}$, A0 to A7 and input/output pins I/O1 to I/O16.

Pin name	Input/Output	Function
$\overline{RAS}$ (Row address strobe)	Input	$\overline{RAS}$ activates the sense amplifier by latching a row address and selecting a corresponding word line. It refreshes memory cell array of one line selected by the row address. It also selects the following function. • $\overline{CAS}$ before $\overline{RAS}$ refresh
$\overline{CAS}$ (Column address strobe)	Input	$\overline{CAS}$ activates data input/output circuit by latching column address and selecting a digit line connected with the sense amplifier.
A0 to A7 (Address inputs)	Input	Address bus. Input total 16-bit of address signal, upper 8-bit and lower 8-bit in sequence (address multiplex method). Therefore, one word is selected from 65,536-word by 16-bit memory cell array. In actual operation, latch row address by specifying row address and activating $\overline{RAS}$. Then, switch the address bus to column address and activate $\overline{CAS}$. Each address is taken into the device when $\overline{RAS}$ and $\overline{CAS}$ are activated. Therefore, the address input setup time (t_{ASR}, t_{ASC}) and hold time (t_{RAH}, t_{CAH}) are specified for the activation of $\overline{RAS}$ and $\overline{CAS}$.
$\overline{WE}$ (Write enable)	Input	Write control signal. Write operation is executed by activating $\overline{RAS}$, $\overline{CAS}$ and $\overline{WE}$.
$\overline{OE}$ (Output enable)	Input	Read control signal. Read operation can be executed by activating $\overline{RAS}$, $\overline{CAS}$ and $\overline{OE}$. If $\overline{WE}$ is activated during read operation, $\overline{OE}$ is to be ineffective in the device. Therefore, read operation cannot be executed.
I/O1 to I/O16 (Data inputs/outputs)	Input/Output	16-bit data bus. I/O1 to I/O16 are used to input/output data.

Note $\overline{CAS}$ means $\overline{UCAS}$ and $\overline{LCAS}$.

Hyper Page Mode (EDO)

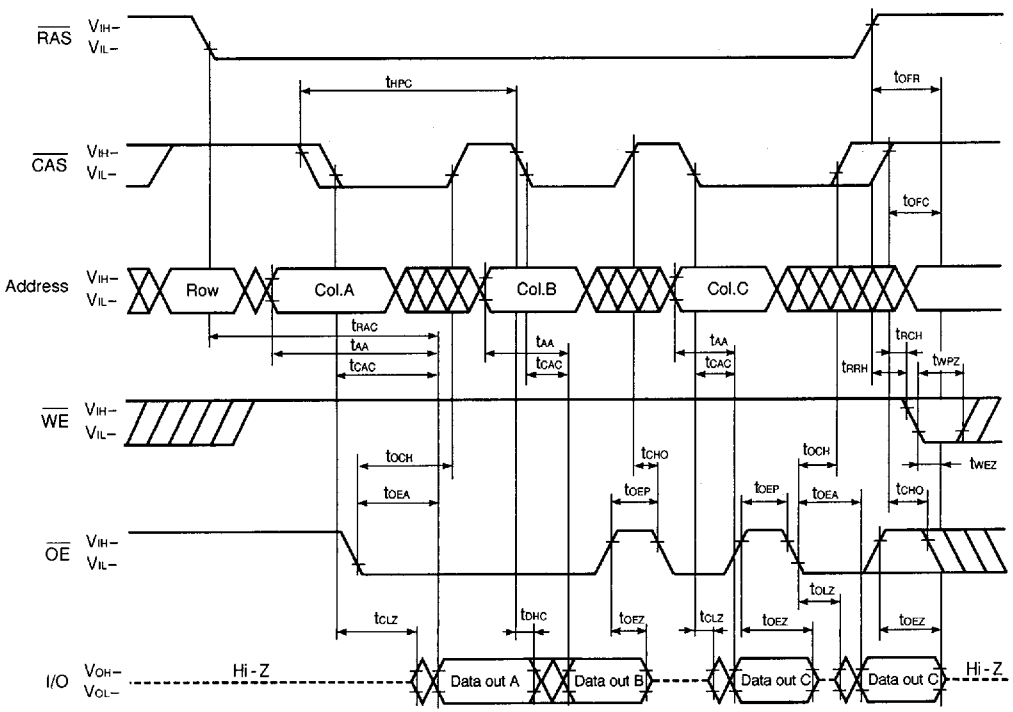
The hyper page mode (EDO) is a kind of page mode with enhanced features. The two major features of the hyper page mode (EDO) are as follows.

1. **Data output time is extended.**
   In the hyper page mode (EDO), the output data is held to the next $\overline{CAS}$ cycle's falling edge, instead of the rising edge. For this reason, valid data output time in the hyper page mode (EDO) is extended compared with the fast page mode (= data extend function). In the fast page mode, the data output time becomes shorter as the $\overline{CAS}$ cycle time becomes shorter. Therefore, in the hyper page mode (EDO), the timing margin in read cycle is larger than that of the fast page mode even if the $\overline{CAS}$ cycle time becomes shorter.

2. **The $\overline{CAS}$ cycle time in the hyper page mode (EDO) is shorter than that in the fast page mode.**
   In the hyper page mode (EDO), due to the data extend function, the $\overline{CAS}$ cycle time can be shorter than in the fast page mode if the timing margin is the same.
   Taking a device whose t_{RAC} is 60 ns as an example, the $\overline{CAS}$ cycle time in the fast page mode is 25 ns while that in the fast page mode is 40 ns.
   In the hyper page mode (EDO), read (data out) and write (data in) cycles can be executed repeatedly during one $\overline{RAS}$ cycle. The hyper page mode (EDO) allows both read and write operations during one cycle, but the performance is equivalent to that of the fast page mode in that case.

The following shows a part of the hyper page mode (EDO) read cycle. Specifications to be observed are described in the next page.

Hyper Page Mode (EDO) Read Cycle



Cautions when using the hyper page mode (EDO)

1. $\overline{CAS}$ access should be used to operate t_{HPC} at the MIN. value.
2. To make I/Os to Hi-Z in read cycle, it is necessary to control $\overline{RAS}$, $\overline{CAS}$, $\overline{WE}$, $\overline{OE}$ as follows. The effective specification depends on the state of each signal.
   (1) Both $\overline{RAS}$ and $\overline{CAS}$ are inactive (at the end of read cycle)
   $\overline{WE}$: inactive, $\overline{OE}$: active
   t_{OFC} is effective when $\overline{RAS}$ is inactivated before $\overline{CAS}$ is inactivated.
   t_{OFR} is effective when $\overline{CAS}$ is inactivated before $\overline{RAS}$ is inactivated.
   (2) Both $\overline{RAS}$ and $\overline{CAS}$ are active or either $\overline{RAS}$ or $\overline{CAS}$ is active (in read cycle)
   $\overline{WE}$, $\overline{OE}$: inactive ····· t_{OEZ} is effective.
   (3) Both $\overline{RAS}$ and $\overline{CAS}$ are inactive or $\overline{RAS}$ is active and $\overline{CAS}$ is inactive (at the end of read cycle)
   $\overline{WE}$, $\overline{OE}$: active and either t_{RRH} or t_{RCH} must be met ····· t_{WEZ} and t_{WPZ} are effective.
3. In read cycle, the effective specification depends on the state of $\overline{CAS}$ signal when controlling data output with the $\overline{OE}$ signal.
   (1) $\overline{CAS}$: inactive, $\overline{OE}$: active ····· t_{CHO} is effective.
   (2) $\overline{CAS}$, $\overline{OE}$: active ····· t_{OCH} is effective.

Electrical Specifications

- $\overline{CAS}$ means $\overline{UCAS}$ and $\overline{LCAS}$.
- All voltages are referenced to GND.
- After power up ($V_{CC} \geq V_{CC\,(MIN.)}$), wait more than 100 μs ($\overline{RAS}$, $\overline{CAS}$ inactive) and then, execute eight $\overline{CAS}$ before $\overline{RAS}$ or $\overline{RAS}$ only refresh cycles as dummy cycles to initialize internal circuit.

Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating	Unit
Voltage on any pin relative to GND	V_T		−1.0 to +7.0	V
Supply voltage	V_{CC}		−1.0 to +7.0	V
Output current	I_O		50	mA
Power dissipation	P_D		1	W
Operating ambient temperature	T_A		0 to +70	°C
Storage temperature	T_{stg}		−55 to +125	°C

Caution Exposing the device to stress above those listed in Absolute Maximum Ratings could cause permanent damage. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

Recommended Operating Conditions

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Supply voltage	V_{CC}		4.5	5.0	5.5	V
High level input voltage	V_{IH}		2.4		V_{CC} + 1.0	V
Low level input voltage	V_{IL}		−1.0		+0.8	V
Operating ambient temperature	T_A		0		70	°C

Capacitance (T_A = 25 °C, f = 1 MHz)

Parameter	Symbol	Test condition	MIN.	TYP.	MAX.	Unit
Input capacitance	C_{I1}	Address			5	pF
	C_{I2}	$\overline{RAS}$, $\overline{CAS}$, $\overline{WE}$, $\overline{OE}$			7	
Data input/output capacitance	$C_{I/O}$	I/O			7	pF

DC Characteristics (Recommended operating conditions unless otherwise noted)

Parameter	Symbol	Test condition		MIN.	MAX.	Unit	Notes
Operating current	I_{CC1}	$\overline{RAS}$, $\overline{CAS}$ cycling $t_{RC} = t_{RC(MIN.)}$, I_O = 0 mA	t_{RAC} = 70 ns		115	mA	1, 2, 3
Standby current	I_{CC2}	$\overline{RAS}$, $\overline{CAS} \geq V_{IH(MIN.)}$, I_O = 0 mA			2.0	mA	
		$\overline{RAS}$, $\overline{CAS} \geq V_{CC} - 0.2$ V, I_O = 0 mA			1.0		
$\overline{RAS}$ only refresh current	I_{CC3}	$\overline{RAS}$ cycling, $\overline{CAS} \geq V_{IH(MIN.)}$ $t_{RC} = t_{RC(MIN.)}$, I_O = 0 mA	t_{RAC} = 70 ns		115	mA	1, 2, 3, 4
Operating current (Hyper page mode (EDO))	I_{CC4}	$\overline{RAS} \leq V_{IL(MAX.)}$, $\overline{CAS}$ cycling $t_{HPC} = t_{HPC(MIN.)}$, I_O = 0 mA	t_{HPC} = 25 ns		115	mA	1, 2, 5
			t_{HPC} = 30 ns		105		
			t_{HPC} = 35 ns		95		
$\overline{CAS}$ before $\overline{RAS}$ refresh current	I_{CC5}	$\overline{RAS}$ cycling $t_{RC} = t_{RC(MIN.)}$, I_O = 0 mA	t_{RAC} = 70 ns		115	mA	1, 2
Input leakage current	$I_{I(L)}$	V_I = 0 to 5.5 V All other pins not under test = 0 V		−10	+10	μA	
Output leakage current	$I_{O(L)}$	V_O = 0 to 5.5 V Output is disabled (Hi-Z)		−10	+10	μA	
High level output voltage	V_{OH}	I_O = −2.5 mA		2.4		V	
Low level output voltage	V_{OL}	I_O = +2.1 mA			0.4	V	

Notes 1. I_{CC1}, I_{CC3}, I_{CC4} and I_{CC5} depend on cycle rates (t_{RC} and t_{HPC}).

2. Specified values are obtained with outputs unloaded.

3. I_{CC1} and I_{CC3} are measured assuming that address can be changed once or less during $\overline{RAS} \leq V_{IL(MAX.)}$ and $\overline{CAS} \geq V_{IH(MIN.)}$.

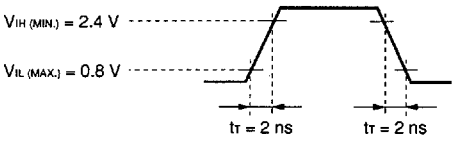
4. I_{CC3} is measured assuming that all column address inputs are held at either high or low.

5. I_{CC4} is measured assuming that all column address inputs are switched only once during each hyper page (EDO) cycle.

AC Characteristics (Recommended Operating Conditions unless otherwise noted)

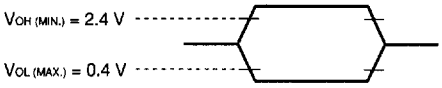
AC Characteristics Test Conditions

(1) Input timing specification

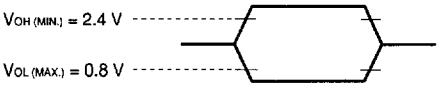


(2) Output timing specification

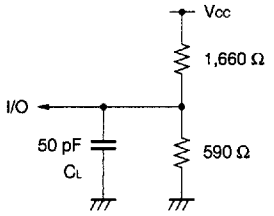
- μPD421165



- μPD421165-A



(3) Output load condition



Common to Read, Write, Read Modify Write Cycle

Parameter	Symbol	t_{HPC} = 25 ns		t_{HPC} = 30 ns		t_{HPC} = 35 ns		Unit	Notes
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Read / Write cycle time	t_{RC}	124	–	124	–	124	–	ns	
$\overline{RAS}$ precharge time	t_{RP}	50	–	50	–	50	–	ns	
$\overline{CAS}$ precharge time	t_{CPN}	10	–	10	–	10	–	ns	
$\overline{RAS}$ pulse width	t_{RAS}	70	10,000	70	10,000	70	10,000	ns	
$\overline{CAS}$ pulse width	t_{CAS}	10	10,000	12	10,000	15	10,000	ns	
$\overline{RAS}$ hold time	t_{RSH}	20	–	20	–	20	–	ns	
$\overline{CAS}$ hold time	t_{CSH}	70	–	70	–	70	–	ns	
$\overline{RAS}$ to $\overline{CAS}$ delay time	t_{RCD}	20	55	20	52	20	50	ns	1
$\overline{RAS}$ to column address delay time	t_{RAD}	15	40	15	35	15	30	ns	1
$\overline{CAS}$ to $\overline{RAS}$ precharge time	t_{CRP}	5	–	5	–	5	–	ns	2
Row address setup time	t_{ASR}	0	–	0	–	0	–	ns	
Row address hold time	t_{RAH}	10	–	10	–	10	–	ns	
Column address setup time	t_{ASC}	0	–	0	–	0	–	ns	
Column address hold time	t_{CAH}	10	–	12	–	15	–	ns	
$\overline{OE}$ lead time referenced to $\overline{RAS}$	t_{OES}	0	–	0	–	0	–	ns	
$\overline{CAS}$ to data setup time	t_{CLZ}	0	–	0	–	0	–	ns	
$\overline{OE}$ to data setup time	t_{OLZ}	0	–	0	–	0	–	ns	
$\overline{OE}$ to data delay time	t_{OED}	15	–	15	–	15	–	ns	
Masked byte write hold time referenced to $\overline{RAS}$	t_{MRH}	0	–	0	–	0	–	ns	
Transition time (rise and fall)	t_T	1	50	1	50	1	50	ns	
Refresh time	t_{REF}	–	4	–	4	–	4	ms	

Notes 1. For read cycles, access time is defined as follows:

Input conditions	Access time	Access time from $\overline{RAS}$
$t_{RAD} \leq t_{RAD\ (MAX.)}$ and $t_{RCD} \leq t_{RCD\ (MAX.)}$	$t_{RAC\ (MAX.)}$	$t_{RAC\ (MAX.)}$
$t_{RAD} > t_{RAD\ (MAX.)}$ and $t_{RCD} \leq t_{RCD\ (MAX.)}$	$t_{AA\ (MAX.)}$	$t_{RAD} + t_{AA\ (MAX.)}$
$t_{RCD} > t_{RCD\ (MAX.)}$	$t_{CAC\ (MAX.)}$	$t_{RCD} + t_{CAC\ (MAX.)}$

$t_{RAD\ (MAX.)}$ and $t_{RCD\ (MAX.)}$ are specified as reference points only ; they are not restrictive operating parameters. They are used to determine which access time (t_{RAC}, t_{AA} or t_{CAC}) is to be used for finding out when output data will be available. Therefore, the input conditions $t_{RAD} \geq t_{RAD\ (MAX.)}$ and $t_{RCD} \geq t_{RCD\ (MAX.)}$ will not cause any operation problems.

2. $t_{CRP\ (MIN.)}$ requirement is applied to $\overline{RAS}$, $\overline{CAS}$ cycles.

Read Cycle

Parameter		Symbol	t_{HPC} = 25 ns		t_{HPC} = 30 ns		t_{HPC} = 35 ns		Unit	Notes
			MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Access time from $\overline{RAS}$		t_{RAC}	–	70	–	70	–	70	ns	1
Access time from $\overline{CAS}$	μPD421165-A	t_{CAC}	–	20	–	20	–	–	ns	1
	μPD421165		–	15	–	18	–	20		
Access time from column address		t_{AA}	–	30	–	35	–	40	ns	1
Access time from $\overline{OE}$		t_{OEA}	–	20	–	20	–	20	ns	
Column address lead time referenced to $\overline{RAS}$		t_{RAL}	30	–	35	–	40	–	ns	
Read command setup time		t_{RCS}	0	–	0	–	0	–	ns	
Read command hold time referenced to $\overline{RAS}$		t_{RRH}	0	–	0	–	0	–	ns	2
Read command hold time referenced to $\overline{CAS}$		t_{RCH}	0	–	0	–	0	–	ns	2
Output buffer turn-off delay time from $\overline{OE}$		t_{OEZ}	0	15	0	15	0	15	ns	3
$\overline{CAS}$ hold time to $\overline{OE}$		t_{CHO}	5	–	5	–	5	–	ns	

Notes 1. For read cycles, access time is defined as follows:

Input conditions	Access time	Access time from $\overline{RAS}$
$t_{RAD} \leq t_{RAD\ (MAX.)}$ and $t_{RCD} \leq t_{RCD\ (MAX.)}$	$t_{RAC\ (MAX.)}$	$t_{RAC\ (MAX.)}$
$t_{RAD} > t_{RAD\ (MAX.)}$ and $t_{RCD} \leq t_{RCD\ (MAX.)}$	$t_{AA\ (MAX.)}$	$t_{RAD} + t_{AA\ (MAX.)}$
$t_{RCD} > t_{RCD\ (MAX.)}$	$t_{CAC\ (MAX.)}$	$t_{RCD} + t_{CAC\ (MAX.)}$

$t_{RAD\ (MAX.)}$ and $t_{RCD\ (MAX.)}$ are specified as reference points only; they are not restrictive operating parameters. They are used to determine which access time (t_{RAC}, t_{AA} or t_{CAC}) is to be used for finding out when output data will be available. Therefore, the input conditions $t_{RAD} \geq t_{RAD\ (MAX.)}$ and $t_{RCD} \geq t_{RCD\ (MAX.)}$ will not cause any operation problems.

2. Either $t_{RCH\ (MIN.)}$ or $t_{RRH\ (MIN.)}$ should be met in read cycles.
3. $t_{OEZ(MAX.)}$ defines the time when the output achieves the condition of Hi-Z and is not referenced to V_{OH} or V_{OL}.

Write Cycle

Parameter	Symbol	t_{HPC} = 25 ns		t_{HPC} = 30 ns		t_{HPC} = 35 ns		Unit	Notes
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
$\overline{WE}$ hold time referenced to $\overline{CAS}$	t_{WCH}	10	–	12	–	15	–	ns	1
$\overline{WE}$ pulse width	t_{WP}	10	–	12	–	15	–	ns	1
$\overline{WE}$ lead time referenced to $\overline{RAS}$	t_{RWL}	20	–	20	–	20	–	ns	
$\overline{WE}$ lead time referenced to $\overline{CAS}$	t_{CWL}	10	–	12	–	15	–	ns	
$\overline{WE}$ setup time	t_{WCS}	0	–	0	–	0	–	ns	2
$\overline{OE}$ hold time	t_{OEH}	0	–	0	–	0	–	ns	
Data-in setup time	t_{DS}	0	–	0	–	0	–	ns	3
Data-in hold time	t_{DH}	10	–	12	–	15	–	ns	3

Notes 1. $t_{WP\ (MIN.)}$ is applied to late write cycles or read modify write cycles. In early write cycles, $t_{WCH\ (MIN.)}$ should be met.

2. If $t_{WCS} \geq t_{WCS\ (MIN.)}$, the cycle is an early write cycle and the data out will remain Hi-Z through the entire cycle.

3. $t_{DS\ (MIN.)}$ and $t_{DH\ (MIN.)}$ are referenced to the $\overline{CAS}$ falling edge in early write cycles. In late write cycles and read modify write cycles, they are referenced to the $\overline{WE}$ falling edge.

Read Modify Write Cycle

Parameter	Symbol	t_{HPC} = 25 ns		t_{HPC} = 30 ns		t_{HPC} = 35 ns		Unit	Note
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Read modify write cycle time	t_{RWC}	165	–	165	–	165	–	ns	
$\overline{RAS}$ to $\overline{WE}$ delay time	t_{RWD}	89	–	89	–	89	–	ns	1
$\overline{CAS}$ to $\overline{WE}$ delay time	t_{CWD}	34	–	37	–	39	–	ns	1
Column address to $\overline{WE}$ delay time	t_{AWD}	49	–	54	–	59	–	ns	1

Note 1. If $t_{WCS} \geq t_{WCS\ (MIN.)}$, the cycle is an early write cycle and the data out will remain Hi-Z through the entire cycle. If $t_{RWD} \geq t_{RWD\ (MIN.)}$, $t_{CWD} \geq t_{CWD\ (MIN.)}$, $t_{AWD} \geq t_{AWD\ (MIN.)}$ and $t_{CPWD} \geq t_{CPWD\ (MIN.)}$, the cycle is a read modify write cycle and the data out will contain data read from the selected cell. If neither of the above conditions is met, the state of the data out is indeterminate.

Hyper Page Mode (EDO)

Parameter	Symbol	t_{HPC} = 25 ns		t_{HPC} = 30 ns		t_{HPC} = 35 ns		Unit	Notes
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
Read / Write cycle time	t_{HPC}	25	–	30	–	35	–	ns	1
$\overline{RAS}$ pulse width	t_{RASP}	70	125,000	70	125,000	70	125,000	ns	
$\overline{CAS}$ pulse width	t_{HCAS}	10	10,000	12	10,000	15	10,000	ns	
$\overline{CAS}$ precharge time	t_{CP}	10	–	10	–	10	–	ns	
Access time from $\overline{CAS}$ precharge	t_{ACP}	–	33	–	40	–	45	ns	
$\overline{CAS}$ precharge to $\overline{WE}$ delay time	t_{CPWD}	54	–	59	–	64	–	ns	2
$\overline{RAS}$ hold time from $\overline{CAS}$ precharge	t_{RHCP}	35	–	40	–	45	–	ns	
Read modify write cycle time	t_{HPRWC}	68	–	75	–	83	–	ns	
Data output hold time	t_{DHC}	5	–	5	–	5	–	ns	
$\overline{OE}$ to $\overline{CAS}$ hold time	t_{OCH}	5	–	5	–	5	–	ns	4
$\overline{OE}$ precharge time	t_{OEP}	5	–	5	–	5	–	ns	
Output buffer turn-off delay from $\overline{WE}$	t_{WEZ}	0	15	0	15	0	15	ns	3,4
$\overline{WE}$ pulse width	t_{WPZ}	10	–	10	–	10	–	ns	4
Output buffer turn-off delay from $\overline{RAS}$	t_{OFR}	0	15	0	15	0	15	ns	3,4
Output buffer turn-off delay from $\overline{CAS}$	t_{OFC}	0	15	0	15	0	15	ns	3,4
Access time from previous $\overline{WE}$ (Hyper page mode (EDO) read modify write cycle)	t_{AWE}	–	55	–	65	–	75	ns	
Access time from previous $\overline{CAS}$ (Hyper page mode (EDO) write and read cycle)	t_{ACE}	–	55	–	65	–	75	ns	

Notes 1. $t_{HPC\ (MIN.)}$ is applied to $\overline{CAS}$ access.

2. If $t_{WCS} \geq t_{WCS\ (MIN.)}$, the cycle is an early write cycle and the data out will remain Hi-Z through the entire cycle. If $t_{RWD} \geq t_{RWD\ (MIN.)}$, $t_{CWD} \geq t_{CWD\ (MIN.)}$, $t_{AWD} \geq t_{AWD\ (MIN.)}$ and $t_{CPWD} \geq t_{CPWD\ (MIN.)}$, the cycle is a read modify write cycle and the data out will contain data read from the selected cell. If neither of the above conditions is met, the state of the data out is indeterminate.

3. $t_{OFC\ (MAX.)}$, $t_{OFR\ (MAX.)}$ and $t_{WEZ\ (MAX.)}$ define the time when the output achieves the conditions of Hi-Z and is not referenced to V_{OH} or V_{OL}.

4. To make I/Os to Hi-Z in read cycle, it is necessary to control $\overline{RAS}$, $\overline{CAS}$, $\overline{WE}$, $\overline{OE}$ as follows. The effective specification depends on state of each signal.

(1) Both $\overline{RAS}$ and $\overline{CAS}$ are inactive (at the end of the read cycle)
$\overline{WE}$: inactive, $\overline{OE}$: active
t_{OFC} is effective when $\overline{RAS}$ is inactivated before $\overline{CAS}$ is inactivated.
t_{OFR} is effective when $\overline{CAS}$ is inactivated before $\overline{RAS}$ is inactivated.

(2) Both $\overline{RAS}$ and $\overline{CAS}$ are active or either $\overline{RAS}$ or $\overline{CAS}$ is active (in read cycle)
$\overline{WE}$, $\overline{OE}$: inactive ····· t_{OEZ} is effective.

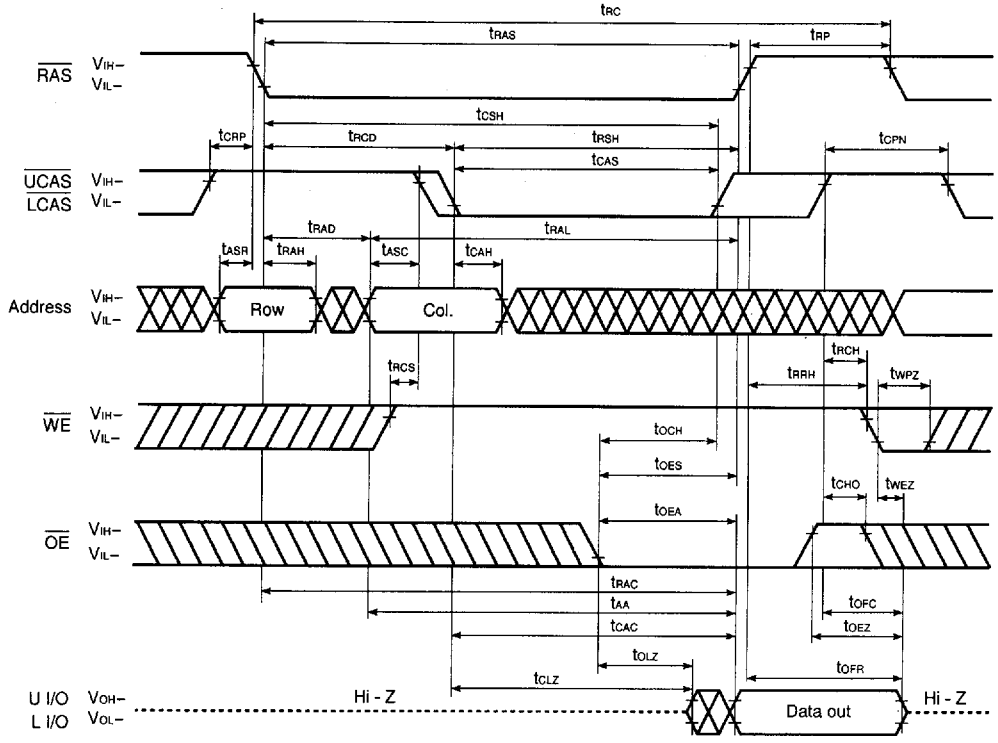
(3) Both $\overline{RAS}$ and $\overline{CAS}$ are inactive or $\overline{RAS}$ is active and $\overline{CAS}$ is inactive (at the end of read cycle)
$\overline{WE}$, $\overline{OE}$: active and either t_{RRH} or t_{RCH} must be met ····· t_{WEZ} and t_{WPZ} are effective.

(4) $\overline{WE}$: inactive (in read cycle)
$\overline{CAS}$: inactive, $\overline{OE}$: active ····· t_{CHO} is effective.
$\overline{CAS}$, $\overline{OE}$: active ····· t_{OCH} is effective.

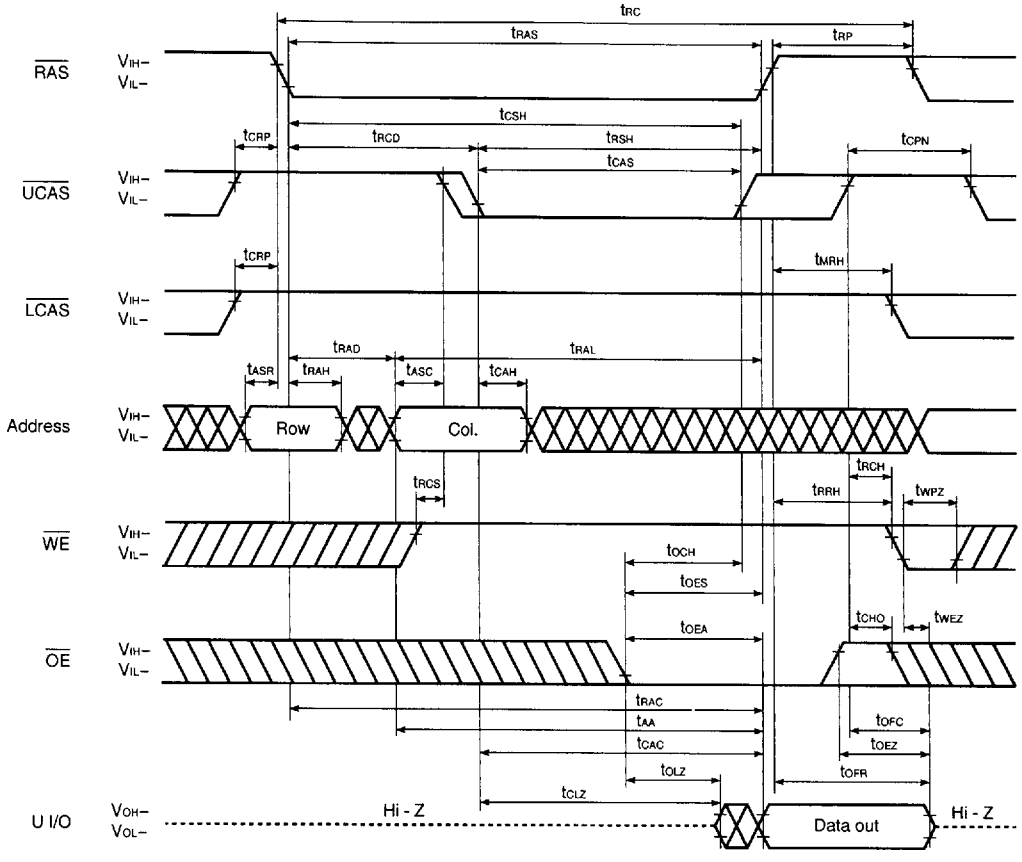
Refresh Cycle

Parameter	Symbol	t_{HPC} = 25 ns		t_{HPC} = 30 ns		t_{HPC} = 35 ns		Unit	Note
		MIN.	MAX.	MIN.	MAX.	MIN.	MAX.		
$\overline{CAS}$ setup time	t_{CSR}	5	–	5	–	5	–	ns	
$\overline{CAS}$ hold time ($\overline{CAS}$ before $\overline{RAS}$ refresh)	t_{CHR}	10	–	10	–	10	–	ns	
$\overline{RAS}$ precharge $\overline{CAS}$ hold time	t_{RPC}	5	–	5	–	5	–	ns	
$\overline{WE}$ hold time	t_{WHR}	15	–	15	–	15	–	ns	

Read Cycle

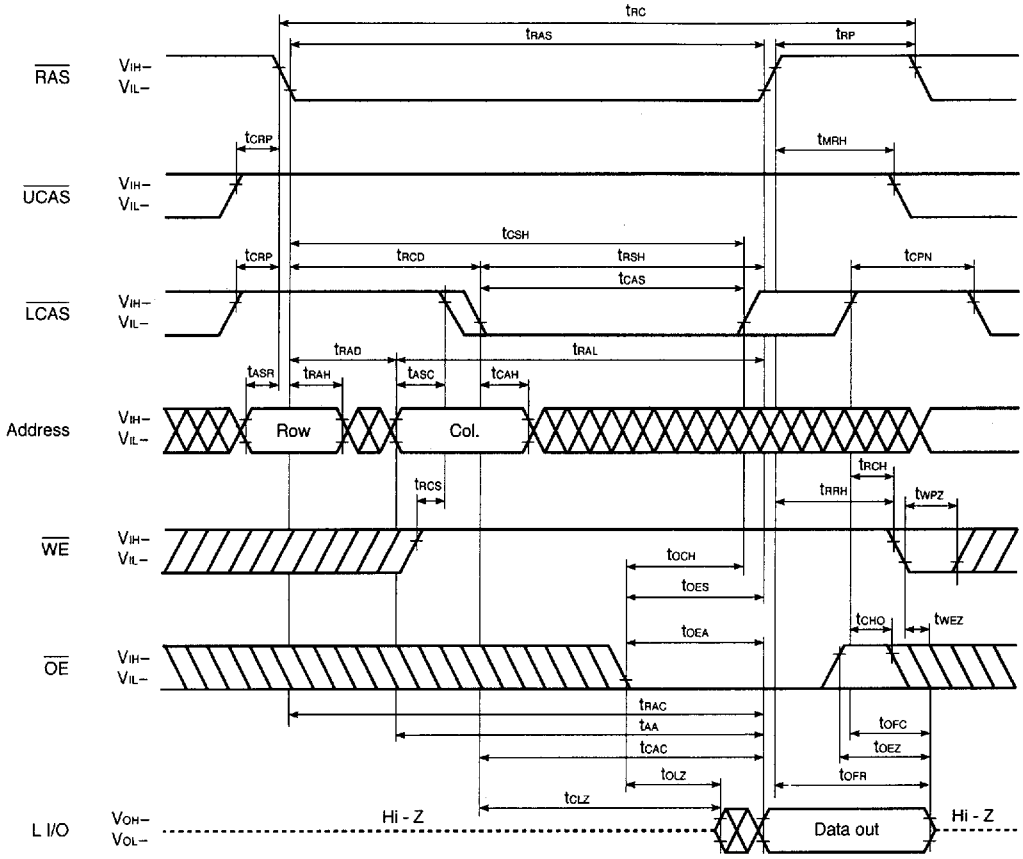


Upper Byte Read Cycle



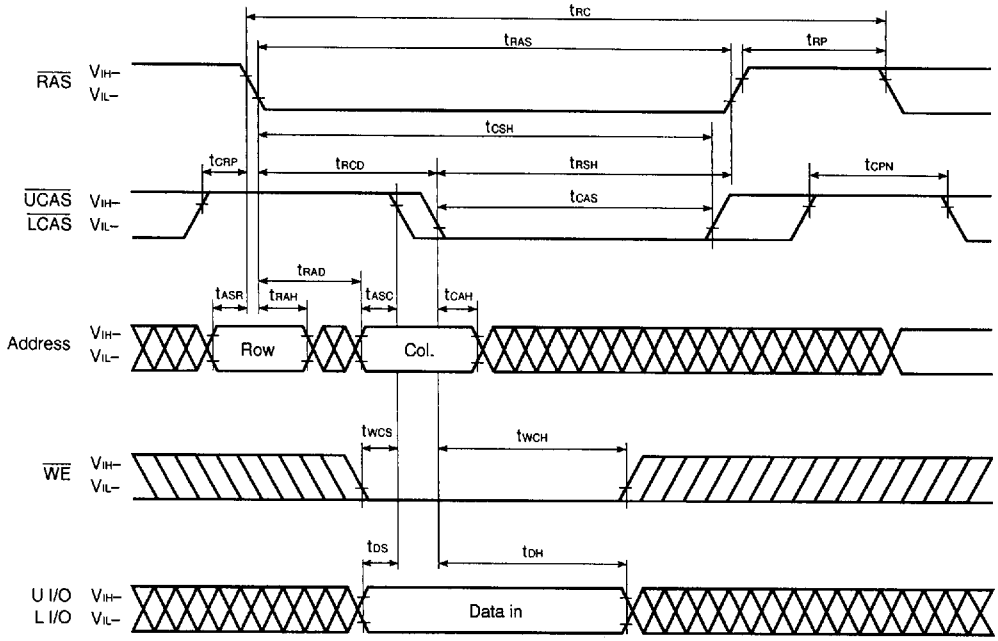
Remark L I/O: Hi-Z

Lower Byte Read Cycle



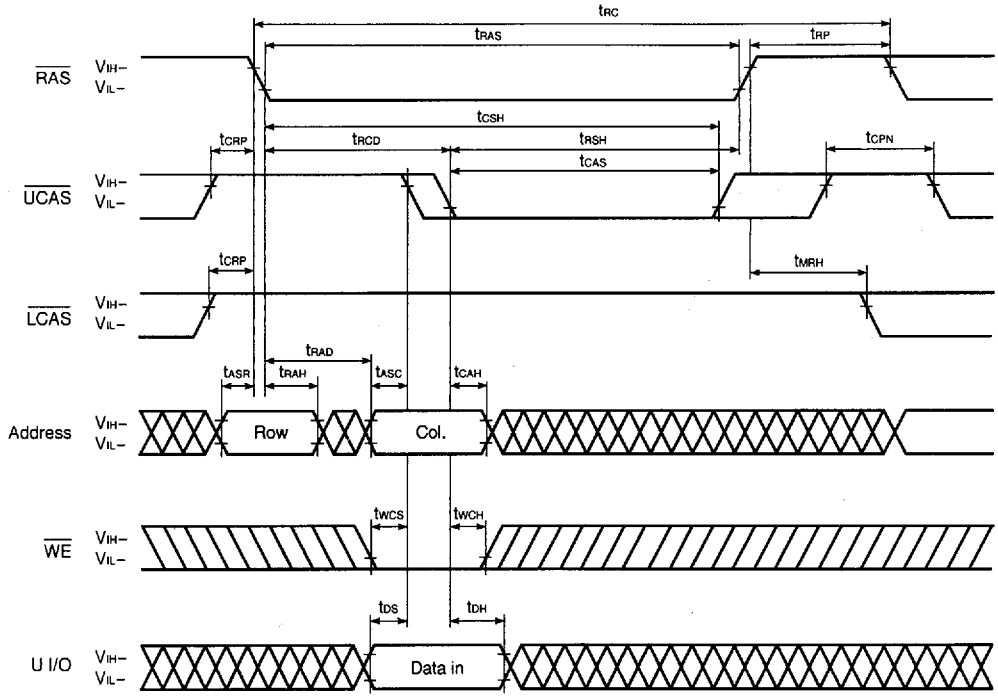
Remark U I/O: Hi-Z

Early Write Cycle



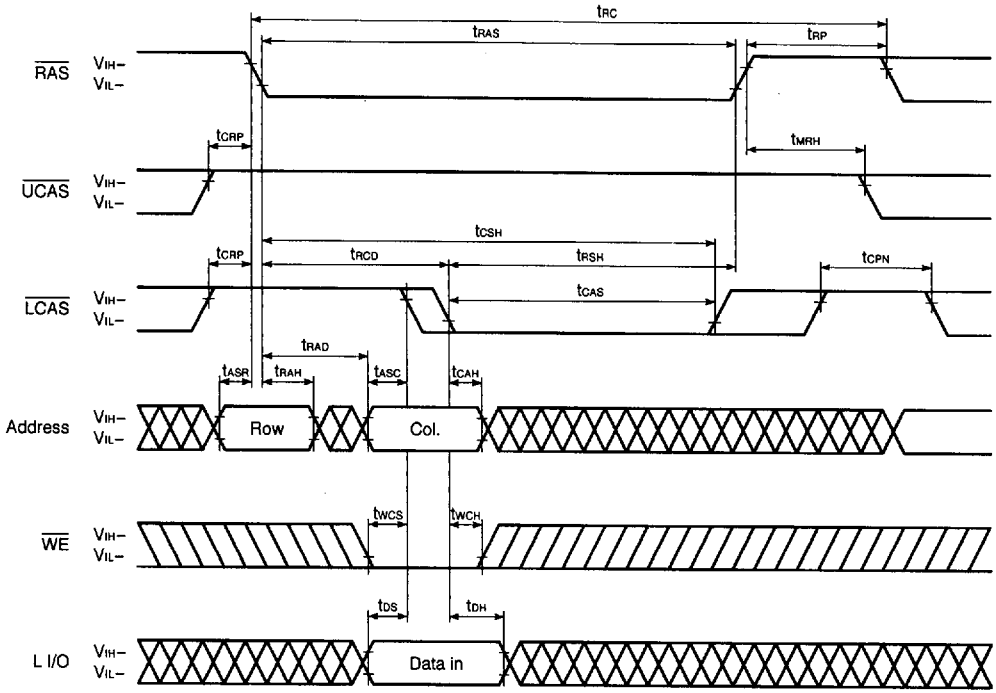
Remark $\overline{OE}$: Don't care

Upper Byte Early Write Cycle



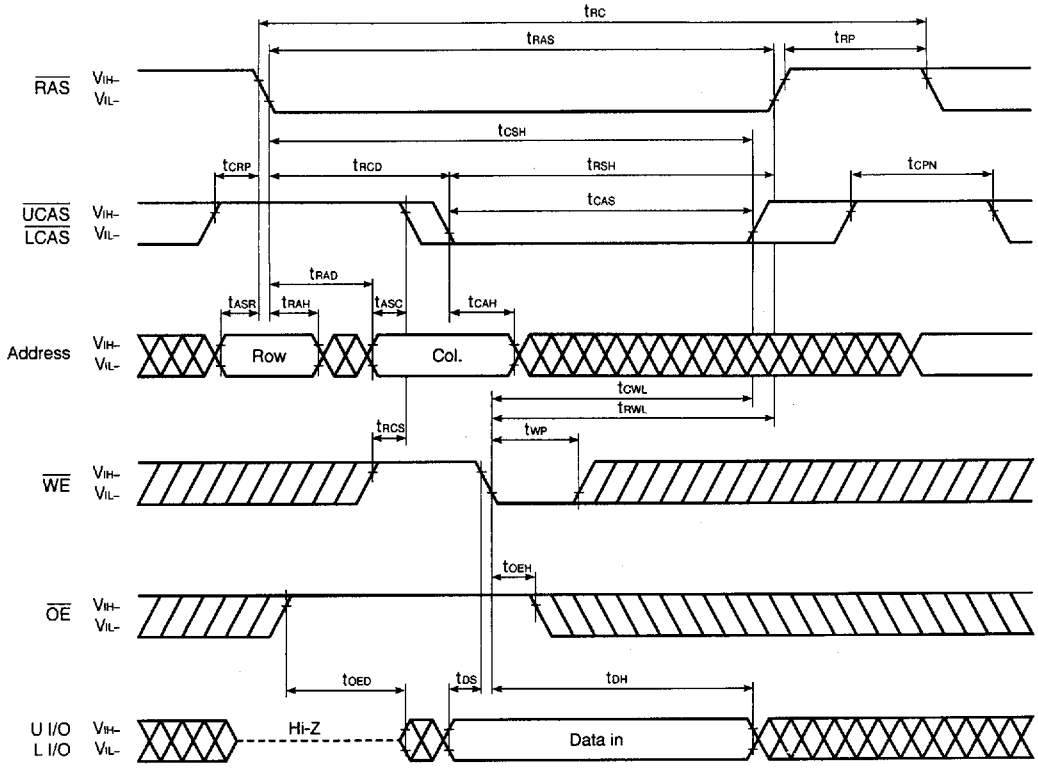
Remark $\overline{OE}$, L I/O: Don't care

Lower Byte Early Write Cycle

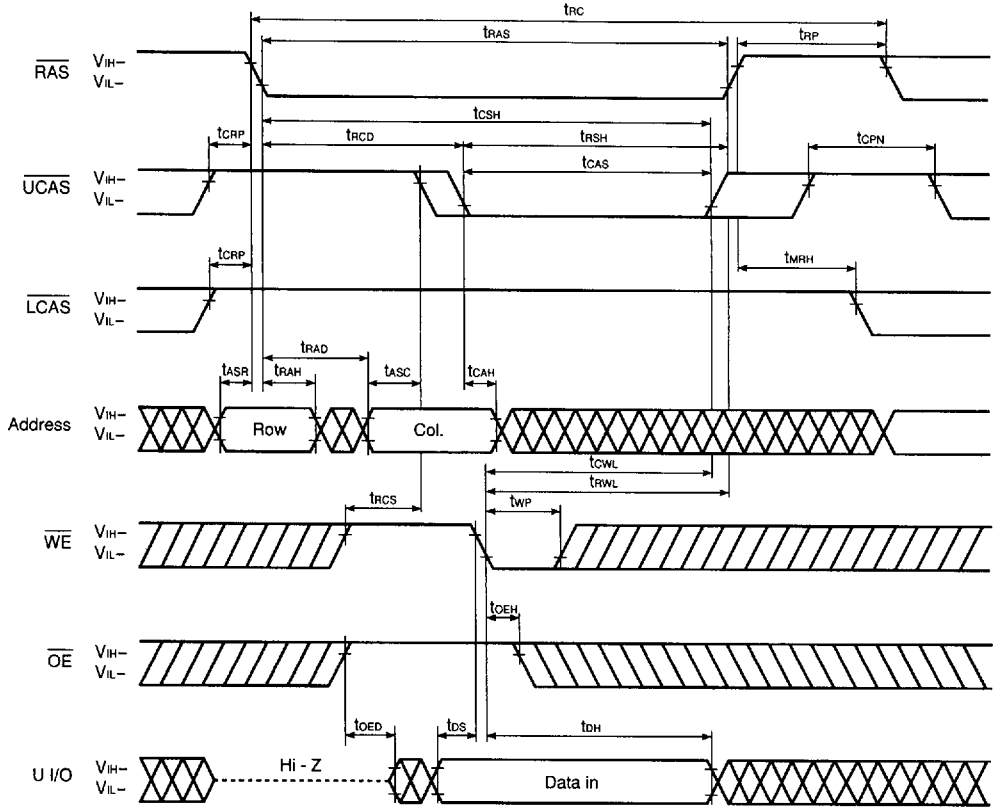


Remark $\overline{OE}$, U I/O: Don't care

Late Write Cycle

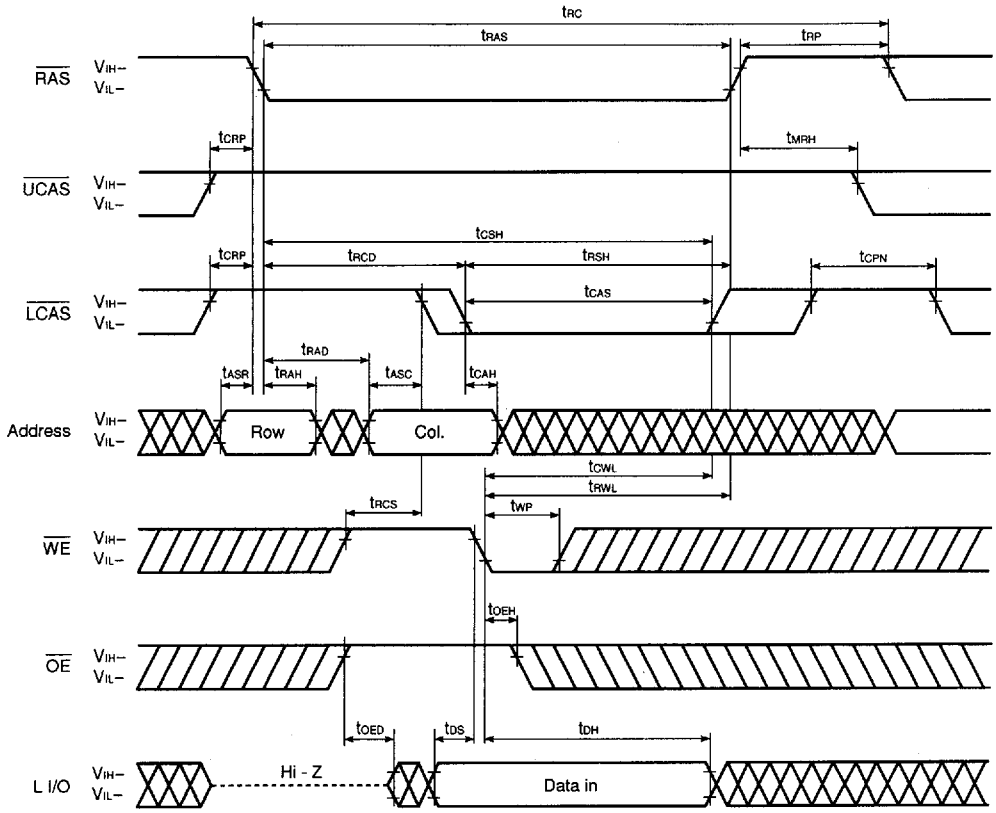


Upper Byte Late Write Cycle



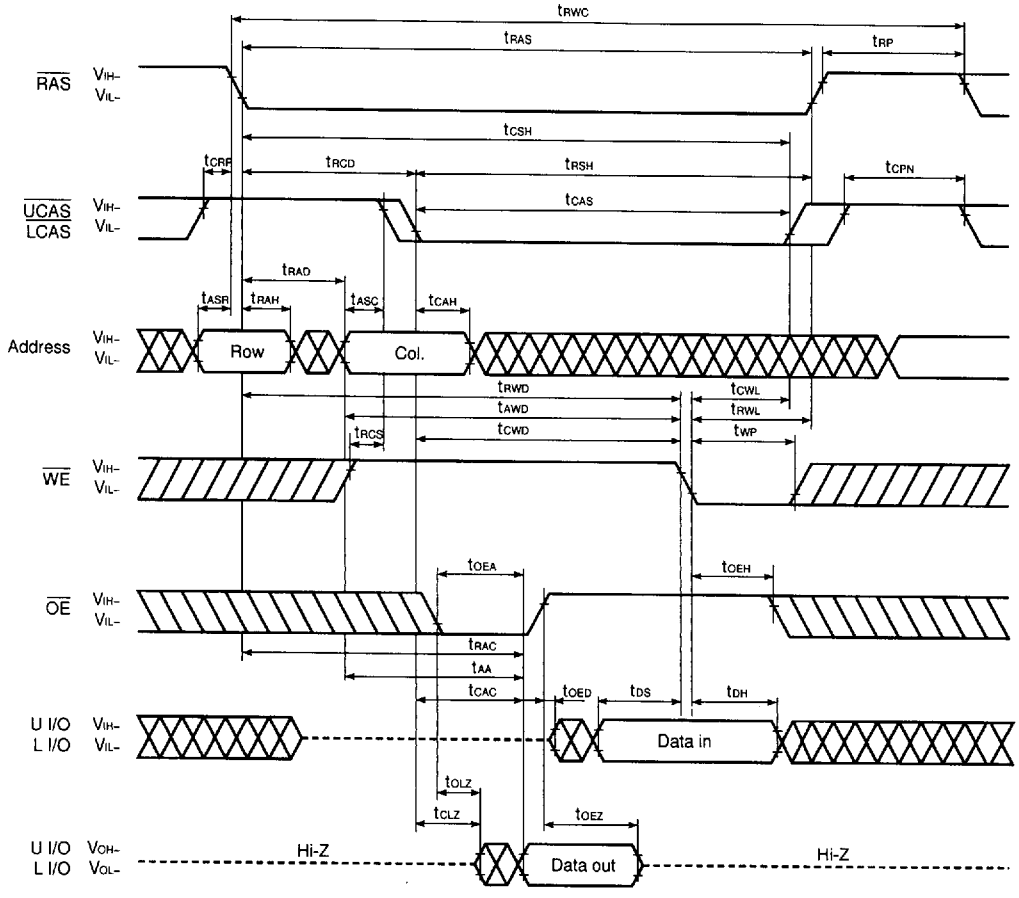
Remark L I/O: Don't care

Lower Byte Late Write Cycle

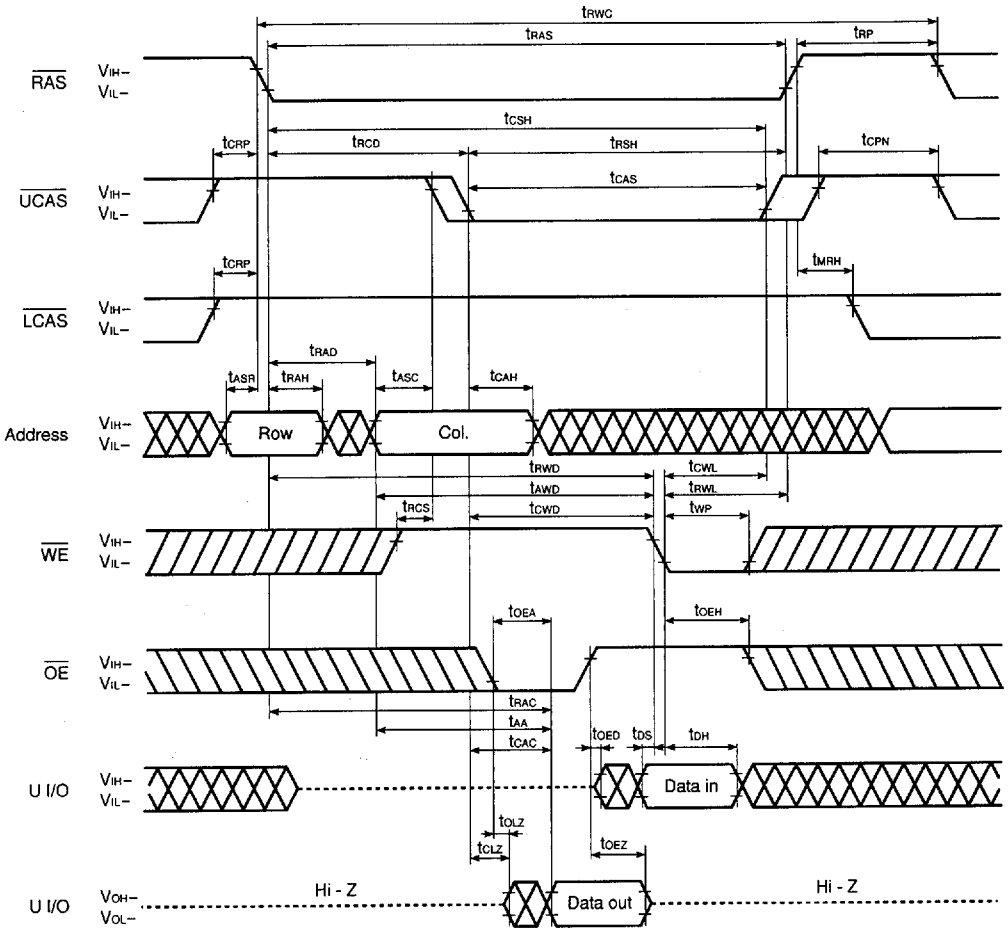


Remark U I/O: Don't care

Read Modify Write Cycle

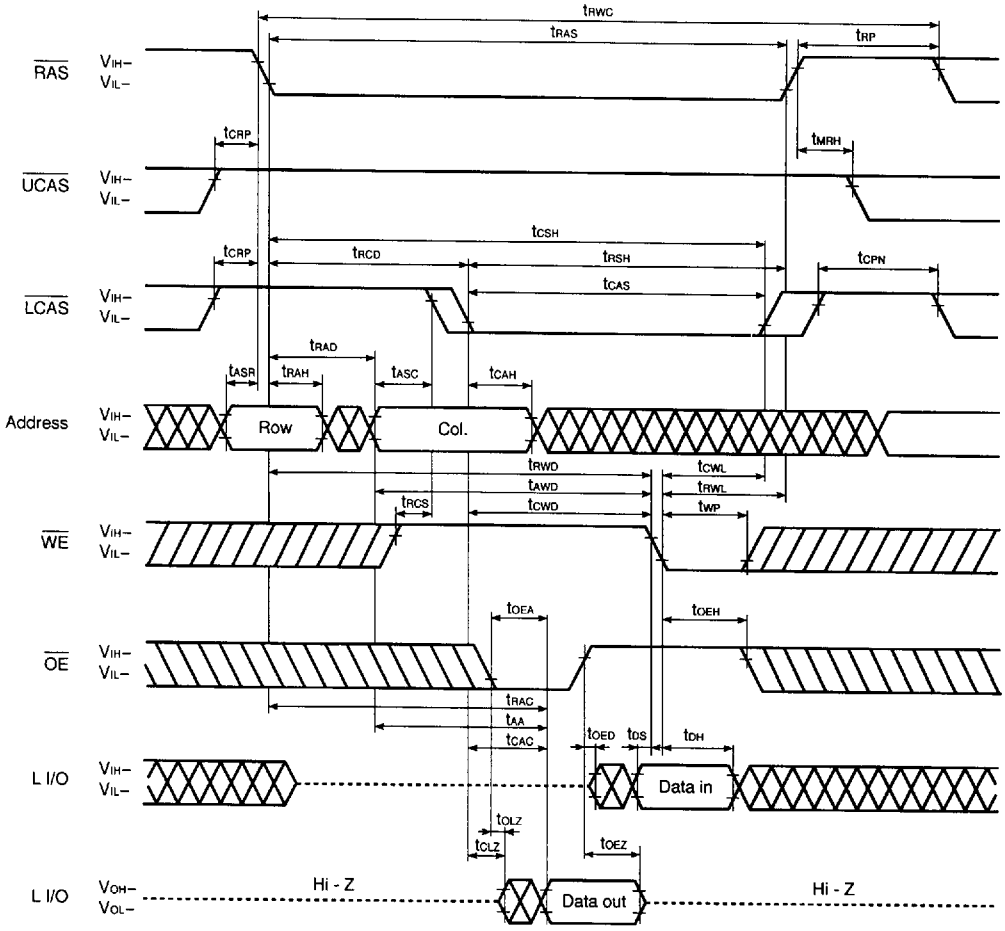


Upper Byte Read Modify Write Cycle



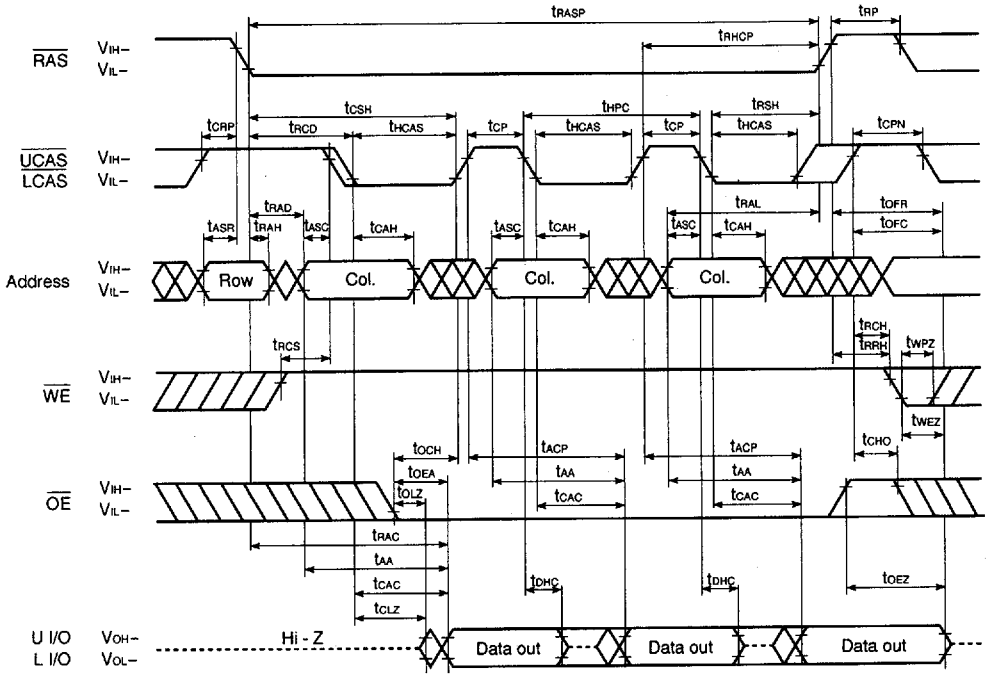
Remark In this cycle, the input data to Lower I/O is ineffective. The data out of that remains Hi-Z.

Lower Byte Read Modify Write Cycle



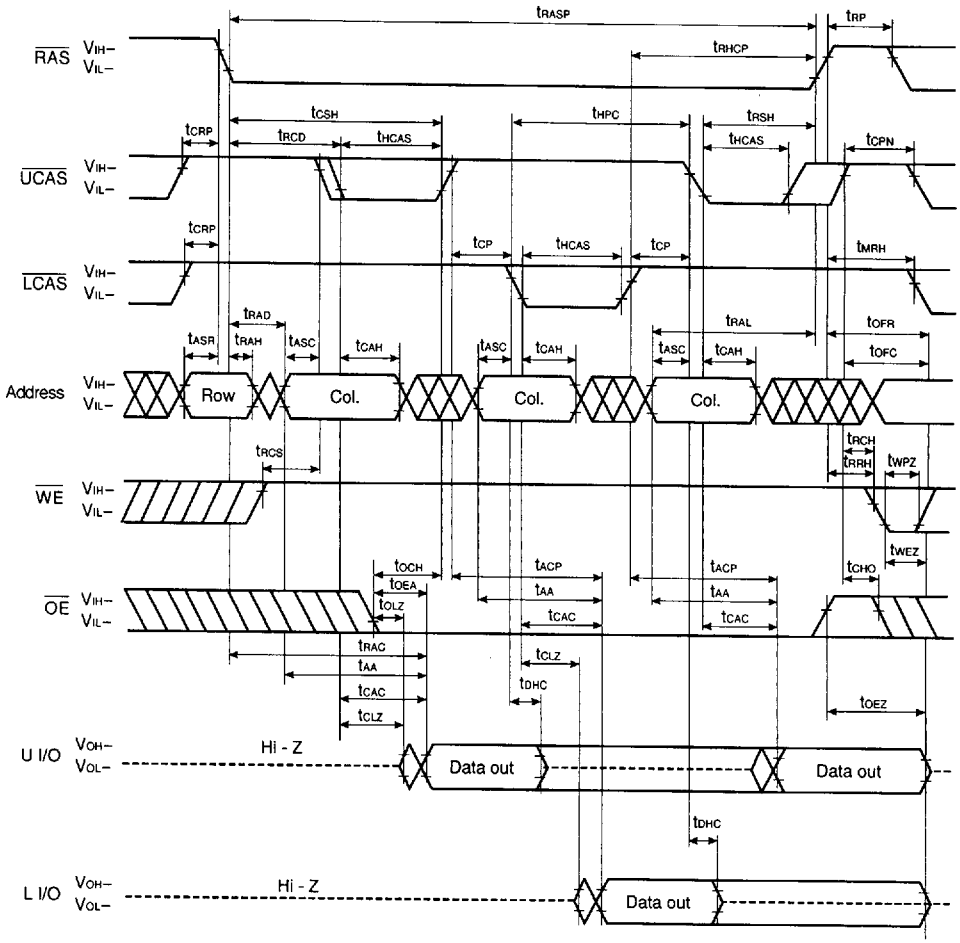
Remark In this cycle, the input data to Upper I/O is ineffective. The data out of that remains Hi-Z.

Hyper Page Mode (EDO) Read Cycle



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

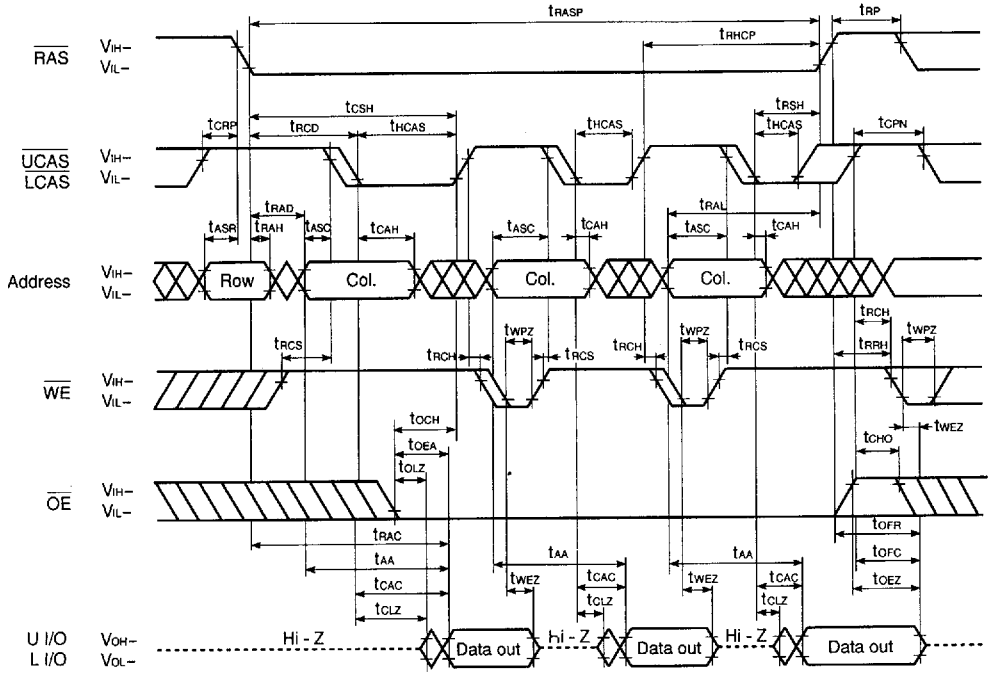
Hyper Page Mode (EDO) Byte Read Cycle



Remark 1. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

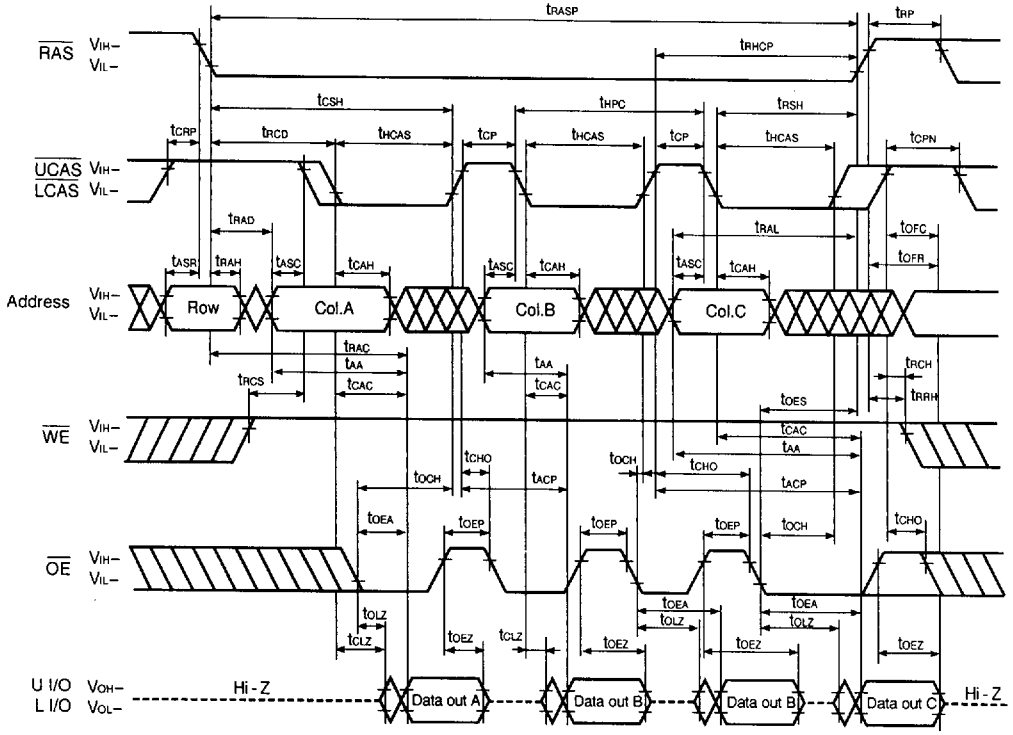
2. This cycle can be used to control either $\overline{UCAS}$ or $\overline{LCAS}$ only. Or, it can be used to control $\overline{UCAS}$ or $\overline{LCAS}$ simultaneously, or at random.

Hyper Page Mode (EDO) Read Cycle ($\overline{WE}$ Control)



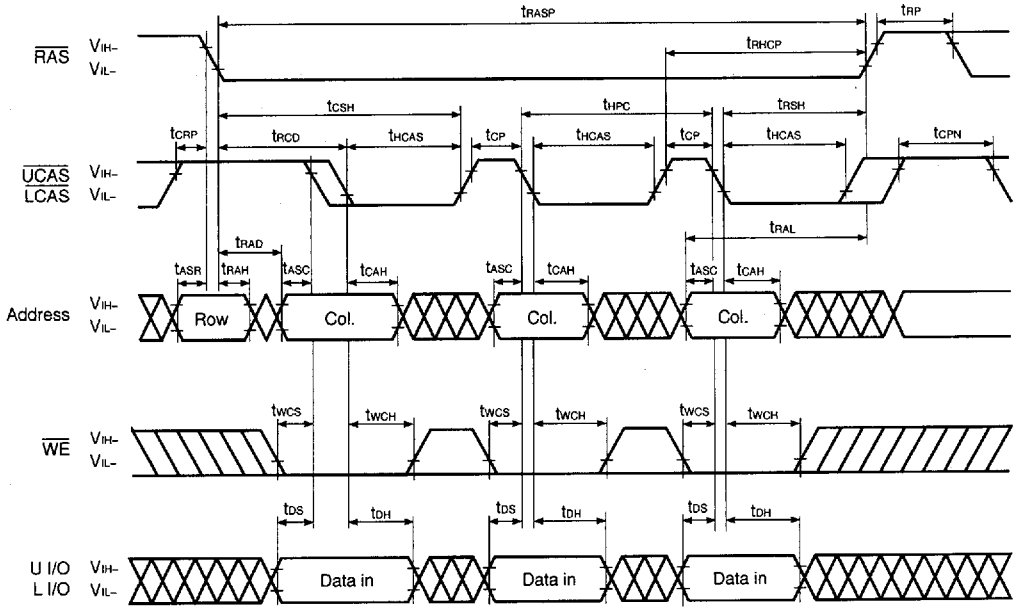
Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

Hyper Page Mode (EDO) Read Cycle ($\overline{OE}$ Control)



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

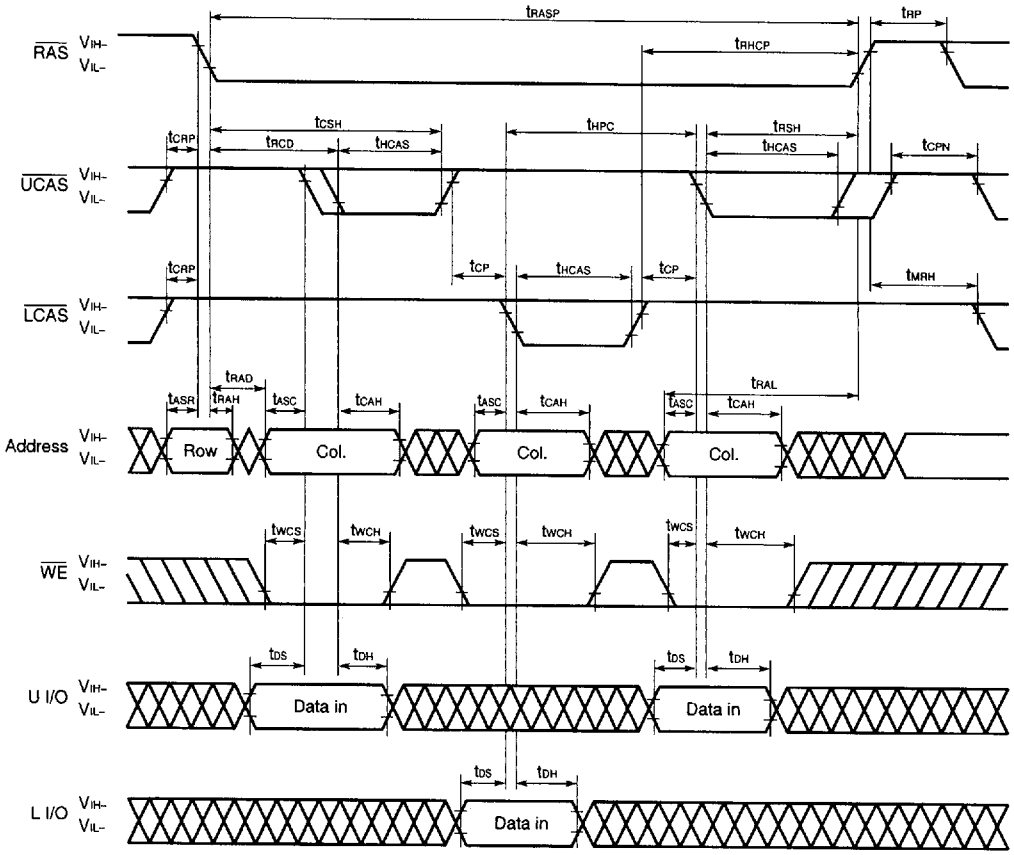
Hyper Page Mode (EDO) Early Write Cycle



Remarks 1. $\overline{OE}$: Don't care

2. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

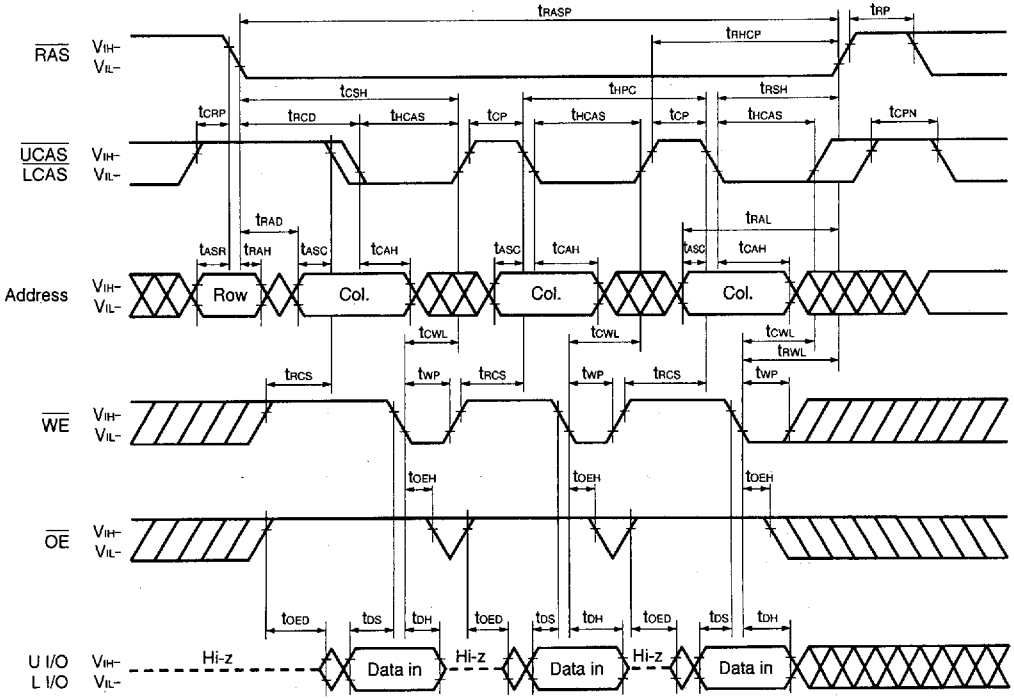
Hyper Page Mode (EDO) Byte Early Write Cycle



Remarks 1. $\overline{OE}$: Don't care

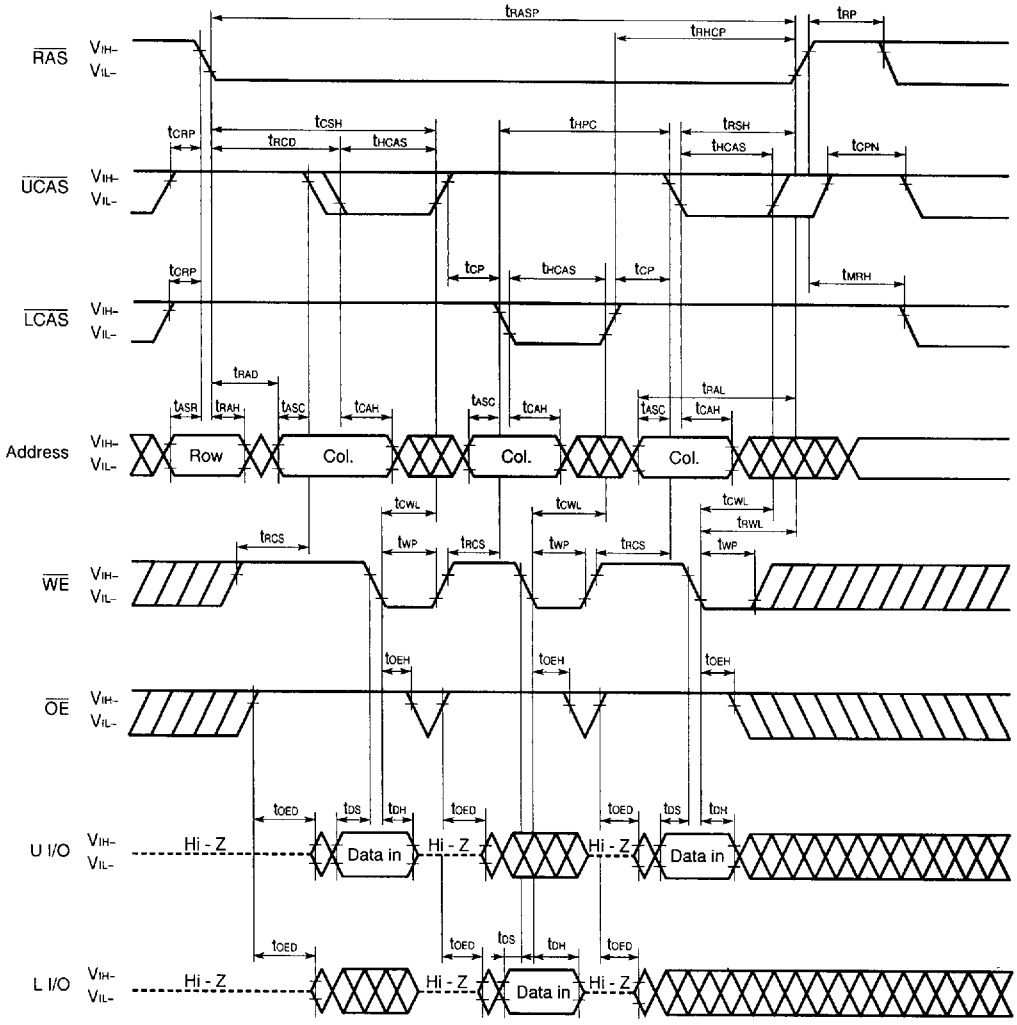
2. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.
3. This cycle can be used to control either $\overline{UCAS}$ or $\overline{LCAS}$ only. Or, it can be used to control $\overline{UCAS}$ or $\overline{LCAS}$ simultaneously, or at random.

Hyper Page Mode (EDO) Late Write Cycle



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

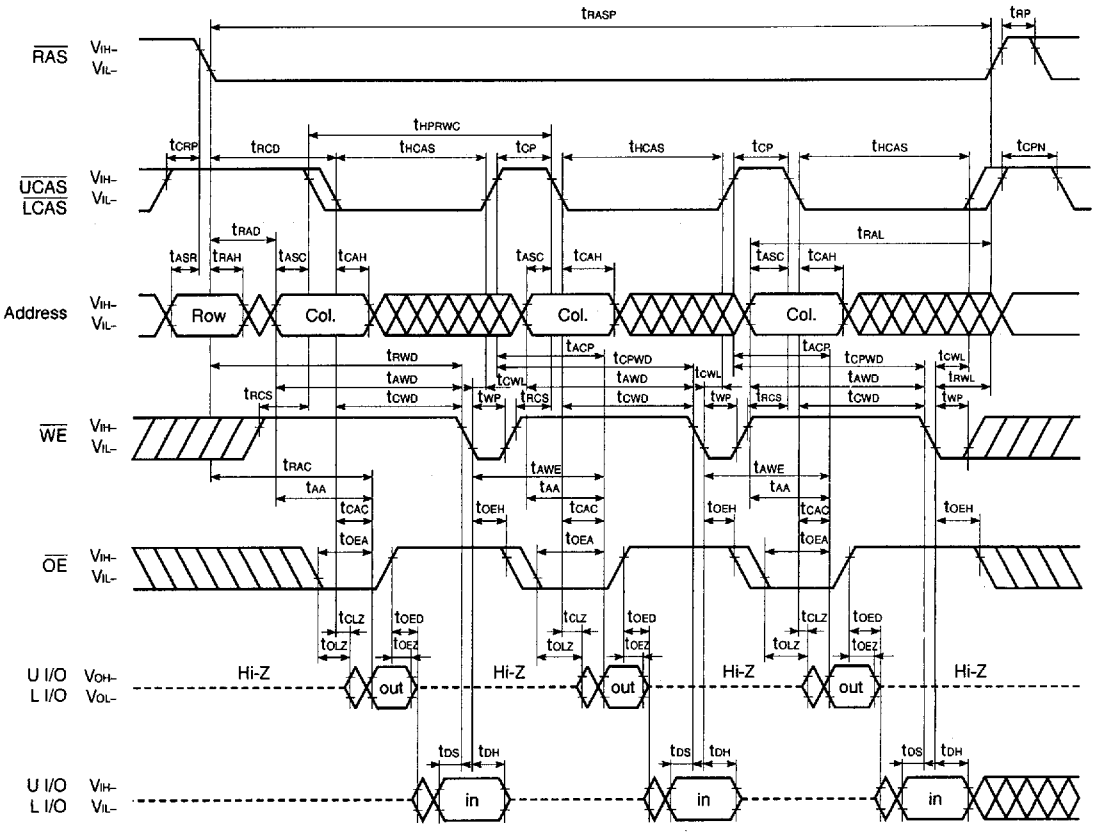
Hyper Page Mode (EDO) Byte Late Write Cycle



Remarks 1. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

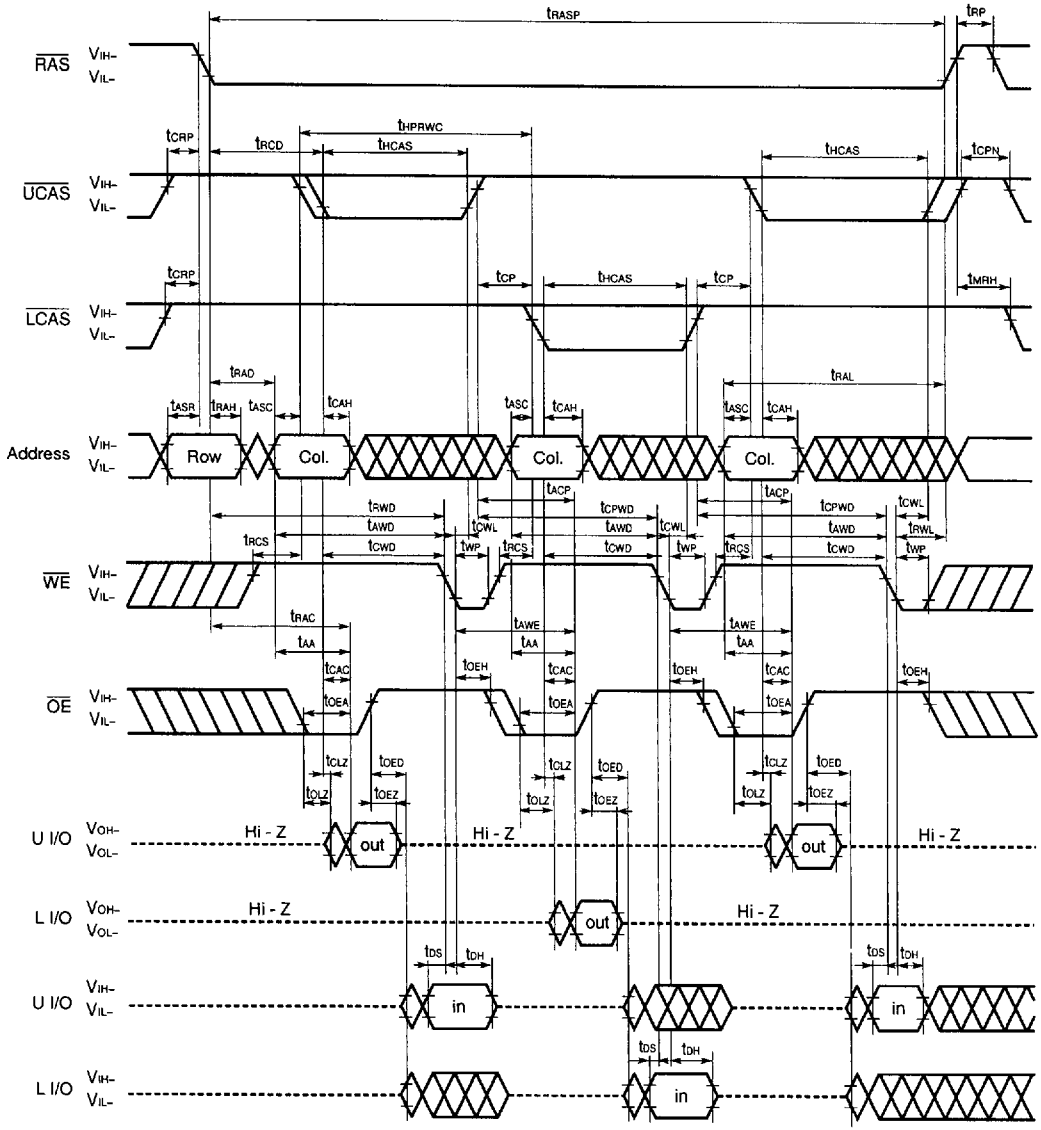
2. This cycle can be used to control either $\overline{UCAS}$ or $\overline{LCAS}$ only. Or, it can be used to control $\overline{UCAS}$ or $\overline{LCAS}$ simultaneously, or at random.

Hyper Page Mode (EDO) Read Modify Write Cycle



Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

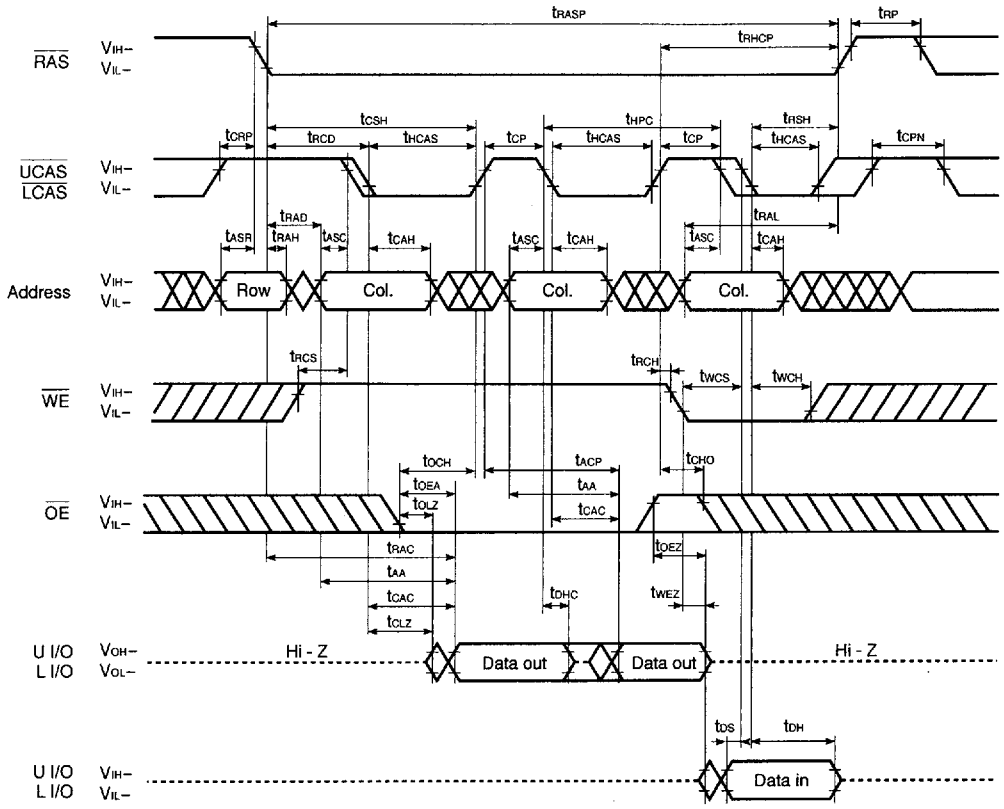
Hyper Page Mode (EDO) Byte Read Modify Write Cycle



Remarks 1. In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

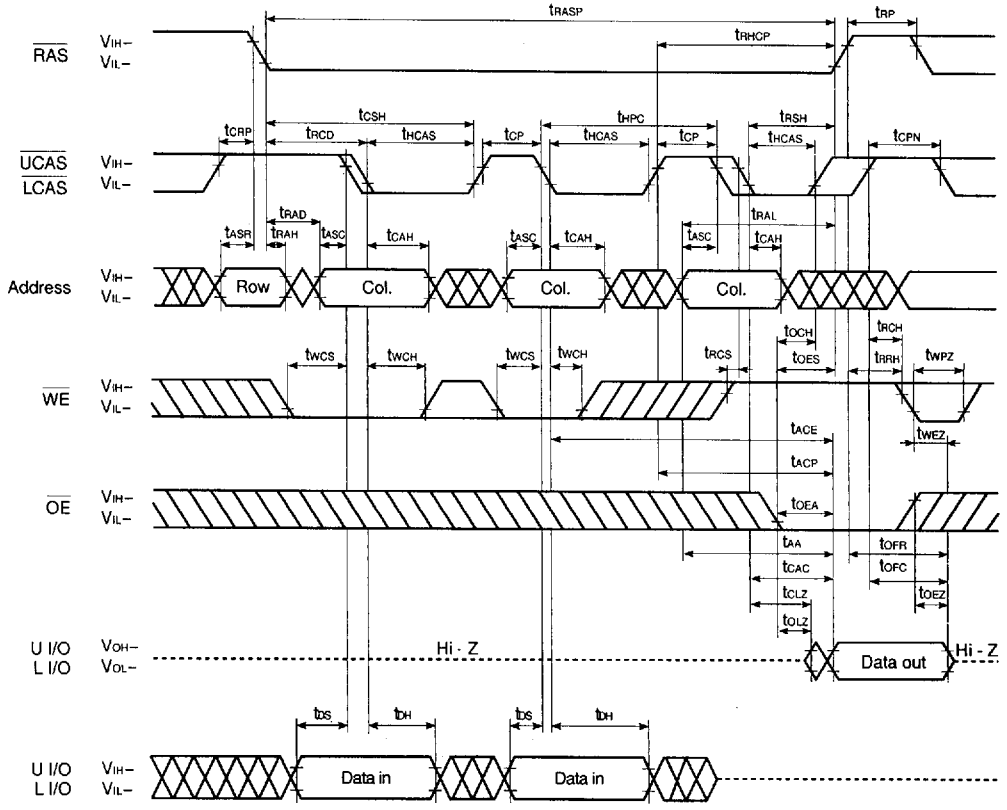
2. This cycle can be used to control either $\overline{UCAS}$ or $\overline{LCAS}$ only. Or, it can be used to control $\overline{UCAS}$ or $\overline{LCAS}$ simultaneously, or at random.

Hyper Page Mode (EDO) Read and Write Cycle



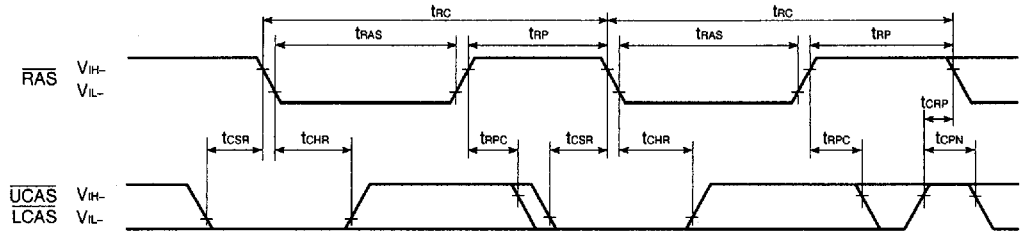
Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

Hyper Page Mode (EDO) Write and Read Cycle



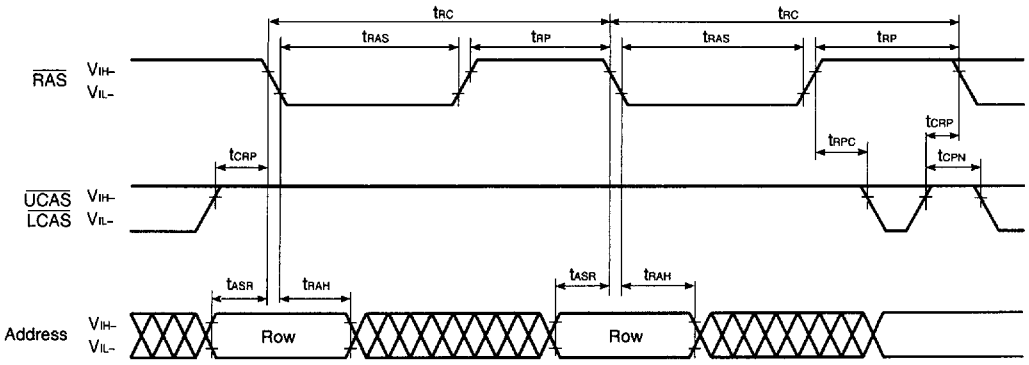
Remark In the hyper page mode (EDO), read, write and read modify write cycles are available for each of the consecutive $\overline{CAS}$ cycles within the same $\overline{RAS}$ cycle.

$\overline{CAS}$ Before $\overline{RAS}$ Refresh Cycle



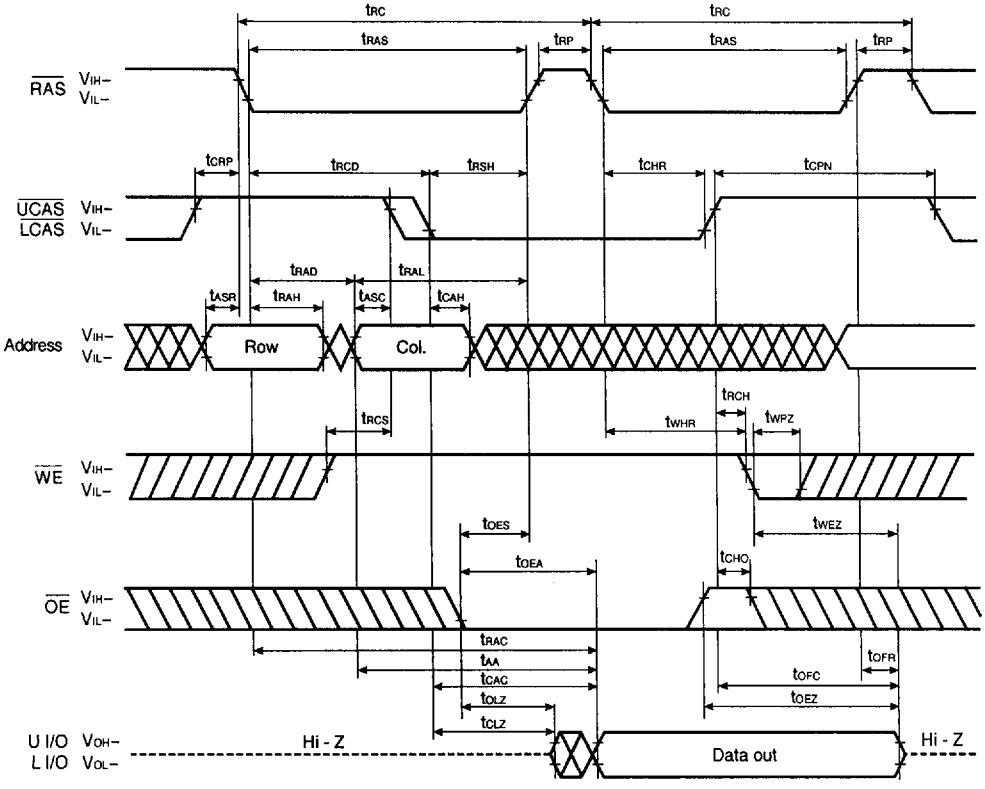
Remark Address, $\overline{WE}$, $\overline{OE}$: Don't care L I/O, U I/O: Hi-Z

$\overline{RAS}$ Only Refresh Cycle

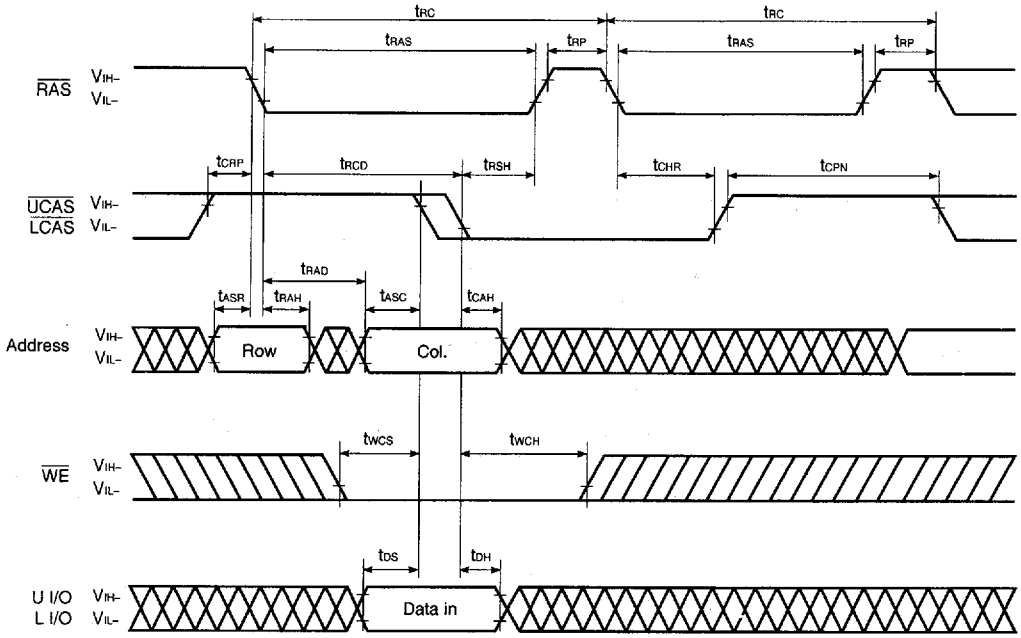


Remark $\overline{WE}$, $\overline{OE}$: Don't care L I/O, U I/O: Hi-Z

Hidden Refresh Cycle (Read)



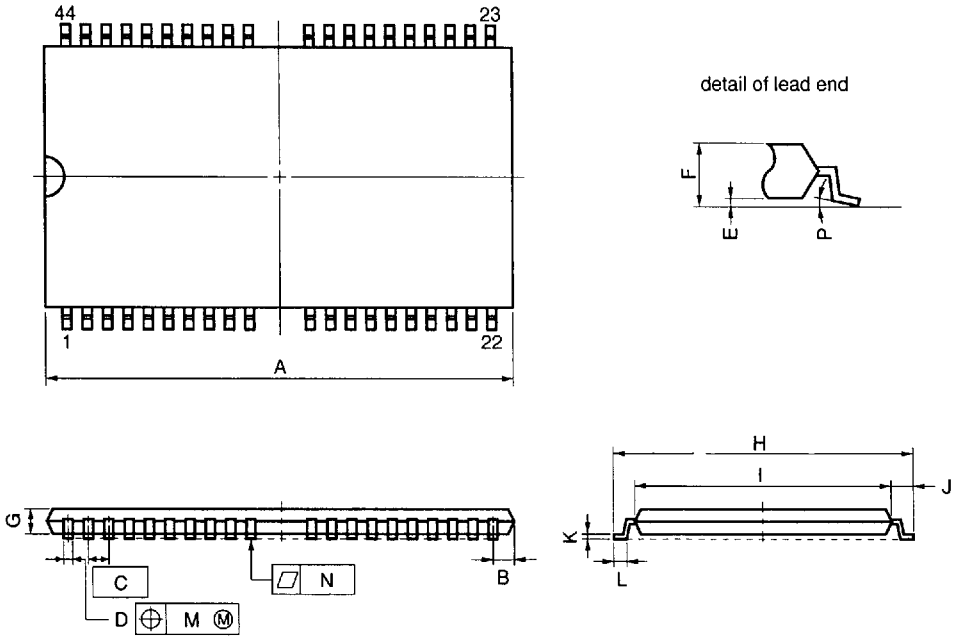
Hidden Refresh Cycle (Write)



Remark $\overline{OE}$: Don't care

Package Drawings

44 PIN PLASTIC TSOP(II) (400 mil)



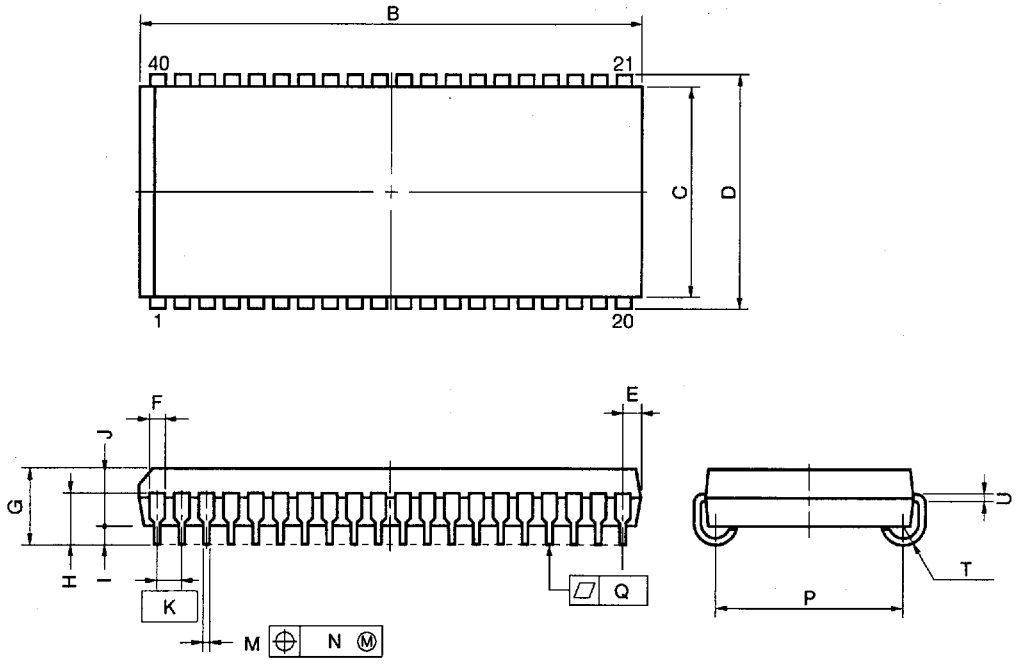
NOTE

Each lead centerline is located within 0.13 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
A	18.63 MAX.	0.734 MAX.
B	0.93 MAX.	0.037 MAX.
C	0.8 (T.P.)	0.031 (T.P.)
D	$0.32^{+0.08}_{-0.07}$	0.013±0.003
E	0.1±0.05	0.004±0.002
F	1.2 MAX.	0.048 MAX.
G	0.97	0.038
H	11.76±0.2	0.463±0.008
I	10.16±0.1	0.400±0.004
J	0.8±0.2	$0.031^{+0.009}_{-0.008}$
K	$0.145^{+0.025}_{-0.015}$	0.006±0.001
L	0.5±0.1	$0.020^{+0.004}_{-0.005}$
M	0.13	0.005
N	0.10	0.004
P	$3^{\circ}{}^{+7^{\circ}}_{-3^{\circ}}$	$3^{\circ}{}^{+7^{\circ}}_{-3^{\circ}}$

S44G5-80-7JF4

40 PIN PLASTIC SOJ (400 mil)



NOTE
Each lead centerline is located within 0.12 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
B	$26.29^{+0.2}_{-0.35}$	$1.035^{+0.008}_{-0.014}$
C	10.16	0.400
D	11.18±0.2	0.440±0.008
E	1.08±0.15	$0.043^{+0.006}_{-0.007}$
F	0.7	0.028
G	3.5±0.2	0.138±0.008
H	2.4±0.2	$0.094^{+0.009}_{-0.008}$
I	0.8 MIN.	0.031 MIN.
J	2.6	0.102
K	1.27(T.P.)	0.050(T.P.)
M	0.40±0.10	$0.016^{+0.004}_{-0.005}$
N	0.12	0.005
P	9.40±0.20	0.370±0.008
Q	0.15	0.006
T	R0.85	R0.033
U	$0.20^{+0.10}_{-0.05}$	$0.008^{+0.004}_{-0.002}$

P40LE-400A-2

Recommended Soldering Conditions

Please consult with our sales offices for soldering conditions of the μPD421165.

Types of Surface Mount Device

μPD421165G5: 44-pin plastic TSOP (II) (400 mil)
μPD421165LE: 40-pin plastic SOJ (400 mil)